

## Master Logic 50

## Programmable Logic

## Controller

## Specification

### Overview

Honeywell's new ML50 compact PLC, with its innovative architecture combines power and versatility to help provide performance in a slim, compact and affordable solution. With its high performance and functionality, the new ML50 PLC offer economical automation platform for many industrial control applications. The ML50 family can be used just as I/O, as a standalone PLC or as a distributed control. It offers broad selection of Base modules, Expansion I/O modules, various network interface options and some special modules to enhance control capabilities.

### Features

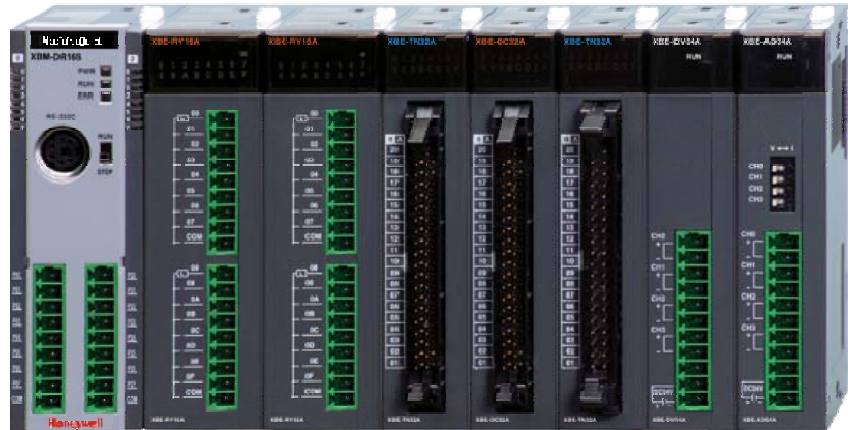
#### • Easiness and Convenience

ML50 series offers convenient user interface with various network diagnosis & monitoring functions and back-up functions.

- Enhanced user interface
- Various monitoring functions
- Network diagnosis & monitoring Battery less back-up

#### • Compactness

ML50 series is very compact but provides powerful functions and performance. Compact & Powerful performance is ML50's steadfast competitiveness.



#### • Functionality

With its powerful and various built-in functions, ML series can provide optimum solution for your automation task.

- Communication: RS232, RS485
- 2-axis positioning functions
- High speed counter
- PID Control
- Various input processing like pulse catch, input filter

#### • High performance

With its high-speed processing and system capability, ML50 series offers utmost efficiency for your applications.

- 160ns/step processing speed and floating-point arithmetic with on-board CPU
- Up to 7 expansion modules, 480 I/O point control – PLC system for low-to-mid level applications
- Up to 5 communication ports with built-in-functions and expansion modules

#### • Integrated programming & debug environment

ML50 series offers enhanced programming convenience and various monitoring / diagnosis functions.

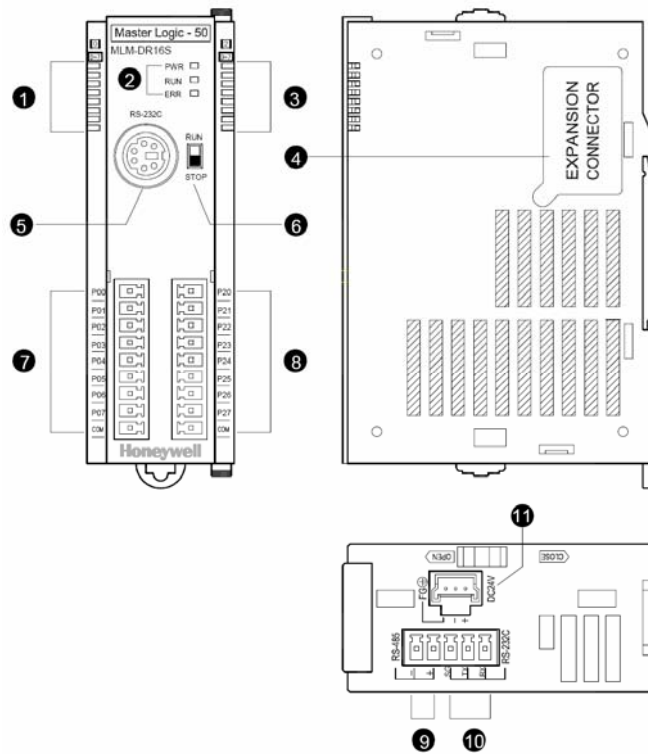
- Programming flexibility with 720 instructions (42 basic instructions, 678 application instructions)
- Multi-PLC, Multi-program management integrated network setting monitoring & diagnosis
- Convenient variable editing
- Compatibility with Microsoft Excel
- Address, Special module & Custom vent monitoring Trend monitor

#### • Easy Expansion

With its detachable terminal block and MIL connector, ML50 provides easy and convenient way for wiring and module change. For expansion of PLC system, each expansion module can be easily connected and separated by its direct-insert method.



## Indicators and Connectors



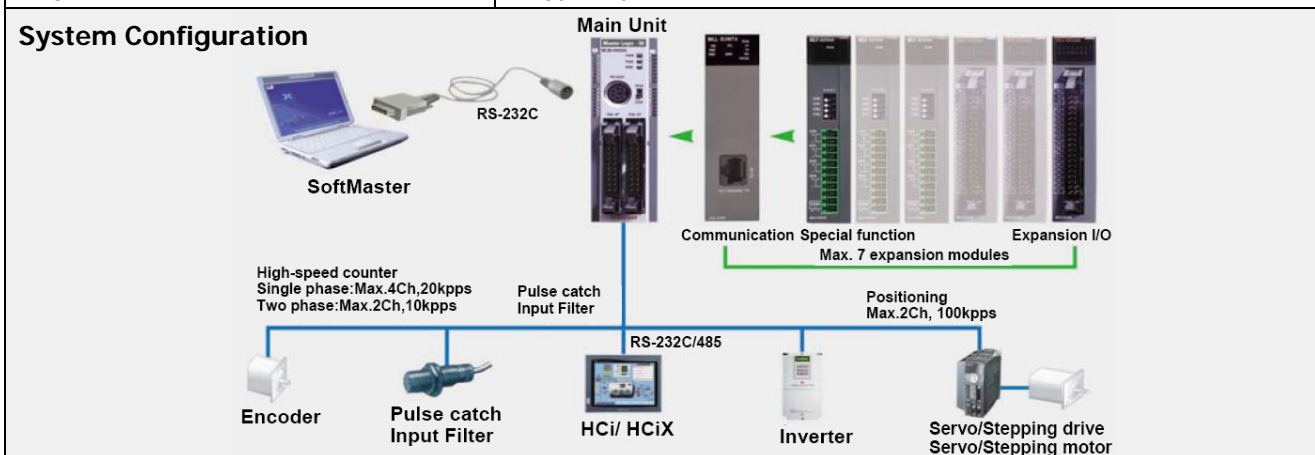
Name		Description	
1	Input LED	Input Indication	Red on/off. Input signal on/off
2	Condition LED	PWR: Power indication	Red on/off. Power on/off
		RUN : RUN indication	Green on/off. PLC RUN/STOP
		ERR : Error indication	Red on/off. PLC error. Red off. PLC normal condition
3	Output LED	Output LED	On/off. Output signal on/off.
4	Expansion Module Connector	Connection of expansion module (I/O, Special function, Communication)	
5	PADT connector	PADT connection	Connector for SoftMaster / SoftMaster-NM connection
6	Model Switch *1	Model setting	Setting RUN/STOP model of PLC
7	Input Connector / Terminal Block	Input wiring connection	
8	Output Connector / Terminal Block	Output wiring connection	
9	RS 485 Connector	Built-in RS-485 terminal connection	
10	RS-232C Connector *2	Built-in RS232C TxD, RxD, GND terminal connection	
11	Power Connector*3	Power supply connection	DC24V Power Supply

\*1) In the remote mode, set the mode switch STOP.

\*2) GND terminal of RS-232C can be used as GND terminal of RS-485.

\*3) Select DC power supply considering current consumption of PLC system.

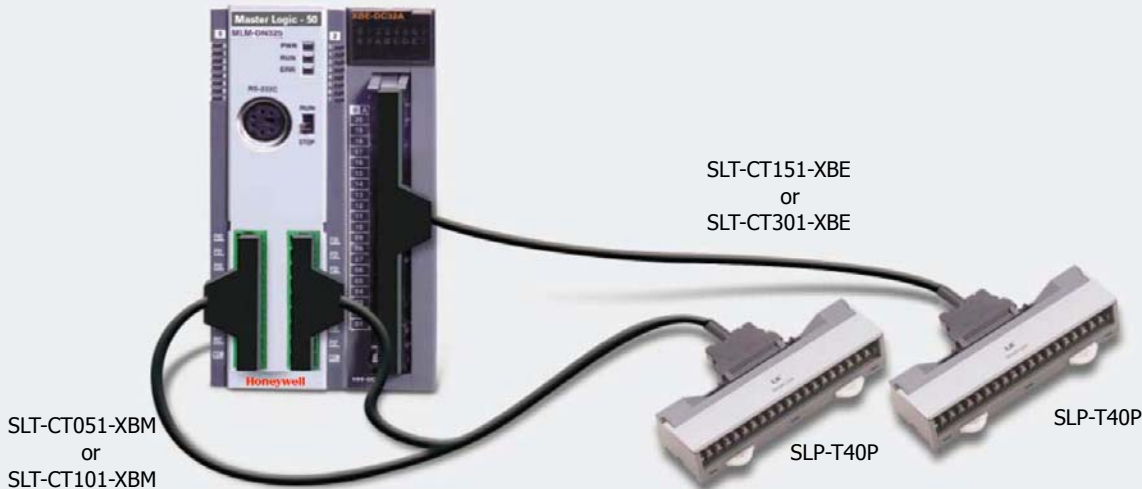
Specifications			
Model	MLM-DR16S	MLM-DN16S	MLM-DN32S
Performance			
Internal Current Consumption	400mA	280mA	300mA
Control Method	Repetitive, cyclic, interrupt, constant scan		
I/O Control Mode	Refresh mode (Batch processing by scan synchronization) Direct mode by instructions		
Programming Language	Ladder diagram, Instruction List		
Number of Instructions	Basic : 42, Applied : 678		
Processing Speed	0.16 $\mu$ s/Step (for basic instruction)		
Program Capacity	10 kilo-steps		
Max. I/O Points	480 points (Main + 7 expansions)		
Data Memory	P	P0000 – P127F (2,048 points)	
	M	M0000 – M255F (4,096 points)	
	K	K00000 – K2559F (Special area: K2600 – 2559F) (40,960 points)	
	L	L00000 – L1279F (20,480 points)	
	F	F000 – F255F (4,096 points)	
	T	100msec, 10msec, 1msec: T000 – T255 (Changeable by parameter setting)	
	C	C000 – C255	
	S	S00.00 – S127.99	
	D	D0000 – D5119 (5,120 word)	
	U	U00.00 – U07.31 (Analog data refresh area: 256 word)	
	Z	Z000 – Z127 (128 word)	
	N	N0000 – N3935 (3,936 word)	
No. of Program	128		
Operation Mode	RUN, STOP, DEBUG		
Self Diagnostic	Operation delay monitoring, Memory error, I/O error, Power supply failure, etc.		
Program Port	RS-232C (Loader) Remote connection using RS-232C, RS-485		
Data Retention at Power Failure	Latch range setting at Basic parameter		
Built-in Functions	RS-232C/485, High-speed counter, PID control, Pulse catch, Input Filter		
	-	External interrupt, Positioning	
Weight	100g(0.22lb)		



Specifications						
DC INPUT						
Model	Main Unit			Expansion		
	MLM-DR16S	MLM-DN16S	MLM-DN32S	MLE-DC08A MLE-DR16A	MLE-DC16A	MLE-DC32A
Input Points	8	8	16	8	16	32
Insulation Method	Photo-coupler insulation					
Rated Input Voltage / Current	DC24V / 4mA (Contact 00 ~ 03 : 7mA)			DC24V / 4mA		
Operation Voltage Range	DC 20.4 to 28.8 V (Ripple rate < 5%)					
ON Voltage / Current	DC19V or more / 3mA or more					
OFF Voltage / Current	DC6V or less / 1mA or less					
Input Resistance	5.6 K $\Omega$ (Contact 00~03: 3.3 K $\Omega$ )			5.6 K $\Omega$		
Response Time	OFF→ON	1 / 3 / 5 / 10 / 20 / 70 / 100 msec (setting by CPU parameter). Initial value: 3msec				
	ON→OFF					
Insulation Pressure	AC 560Vrms / 3 Cycle (altitude 2000m(6,561.68 fts))					
Insulation Resistance	10 M $\Omega$ or more by megger					
COMMON Method	8 points / COM		16 points/COM	8 points/COM	16 points/COM	32 points/COM
Proper Cable Size	Twisted wire 0.3 – 0.75 mm <sup>2</sup> (external diameter $\leq$ 2.8mm, 0.11inch)					
Operation Indication	Input On, LED On					
Internal Current Consumption	400 mA	240 mA	300 mA	30 mA	40 mA	50 mA
External Connection Method	9-Pin Terminal block	20-pin Connector	20-pin Connector	10-pin Terminal block	8-pin + 10-pin Terminal block	40-pin connector
Open collector OUTPUT						
Model	Main Unit			Expansion		
	MLM-DN16S	MLM-DN32S		MLE-TN08A	MLE-TN16A	MLE-TN32A
Output Points	8	16		8	16	32
Insulation Method	Photo-coupler insulation					
Rated Load Voltage	DC 12 / 24V					
Load Voltage Range	DC10.2 to 26.4V					
Max. Load Current	0.2A / Point	0.2A/Point,2A/COM		0.5A / Point	0.2A/Point, 2A/COM	
OFF Leakage Current	0.1mA or less					
Max. Voltage Drop(ON)	DC 0.4V					
Surge Absorber	Zener Diode					
Response Time	OFF→ON	1msec or less				
	ON→OFF					
Common Method	8 Points / COM	16 Points / COM		8 Points / COM	16 Points / COM	32 Points / COM
Internal Current Consumption	180mA	200mA		40mA	60mA	120mA
External Power Supply	Voltage	DC12/24V $\pm$ 10% (Ripple Voltage $\leq$ 4 Vp-p)				
	Current	24mA or less (at DC24V)		10mA or less (at DC24V)		20mA or less (at DC24V)
Operation Indicator	Output ON, LED ON					
External Connection Method	20-pin connector			10-pin terminal block	8-pin + 10-pin terminal block	40-pin connector

Specifications				
Relay OUTPUT				
Model	Main Unit		Expansion	
	MLM-DR16S		MLE-RY08A, MLE-DR16A	MLE-RY16A
Output Points	8 points		8 points	16 points
Insulation Method	Relay insulation			
Rated Load Voltage/Current	DC 24V, 2A (Resistive load) / AC220V, 2A (COS $\psi$ = 1), 5A/COM			
Minimum Load Voltage/Current	DC 5V / 1mA			
Maximum Load Voltage/Current	AC250V / DC125V			
OFF Leakage Current	0.1mA (AC250V, 60Hz)			
Max. ON/OFF Frequency	3,600 times / Hour			
Surge Absorber	None			
Service Life	Mechanical	20 million times or more		
	Electrical	Rated load voltage/current 100,000 times or more		
		AC200V/1.5A, AC240V/1A ( COS $\psi$ = 0.7) 100,000 times or more		
		AC200V/1A, AC240V/0.5A ( COS $\psi$ = 0.35) 100,000 times or more		
		DC24V/1A, DC100V/0.1A ( L / R = 7ms) 100,000 times or more		
Response Time	OFF→ON	10msec or less		
	ON→OFF	12msec or less		
Common Method	8 points / 1 COM			
Internal Current Consumption	360 mA	230 mA	420 mA	
Operation Indicator	Output ON, LED ON			
External Connection	9-pin terminal block		9-pin terminal block X 2	
Input & Output wiring				
8-point DC Input	8-point NPN Output	8-point Relay Output	16-point Relay Output	
MLM-DR16S	MLE-TN08A	MLM-DR16S, MLE-RY08A	MLE-RY16A	
<p>Contact number</p>	<p>Contact number</p>	<p>Contact number</p>	<p>Contact number</p>	

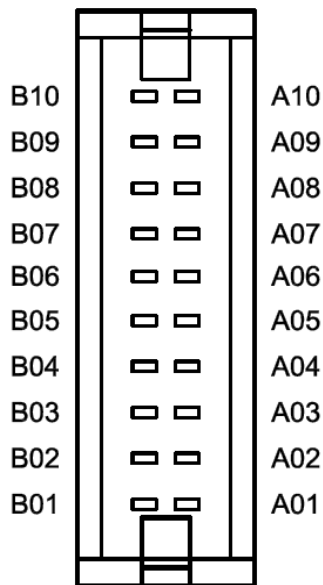
## Wiring with Smart Link



ML50 Module	Smart Link Terminal	Description	Cable number	Cable Specification
Main Unit (20+20 pin)	SLP-T40P	40pin Main I/O wiring	SLT-CT101-XBM	Soft tube type 1meter(39.4inch)
			SLT-CT051-XBM	Soft tube type 0.5meter(19.7inch)
Expansion Input and Output(40pin)	SLP-T40P	40pin 32 point expansion I/O wiring	SLT-CT151-XBE	Soft tube type 1.5meter(59.1inch)
			SLT-CT301-XBE	Soft tube type 3meter(118.1inch)

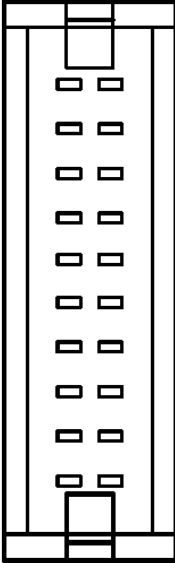
### Terminal Layout

#### 20+20pin Terminal Layout(Input)

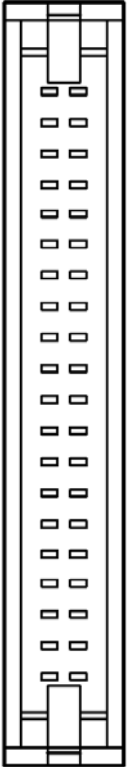


PLC	Smart Link		
	Pin number	MLM-DN16S	MLM-DN32S
B10	00	00	A1
B09	01	01	B1
B08	02	02	A2
B07	03	03	B2
B06	04	04	A3
B05	05	05	B3
B04	06	06	A4
B03	07	07	B4
B02	COM0	COM0	A5
B01	COM0	COM0	B5
A10	NC	08	A6
A09	NC	09	B6
A08	NC	0A	A7
A07	NC	0B	B7
A06	NC	0C	A8
A05	NC	0D	B8
A04	NC	0E	A9
A03	NC	0F	B9
A02	NC	COM1	A10
A01	NC	COM1	B10

## 20+20pin Terminal Layout(Output)

	PLC			Smart Link	
	Pin number	MLM-DN16S		MLM-DN32S	SLP-T40P
	B10	20	20	20	A11
	B09	21	21	21	B11
	B08	22	22	22	A12
	B07	23	23	23	B12
	B06	24	24	24	A13
	B05	25	25	25	B13
	B04	26	26	26	A14
	B03	27	27	27	B14
	B02	+12 / 24V	+12 / 24V	+12 / 24V	A15
	B01	+12 / 24V	+12 / 24V	+12 / 24V	B15
	A10	NC	28	28	A16
	A09	NC	29	29	B16
	A08	NC	2A	2A	A17
	A07	NC	2B	2B	B17
	A06	NC	2C	2C	A18
	A05	NC	2D	2D	B18
	A04	NC	2E	2E	A19
	A03	NC	2F	2F	B19
A02	COM0	COM0	COM0	A20	
A01	COM0	COM0	COM0	B20	

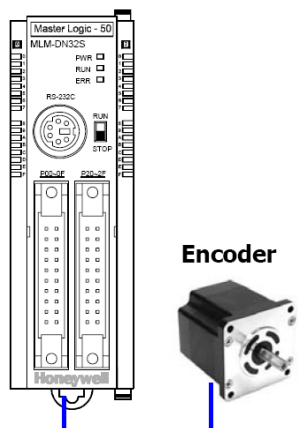
## 40+40pin Terminal Layout(Output)

	PLC						Smart Link	
	Pin number	MLE-DC32A <sup>(Note1)</sup>			MLE-TN32A <sup>(Note1)</sup>		SLP-T40P (I/O Link terminal)	
	B20	A20	00(20)	10(30)	00(20)	10(30)	A1	A11
	B19	A19	01(21)	11(31)	01(21)	11(31)	B1	B11
	B18	A18	02(22)	12(32)	02(22)	12(32)	A2	A12
	B17	A17	03(23)	13(33)	03(23)	13(33)	B2	B12
	B16	A16	04(24)	14(34)	04(24)	14(34)	A3	A13
	B15	A15	05(25)	15(35)	05(25)	15(35)	B3	B13
	B14	A14	06(26)	16(36)	06(26)	16(36)	A4	A14
	B13	A13	07(27)	17(37)	07(27)	17(37)	B4	B14
	B12	A12	08(28)	18(38)	08(28)	18(38)	A5	A15
	B11	A11	09(29)	19(39)	09(29)	19(39)	B5	B15
	B10	A10	0A(2A)	1A(3A)	0A(2A)	1A(3A)	A6	A16
	B09	A09	0B(2B)	1B(3B)	0B(2B)	1B(3B)	B6	B16
	B08	A08	0C(2C)	1C(3C)	0C(2C)	1C(3C)	A7	A17
	B07	A07	0D(2D)	1D(3D)	0D(2D)	1D(3D)	B7	B17
	B06	A06	0E(2E)	1E(3E)	0E(2E)	1E(3E)	A8	A18
	B05	A05	0F(2F)	1F(3F)	0F(2F)	1F(3F)	B8	B18
	B04	A04	NC	NC	NC	NC	A9	A19
	B03	A03	NC	NC	NC	NC	B9	B19
B02	A02	COM	COM	DC12/24V	COM	A10	A20	
B01	A01					B10	B20	

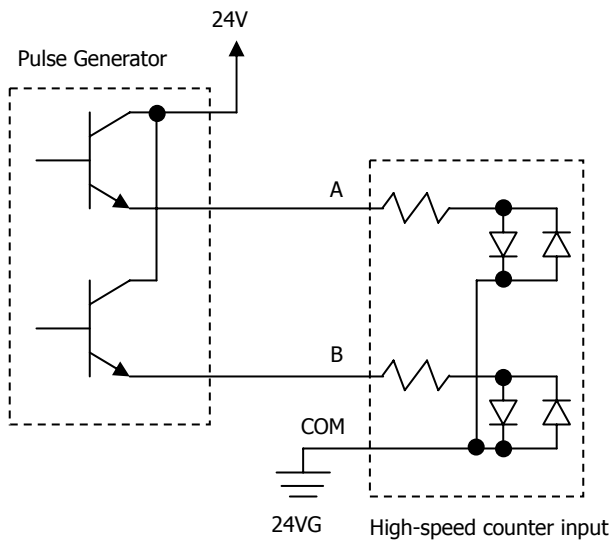
\*NOTE1) The number inside ( ) is the address of 64point I/O module.



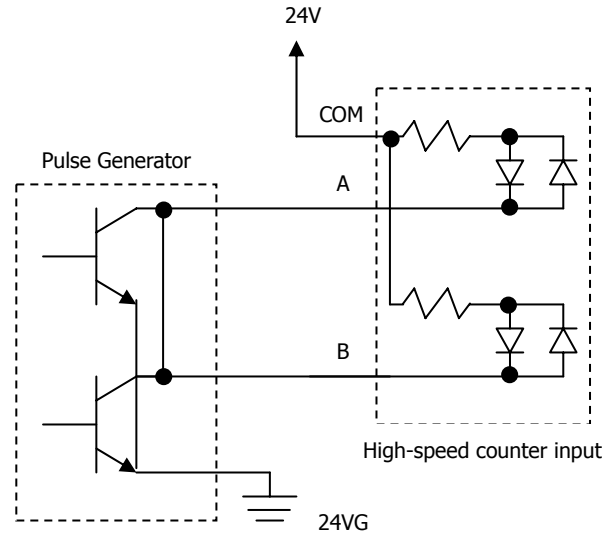
Wiring Diagram	
Model	Wiring Diagram
MLM-DN16S Wiring Diagram	<p>The diagram shows 16 contacts labeled 00 through 07 and 20 through 27. Contacts 00-07 are connected to terminals B1-B8. Contacts 20-27 are connected to terminals B11-B18. A DC24V source is connected to contact 00. A DC12/24V source is connected to terminal B20.</p>
MLM-DN32S Wiring Diagram	<p>The diagram shows 32 contacts labeled 00 through 07, 08 through 0F, and 20 through 27. Contacts 00-07 connect to B1-B8, 08-0F to B9-B16, and 20-27 to B17-B20. A DC24V source is connected to contact 00. A DC12/24V source is connected to terminal B20.</p>
MLE-DC32A Input Wiring Diagram	<p>The diagram shows 32 contacts labeled 00 through 0F and 10 through 1F. Contacts 00-0F connect to B1-B16, and 10-1F connect to B17-B20. A DC24V source is connected to contact 00.</p>
MLE-TN32A Output Wiring Diagram (SLP-40P)	<p>The diagram shows 32 contacts labeled 00 through 0F and 10 through 1F. Contacts 00-0F connect to B1-B16, and 10-1F connect to B17-B20. A DC12/24V source is connected to contact 00.</p>

Specifications					
High Speed Counter					
Function					
Pulse Input Mode	Incremental / Decremental counter by program when input is 1-phase pulse.				
	Incremental / Decremental counter by B-axis input when input is 1-phase pulse.				
	Incremental / Decremental counter by Incremental / Decremental input when input is 2-phase pulse.				
	Incremental / Decremental counter (4 multiplication) by phase difference when input 2-phase pulse.				
	Incremental counter by CW/CCW input				
Counter Mode	Linear counter				
	Ring counter: Counter rotating between value in 0 ~ (Ring counter setting value -1)				
Present Value Preset	Changes present value of counter to optional value – Internal preset / External preset				
Comparison Output	Sets output contact when counter value corresponds with comparison output condition. Comparison output condition : >, ≥, =, ≤, <, inclusion, exclusion				
No. of Rotation	Outputs the rotation number of input pulse per unit time.				
Performance					
No. of Points	1-phase 4 points, 2-phase 2 points				
Input Points	A Phase, B Phase, Preset input				
Counting Range	Linear counter: - 2,147,483,648 ~ 2,147,483,647 (Binary 32 Bit)				
Counting Speed	1-phase 20kpps/2-phase 10 kpps				
Incremental Functions	Ring counter, preset, Rotation number per unit time, Comparison output, Latch counter				
Electrical					
Input Voltage	DC 24V (20.4V ~ 28.8V)				
Input Current	7mA				
On Guaranteed Voltage (Minimum)	DC 20.4 V				
Off Guaranteed Voltage (Maximum)	DC 6V				
High-speed Counter Terminal					
High speed counter accurately counts the number of high speed pulse generated from encoder or pulse generator.					
 <p>High speed Counter One phase : Max. 4Ch, 20kpps Two phase : Max. 2Ch, 10kpps</p>	Terminal Number	1-Phase		2-Phase	
			Signal name	Description	Signal name
	000	Ch0 counter input	Counter input	Ch0 A-axis input	A-axis input
	001	Ch1 counter input	Counter input	Ch0 B-axis input	B-axis input
	002	Ch2 counter input	Counter input	Ch2 A-axis input	A-axis input
	003	Ch3 counter input	Counter input	Ch2 B-axis input	B-axis input
	004	Ch0 preset 24V	Preset input	Ch0 preset 24V	Preset input
	005	Ch1 preset 24V	Preset input	-	-
	006	Ch2 preset 24V	Preset input	Ch2 preset 24V	Preset input
	007	Ch3 preset 24V	Preset input	-	-
COM0	Input COMMON	COMMON	Input COMMON	COMMON	

## Encoder Wiring



Voltage Output Encoder



Open Collector Encoder

## Operation Setting Address of High-speed Counter

ITEM	Device Range for each Channel				Remark
	CH1	CH2	CH3	CH4	
Counter Enable	K2600	K2700	K2800	K2900	Bit
Counter Internal Preset Assignment	K2601	K2701	K2801	K2901	Bit
Counter External Preset Enable	K2602	K2702	K2802	K2902	Bit
Substraction Counter Assignment	K2603	K2703	K2803	K2903	Bit
Comparison Output Enable	K2604	K2704	K2804	K2904	Bit
Rotation Number per Unit Time Enable	K2605	K2705	K2805	K2905	Bit
Latch Counter Enable	K2606	K2706	K2806	K2906	Bit
Carry Signal(Bit)	K2610	K2710	K2810	K2910	Bit
Borow Signal(Bit)	K2611	K2711	K2811	K2911	Bit
Comparison Output Signal	K2612	K2712	K2812	K2912	Bit

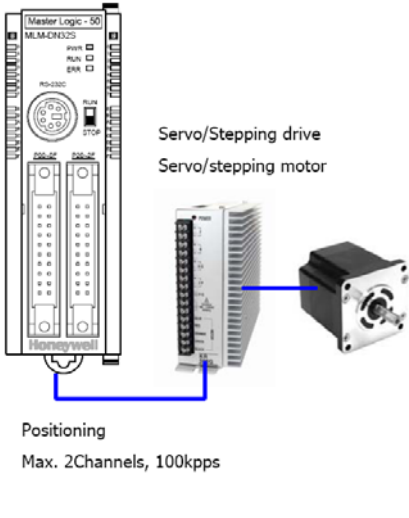
## Parameter Setting Address of High-speed Counter

ITEM	Description		Device Range for each Channel				Remark
	Setting Value	Setting Description	CH1	CH2	CH3	CH4	
Counter Enable	H0000 H0001	Linear Counter Setting Ring Counter Setting	K300	K330	K360	K390	Word
Pulse Input Mode Setting	H0000 H0001 H0002 H0003	1phase 1input 1multiplication 1phase 2input 1multiplication CW/CCW 2phase 4multiplication	K301	K331	K361	K391	Word
Comparison Output Mode Setting	H0000 H0001 H0002 H0003 H0004 H0005 H0006	(Single comparison) < (Single comparison) ≤ (Single comparison) = (Single comparison) ≥ (Single comparison) > (Section comparison) Inclusion (Section comparison) Exclusion	K302	K332	K362	K392	Word
Internal Preset Value Setting	-2,147,483,648~2,147,483,647		K304	K334	K364	K394	Word

External Preset Value Setting	-2,147,483,648~2,147,483,647		K306	K336	K366	K396	Word
Max. Ring Counter Value Setting	-2,147,483,648~2,147,483,647		K310	K340	K370	K400	Word
Min. Comparison Output Value Setting	-2,147,483,648~2,147,483,647		K312	K342	K372	K402	Word
Max. Comparison Output Value Setting	-2,147,483,648~2,147,483,647		K314	K344	K374	K404	Word
Comparison Output Contact Assignment	0x0000 0x0001 0x0002 0x0003 0x0004 0x0005 0x0006 0x0007	P20 P21 P22 P23 P24 P25 P26 P27	K320	K350	K380	K410	Word
Rotation Number Setting per Unit Time	0 ~ 60000		K322	K352	K382	K412	Word
Pulse Number Setting per Rotation	0 ~ 60000		K323	K353	K383	K413	Word
<b>High Speed Counter Monitoring</b>							
<b>Special Function Monitoring</b>							
Special Function Monitoring in SoftMaster can monitor operation condition and data of high speed counter while PLC is on-line.							
<b>Device Monitoring</b>							
While PLC is on-line, Device Monitoring can monitor the operation condition and data by monitoring the device setting area.							
<b>Parameter Setting Address of High-speed Counter</b>							
Item	Device Range for Each Channel				Remark		
	CH1	CH2	CH3	CH4			
Present Counter Value	K262	K272	K282	K292	Double Word		
No. of Rotation per Unit Time	K264	K274	K284	K294	Double Word		
Error Code	K266	K276	K286	K296	Word		
<b>Error Code of High-speed Counter</b>							
Error Code(Decimal)	Error Description						
20	Out of Counter type range						
21	Out of Pulse input type range						
22	When Requesting RUN of CH1[3] during 2-phase operation of CH0[2] (Use of CH1[3] is not available during 2-phase operation of CH0[2])						
23	Out of Comparison output type range						
25	Internal preset value setting error(Out of counter range)						
26	External preset value setting error(Out of counter range)						
27	Ring counter setting error(Ring counter value should be set as 2 or more)						
28	Comparison minimum value setting error(Out of minimum input range)						
29	Comparison maximum value setting error(Out of maximum input range)						
30	Minimum comparison output1 > Maximum comparison output1						
31	Contact assignment value setting error of comparison output						
34	Out of unit time setting range						
35	Out of pulse value range per rotation						

Specifications						
<b>Positioning Function</b>						
<b>Performance</b>						
No. of Control Axis		2-axis				
Interpolation		2-axis linear interpolation				
Control Mode		Position control, Speed control, Speed / Position switching control, Position / Speed switching control				
Control Unit		Pulse				
Positioning Data		30-step pattern for each axis (set in SoftMaster) (Operation step number: 1~30)				
Positioning Monitor		Dedicated monitoring function for positioning in SoftMaster				
Back-up		Permanent Backup of downloaded parameter (FLASH memory)				
		2-month Super Cap. Backup of parameter / data modified during operation (RAM)				
		Permanent Backup of parameter / data in RAM by instruction (FLASH memory)				
Positioning	Positioning Method		Absolute / Incremental method			
	Positioning Range		- 2,147,483,648 ~2,147,483,647			
	Speed Range		1~ 100,000 (pulse / sec)			
	Acceleration / Deceleration Type		Trapezoidal acceleration / deceleration			
	Acceleration / Deceleration Time		1~ 10,000 msec ( 4 patterns each can be set)			
Maximum Output Pulse		100 kpps				
Maximum Distance of Connections		2 meters (6.56 feet)				
<b>Electrical</b>						
Output	Signal		Output Pulse			
	Rated Input Voltage		DC 5 ~ 24V			
	Load Voltage Range		DC 4.75 ~ 26.4V			
	Max. Load Current/Inrush Current		100mA (1 point) 1A / 10msec or less			
	Max. Voltage Drop(ON)		DC 0.3V or less			
	Leakage Current(OFF)		0.1mA or less			
	Response Time		100μs or less			
Input	Signal		External High Limit	External Low Limit	Approximate Zero	Zero
	Rated Input Voltage / Current		DC 24V / 7mA		DC 24V / 4mA	
	Load Voltage Range		DC 20.4 ~ 28.8 V			
	ON Voltage / Current		DC 19V / 5.7 mA or more		DC 19V / 3.4 mA or more	
	OFF Voltage / Current		DC 6V / 1.8 mA or less		DC 6V / 1.1 mA or less	
	Input Resistance		3.3 KΩ		5.6 KΩ	
	Response Time		0.5 ms or less			

## Positioning Function Terminals

	Item	Pin Number		Signal Name		Direction of Positioning Signal	Operating Direction
		X axis	Y axis				
	Output	A1	A2	Pulse	Pulse output (open collector)	-	-
		A3	A4	Direction	Pulse output (open collector)	-	-
		A9/A10		DC24V	External 24V Power supply	-	-
		B9/B10		Output COM	External 24V GND	-	-
	Input	A1	A3	Limit L	Low Limit	-	Edge
		A2	A4	Limit H	High Limit	-	Edge
		A5	A7	DOG	Near Point	-	Edge
		A6	A8	Zero	Zero signal (+24V)	-	Edge
A9/10, B9/10		Input COM	COMMON	-	-		

### Storage Range of Positioning Parameter

Assigned Parameters are stored on the following memory range. While operating PLC, command parameters can be changed by changing data in corresponding range.

	Item	Setting Range	Initial Value	Device Range		Remark
				X axis	Y axis	
Basic Parameter	Positioning	0:Disabled,1:Enabled	0	K4870	K5270	Bit
	Pulse Output Level	0:Low active, 1:High active	0	K4871	K5271	Bit
	Bias Speed	1~100,000 [Pulse/sec]	1	K450	K490	Double Word
	Speed Limit	1~100,000 [Pulse/sec]	100,000	K452	K492	Double Word
	Acceleration Time1	0~10,000 [Unit:msec]	500	K454	K494	Word
	Deceleration Time1	0~10,000 [Unit:msec]	500	K455	K495	Word
	Acceleration Time2	0~10,000 [Unit:msec]	1,000	K456	K496	Word
	Deceleration Time2	0~10,000 [Unit:msec]	1,000	K457	K497	Word
	Acceleration Time3	0~10,000 [Unit:msec]	1,500	K458	K498	Word
	Deceleration Time3	0~10,000 [Unit:msec]	1,500	K459	K499	Word
	Acceleration Time4	0~10,000 [Unit:msec]	2,000	K460	K500	Word
	Deceleration Time4	0~10,000 [Unit:msec]	2,000	K461	K501	Word
	Soft High Limit	-2,147,483,648~2,147,483,647[pulse]	2,147,483,647	K462	K502	Double Word
	Soft Low Limit	-2,147,483,648~2,147,483,647[pulse]	-2,147,483,648	K464	K504	Double Word
	Backlash Compensation Amount	0~65,535[pulse]	0	K466	K506	Word
Detection of Soft High/Low Limit during equal speed operation	0:Disabled,1:Enabled	0	K4684	K5084	Bit	
Use of High/Low Limit	0:Disabled,1:Enabled	1	K4872	K5272	Bit	
Zero/ Manual Parameter	Zero Address	-2,147,483,648~2,147,483,647[pulse]	0	K469	K509	Double Word
	Zero-return High Speed	1~100,000 [Pulse/sec]	5,000	K471	K511	Double Word
	Zero-return Low Speed	1~100,000 [Pulse/sec]	500	K473	K513	Double Word
	Zero-return Acceleration Time	0~10,000 [Unit:msec]	1,000	K475	K515	Word
	Zero-return Deceleration Time	0~10,000 [Unit:msec]	1,000	K476	K516	Word

	Zero-return Dwell Time	0~50,000 [Unit:msec]	0	K477	K517	Word
	Zero-return method	0 : Zero detection after near zero OFF 1: Zero detection after deceleration when near zero is ON 2 : Zero detection by near zero	0	K4780 K4781	K5180 K5181	Word
	Zero-return direction	0:Forward, 1:Reverse	1	K4782	K5182	Bit
	JOG High Speed	1~10,000 [Pulse/sec]	5,000	K479	K519	Double Word
	JOG Low Speed	1~10,000 [Pulse/sec]	1,000	K481	K521	Double Word
	JOG Acceleration time	0~65,535[Unit:msec]	1,000	K483	K523	Word
	JOG Deceleration time	0~65,535[Unit:msec]	1,000	K484	K524	Word
	Inching Speed	0~65,535[Pulse/sec]	100	K485	K525	Word

## Positioning Dedicated Instruction

Instruction <sup>*1)</sup>	Description	Instruction Operand <sup>*1)</sup>
ORG	Zero Return Start	Slot, Instruction axis
FLT	Floating-point zero setting	Slot, Instruction axis
DST	Direct Start	Slot, Instruction axis, Position, Speed, Dwell time, M code, Control word
IST	Indirect Start	Slot, Instruction axis, Step number
LIN	Linear Interpolation Start	Slot, Instruction axis, Step number, Axis information
SST	Simultaneous Start	Slot, Instruction axis, X-axis step number Y-axis step number, Z-axis step number, Axis information
VTP	Speed/Position Conversion	Slot, Instruction axis
PTV	Position/Speed Conversion	Slot, Instruction axis
STP	Stop	Slot, Instruction axis, Deceleration
SSP	Position Synchronization	Slot, Instruction axis, Step number, Master-axis position, Master-axis setting
SSS	Speed Synchronization	Slot, Instruction axis, Master-axis ratio, Slave-axis ratio, Master-axis setting
POR	Position Override	Slot, Instruction axis, Position
SOR	Speed Override	Slot, Instruction axis, Speed
PSO	Positioning Speed	Slot, Instruction axis, Position, Speed
INCH	Inching	Slot, Instruction axis, Inching amount
MOF	M code OFF	Slot, Instruction axis
PRS	Present Position Preset	Slot, Instruction axis, Position
EMG	Emergency Stop	Slot, Instruction axis
CLR	Error Reset, Output Disable Annulment	Slot, Instruction axis, Pulse output Enable/Disable
WRT	Parameter / Operation Data Saving	Slot, Instruction axis, Axis information

\*1) In instruction, the slot should be assigned as number '0'.

Operation Data Range for Positioning						
Step Number	Item	Specification	Initial Value	Device Range		Remark
				X-axis	Y-axis	
1	Coordinates	0:Absolute, 1:Relative	Absolute	K5384	K8384	Bit
	Operation Pattern	0:End, 1:Continue, 2:Repeat	End	K5382~3	K8382~3	Bit
	Control Method	0:Position control, 1:Speed control	Position	K5381	K8381	Bit
	Operation Method	0:Single operation, 1:Repeated Operation	Single	K5380	K8380	Bit
	Repeating Step	0~30	0	K539	K839	Word
	Targeted Position	-2,147,483,648~2,147,483,647[pulse]	0	K530	K830	Double Word
	M Code Number	0~65,535	0	K537	K837	Word
	Accel/Decel Number	0:Number1, 1:Number2 2:Number3, 3: :Number4	0	K5386	K8386	Bit
				K5387	K8387	Bit
	Operation Speed	1~100,000[pulse/sec]	0	K534	K834	Double Word
Dwell Time	1~50,000[pulse/sec]	0	K536	K836	Word	
2	Same items as Step number 0			K540~549	K840~849	-
3	Same items as Step number 0			K550~559	K850~859	-
4~29	Same items as Step number 0			K560~819	K860~1119	-
30	Same items as Step number 0			K820~829	K1120~1129	

Operation Monitoring Range for Positioning							
Item	Device Range						Remark
	X axis			Y axis			
	Word	Bit	Address	Word	Bit	Address	
Busy Signal	K420	0	K4200	K430	0	K4300	Operation Monitoring
ERROR		1	K4201		1	K4301	
Positioning Completed		2	K4202		2	K4302	
M code ON		3	K4203		3	K4303	
Zero Determination		4	K4204		4	K4304	
Output Disable		5	K4205		5	K4305	
Stop		6	K4206		6	K4306	
High Limit Detection		8	K4208		8	K4308	
Low Limit Detection		9	K4209		9	K4309	
Emergency Stop		A	K420A		A	K430A	
Forward/Reverse Rotation		B	K420B		B	K430B	
Operation (Acceleration)		C	K420C		C	K430C	
Operation (Fixed Speed)		D	K420D		D	K430D	
Operation (Deceleration)		E	K420E		E	K430E	
Operation (Dwell)		F	K420F		F	K430F	
Operation Control (Position Control)	K421	0	K4210	K431	0	K4310	
Operation Control (Speed Control)		1	K4211		1	K4311	

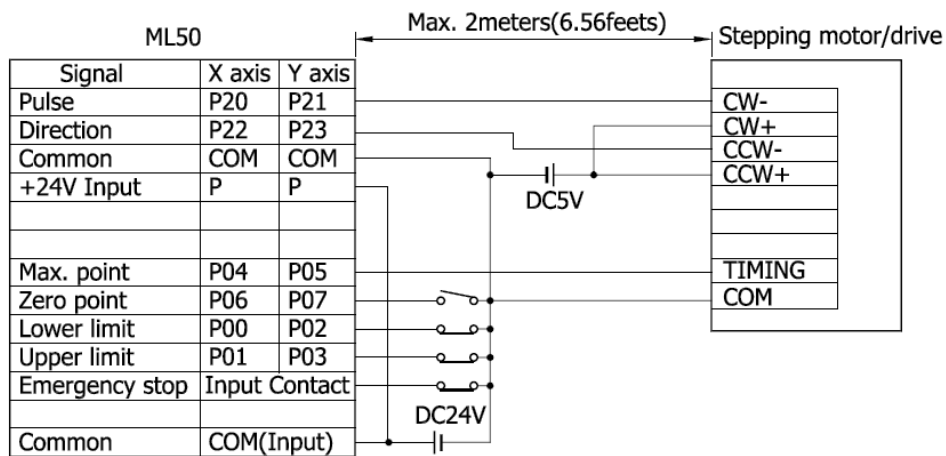


Operation Control (Linear Interpolation)		2	K4212		2	K4312
Zero Return		5	K4215		5	K4315
Position Synchronization		6	K4216		6	K4316
Speed Synchronization		7	K4217		7	K4317
JOG Low Speed		8	K4218		8	K4318
JOG High Speed		9	K4219		9	K4319
Inching		A	K421A		A	K431A
Present Position	K422	-	K422	K432	-	K432
Present Speed	K424	-	K424	K434	-	K434
Step Number	K426	-	K426	K436	-	K436
Error Code	K427	-	K427	K437	-	K437
M Code	K428	-	K428	K438	-	K438
JOG Operation (Start)	K429		K4290	K439	0	K4390
JOG Forward Operation			K4291		1	K4391
JOG Reverse Operation			K4292		2	K4392
JOG Low/High Speed			K4293		3	K4393

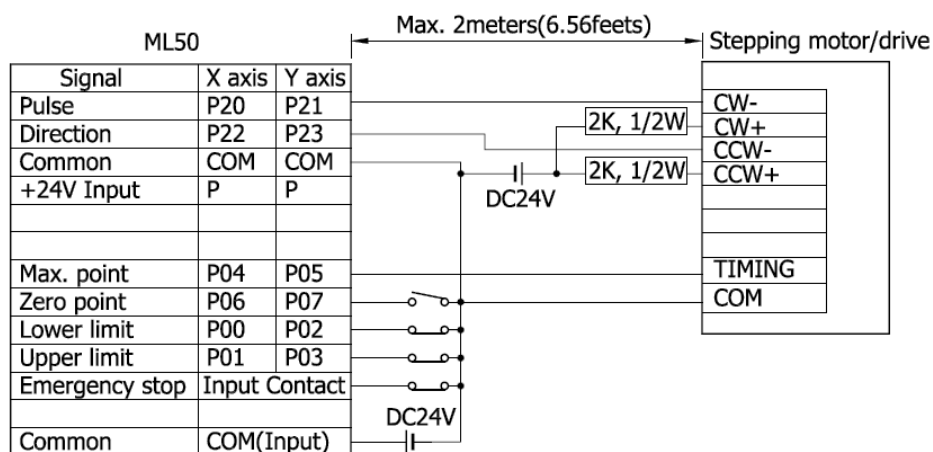
JOG Command

## Positioning Function Wiring

- With DC5V



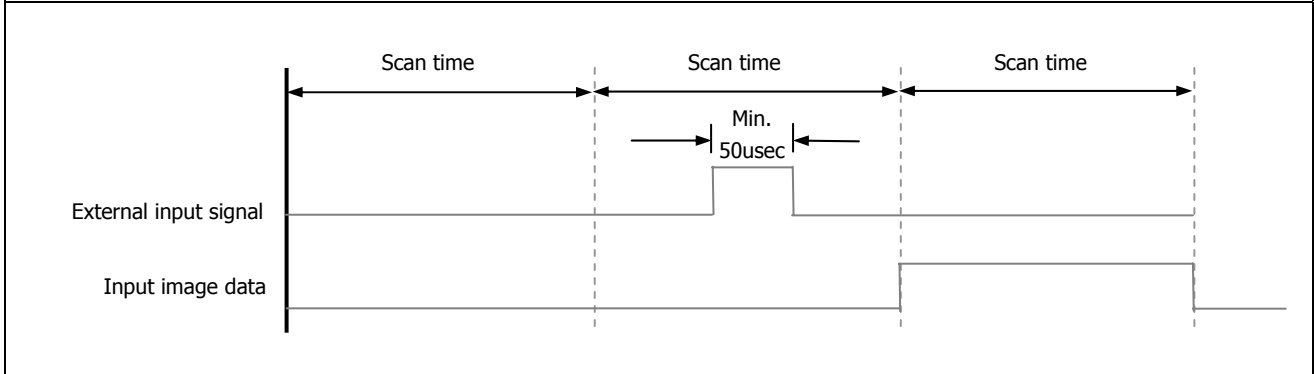
- With DC24V



Specifications		
<b>PID Control</b>		
<b>Features</b> <ul style="list-style-type: none"> <li>- Built-in PID control function in ML50's main unit</li> <li>- Various control operation (P, PI, PD, PID, On/Off)</li> <li>- PWM (Pulse Width Modulation) output of control result</li> <li>- Forward, Reverse, Forward / Reverse Mixed Operation</li> <li>- Enhanced response to disturbance with cascade loop</li> <li>- Available to use 2 set values and PID parameters simultaneously according to operation zone</li> <li>- Various PID control configurations with its SV Ramp, PV Tracking, Delta MV, MV Preset, Alarm functions</li> </ul>		
<b>Performance</b>		
No. of Control Loop	16-loop independent control	
Control Mode	P control, PI control, PD control, PID control	
Control Period	10ms ~ 6563.5 ms (Setting unit: 0.1ms)	
Function	Forward / Reverse Mixed Control	Switching control direction automatically when exceeding dead band
	Cascade	Improved control precision by serial connection between Master loop and Slave loop
	SV Ramp	Preventing overload caused by excessive SV change by setting variation slope
	Alarm	Improved control stability with various alarm function such as MV high limit / low limit, PV high limit / low limit, PV variation width
	Auto Tuning	Auto tuning with improved auto-tuning algorithm
	Additional Function	PWM output, PV tracking, $\Delta$ MV, $\Delta$ PV, etc.

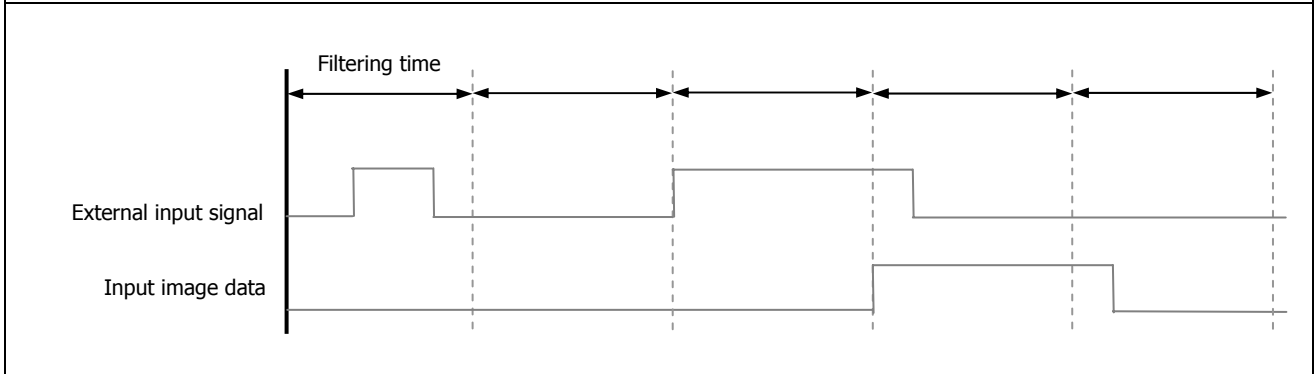
## Pulse catch / Input Filter / Task

**Pulse Catch**  
 When the On-condition time of input signal (P0000~P0007) is shorter than 1 scan time (Min. 50μs), Pulse catch processes the input signal as normal input.



No. of Setting Points	8 points : P000~P007
Min. Pulse Width	50usec

**Input Filter**  
 Input filter prevents processing of input signal that is shorter that the filtering time. (Filtering time set by parameter). In the application site where noise is frequently generated. Input filter prevents wrong input caused by noise.

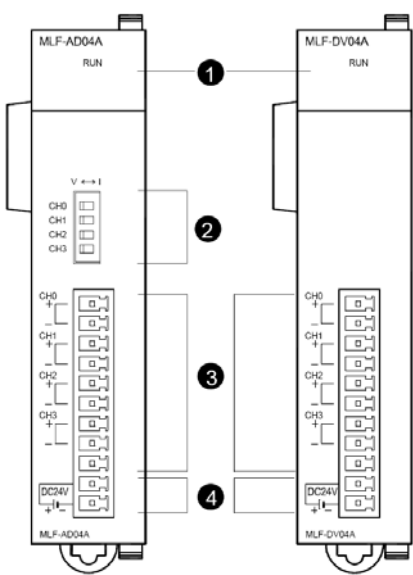


No. of Setting Points	Every input contact
Input Filtering Time Setting	Assigning for each module
Setting Range	1-100msec( 1, 3, 5, 10, 20, 70, 100)

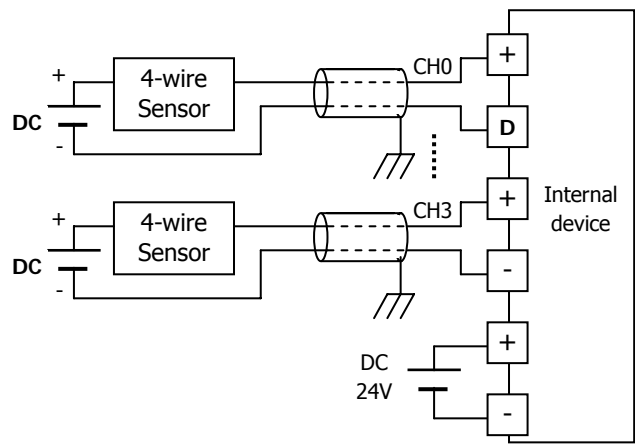
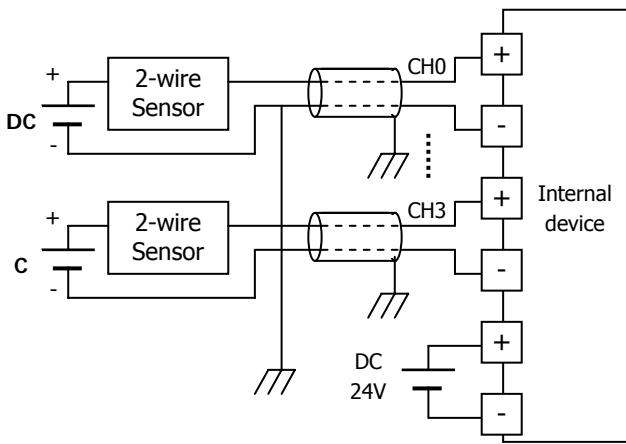
**Task**  
 Task function is the processing method of internal / external signal generated periodically (Total 24 Tasks can be assigned). It stops operation of scan program for the moment and then executes the assigned task.

### Types of Task

Initialization Task Setting	Running a task one time before INIT_DONE at initial execution	
Fixed Cycle Task Setting	No. of Setting Points	8 points
	Setting Range	1 ~ 42,94,967,295 msec
External Points Task Setting	No. of Setting Points	8 points: P000 ~ P007
	Minimum Pulse Width	Min. 50usec
	Condition	Up, Down, Change
Internal Device Task Setting	No. of Setting Points	8 points
	Condition	Up, Down, change, On, Off

Specifications							
Analog Input / Output							
Performance							
Model		Analog Input			Analog Output		
		MLF-AD04A			MLF-DV04A		
Analog Range		DC 0 ~ 10V(Input Resistance : 1M $\Omega$ min.) DC 4 ~ 20mA DC 0 ~ 20mA(Input Resistance 250 $\Omega$ )			DC 0 ~ 10V(Load Resistance $\geq$ 1k $\Omega$ )		
Analog Range Selection		- Analog input range can be selected by user (sequence) program - Each input range can be set for each channel.			-		
Digital Data	Analog Range	0 ~ 10V	4~20mA	0 ~ 20mA	0 ~ 10V		
	Unsigned Value	0 ~ 4000				0 ~ 4000	
	Signed Value	-2000 ~ 2000				-2000 ~ 2000	
	Precise Value	0 ~ 1000	400 ~ 2000	0 ~ 2000	0 ~ 1000		
	Percentile Value	0 ~ 1000				0 ~ 1000	
	Data format of digital output is set by user program of software package. (Setting for each channel is available.)						
Resolution(1/4000)		2.5mV, at 0 ~ 10V			2.5mV		
		5.0uA, at 4~20mA or 0~20mA					
Max. Conversion Speed		1.5msec / channel			1msec / channel		
Max. Absolute Input / Output		$\pm$ 15V		$\pm$ 25mA	$\pm$ 15V		
Accuracy		$\pm$ 0.5% or less			$\pm$ 0.5% or less		
Analog I/O Channels		4 channel / module					
Insulation Method		Photo coupler insulation between I/O terminal and power supply.					
Connection Terminal		11-point terminal block					
Occupied I/O Points		Fixed type : 64points					
Current Consumption		DC24V:80mA(External input)			DC24V:200mA(External input)		
Names and Functions							
		No	Name	Description			
		1	RUN LED	Indicates condition of module <ul style="list-style-type: none"> <li>• LED ON : Normal condition</li> <li>• LED Flicking(ON/OFF) : Error</li> <li>• LED OFF : Power off or Module malfunction</li> </ul>			
		2	Input Selection Switch	Voltage/Current selection terminal <ul style="list-style-type: none"> <li>• V : Voltage input selection</li> <li>• I : Current input selection</li> </ul>			
		3	External Connection Terminal	External device connection			
4	External Power Supply Terminal	External DC24V input					

## Analog Input Wiring



\* Use 22AWG, 2 conductor, twist shield cable when wiring between analog module and external device.

## Analog / Digital Conversion Characteristics (MLF-AD04A)

Output Value Selection	Precise Value			Percentile Value	-2,000 ~ 2,000	0 ~ 4,000	
	4~20mA	0~20mA	0~10V				
Digital Output	2,023	2,023	1,011	1,011	2,047	4,047	
	2,000	2,000	1,000	1,000	2,000	4,000	
	1,600	1,500	750	750	1,000	3,000	
	1,200	1,000	500	500	0	2,000	
	800	500	250	250	-1,000	1,000	
	400	0	0	0	-2,000	0	
381				-2,048	-48		
Analog Input 0 ~ 10V 0 ~ 20mA 4 ~ 20mA							0    2.5    5    7.5    10 0    5    10    15    20 4    8    12    16    20

\* Note1) Supported in case of analog input is 4~20mA.

## Analog Output Wiring

	Analog output 
	Digital output 0~4000 -2000~2000 Percentile 0    1000    2000    3000    4000 -2000    -1000    0    1000    2000 0    250    500    750    1000

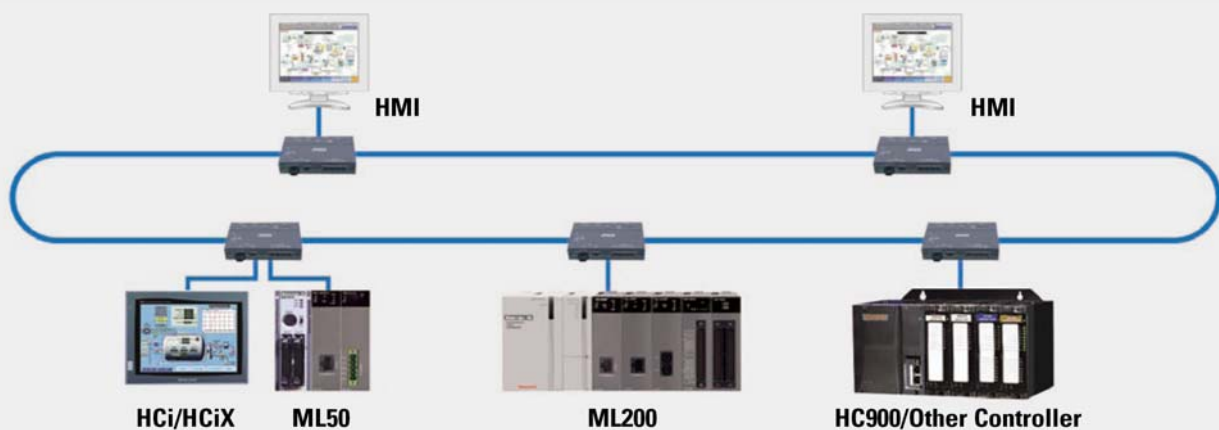
## Specifications

### Communication – Fast Ethernet

#### Features

- 10/100 Base-Tx Fast Ethernet for industrial use (IEEE802.3)
- Dedicated service for HMI connection (Modbus-TCP protocol)
- High speed link communication with high-level PLC(MasterLogic200, MasterLogic200i)
- Remote program, Remote monitoring with SoftMaster remote service
- Network security with Host table(limitation of unwanted connections)
- Convenient network system setting and various self-diagnosis / monitoring with SoftMaster-NM
  - Monitoring network information (Auto scan)
  - Checking module in network (PING)
  - Providing information of each service  
(High speed link, P2P, dedicated service, media condition)
- User protocol editing and P2P service (Communication with other brand's equipment)

### Network with Ethernet



### Performance

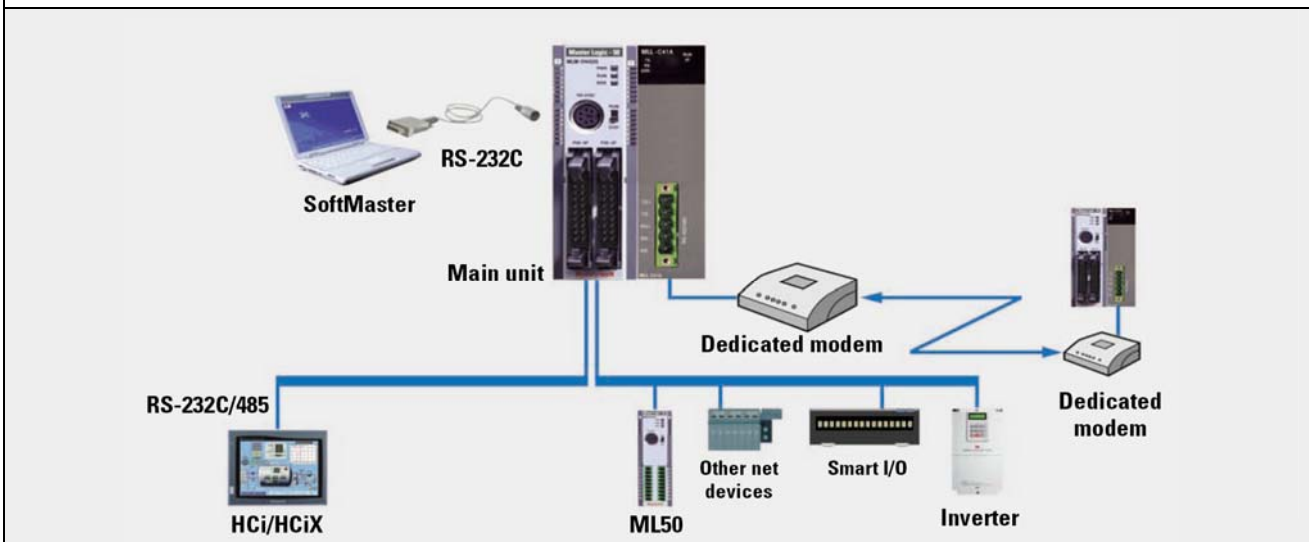
Model	MLL-EMTA	
Communication Spec.	10/100 Base-TX	
Protocol	TCP/IP, UDP/IP	
Service	With ML PLCs	High-speed link, P2P service
	With Other Devices	P2P service
	Application	Dedicated protocol service, SoftMaster Service
HS Link Sending / Receiving	200 words / block(Max. 128 blocks)	
No. of Channel Connectable to Upper Stage	8 channels	
Service	Communication with PC (HMI) and external devices, high-speed communication among ML PLC's	
Media	UTP/STP Category 5	
Current Consumption(mA)	410	

## Communications – Snet

### Features

- Max. 2 modules mountable for 1 main unit. Total 5 channels of communication in 1 MasterLogic-50 system(including Loader)
- Max. 32-unit connection through RS-485 communication.
- Protocol editing and parameter setting using SoftMaster-NM.
- Configurable communication speed setting (300 ~ 115,200 bps)
- Long distance communication system using dedicated modem (expansion RS-232C Communication module)
- Full duplex / Half Duplex communication (expansion RS485 Communication module)
- PTP : User-defined Communication and Modbus communication master
- Modbus RTU / ASCII drivers for HMI connection
- Various diagnosis function using SoftMaster-NM (I/O information, CPU, Link, Service, LOG)
- Simultaneous monitoring of sending / receiving frame and checking the result of frame
- Communication service information (Checking information of dedicated service, P2P service)

### System Configuration



### Performance

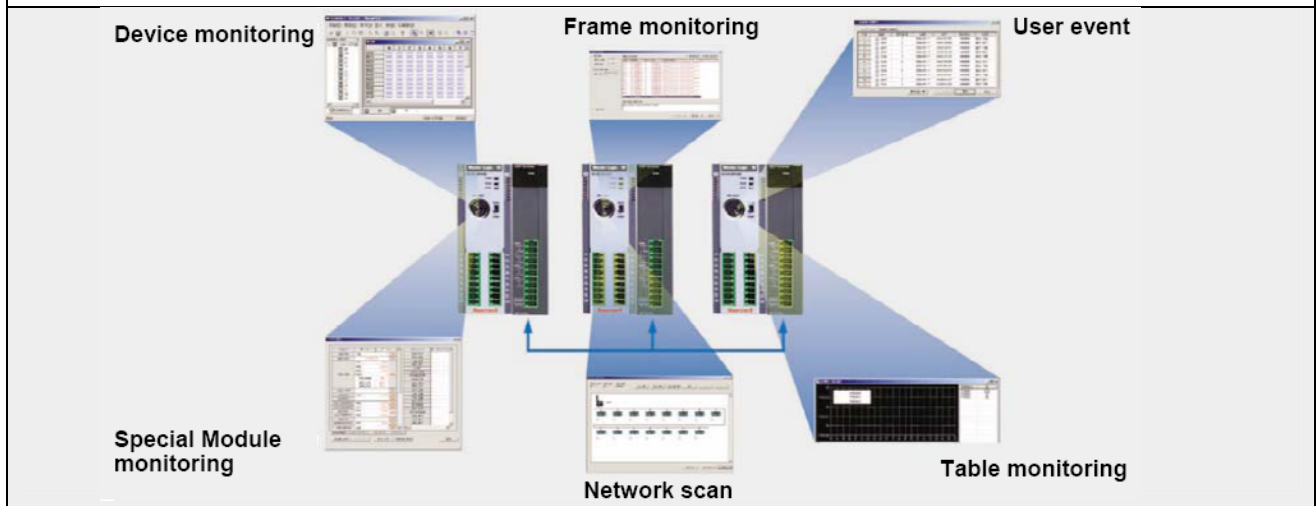
Model	Built-in RS-232C	MLL-CU21A	Built-in RS485	MLL-CU41A
Interface	RS-232C 1Ch	RS-232C 1Ch	RS-485 1Ch	RS-422/485 1 Ch
Modem Connection	Remote communication with external devices via modem connection, Available for only RS-232C port.			
Comm. Mode	Dedicated Mode	1:1 or 1:N communication using ML dedicated protocol		
	SoftMaster	Program upload / download and remote control		
	P2P Mode	Communication by protocol using SoftMaster-NM (Interface with other PLC's), HMI, Modbus RTU / ASCII master communication		
Operation Mode	Server(Slave)	Remote connection simultaneously using Modbus server, user-defined		
	Master	Modbus RTU / ASCII master, user defined		
Data Type	Start bit	1		
	Data bit	7 or 8		
	Stop bit	1 or 2		
	Parity	Even / Odd / None		
	Setting	Basic parameter setting with SoftMaster-NM		
Synchronization	Asynchronous			
Transmission Speed(bps)	Selectable 1200 / 2400 / 4800 / 9600 / 19200 / 38400 / 57600 / 115200 bps			

Station Number Setting	Up to 32 stations, from 0 to 31 with SoftMaster-NM			
Transmission Distance	Max.15meters (49.21 feet), extended using modem		Max.500meters (1640.42 feet)	
Modem Communication	Not available	Available	Not available	Not available
Network Configuration	1:1		1:N	
Diagnosis Function	Available through LED and SoftMaster-NM diagnosis service			
Max. Number of Installation	Built-in	2	Built-in	2

## Software

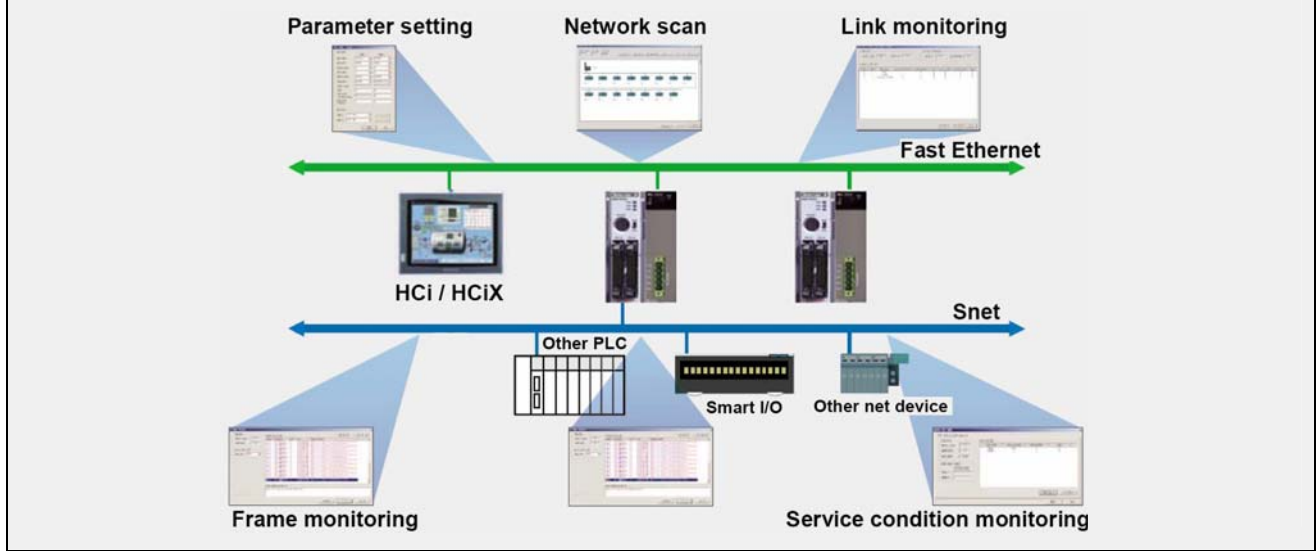
**Programming Software SoftMaster**

- Programming editing & engineering software
- Windows based easy operation
- Multi-PLC, Multi-programming supports
- Various monitoring and diagnosis functions
- Windows 2000, XP (Limited use in Windows 98, ME version)



**Network setting**

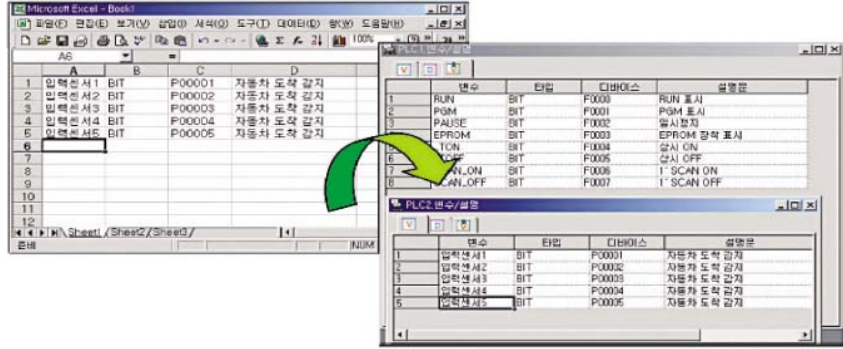
- Convenient network setting
- Extended monitoring function for network system and communication modules
- Fast interface with CPU by effective network management
- Various built-in diagnosis functions  
(CPU condition, Link condition, Service condition, Auto scan, LOG, Frame monitoring)





## Programming Environment

- Cell type input window
- Cell-unit editing
- Auto filling
- Compatibility with Microsoft EXCEL
- Redo & Undo
- Screen split editing
- Drag & Drop – Supports Drag & Drop for project, Variable / Statement, Ladder editing, Variable monitoring
- User defined shortcut key – Enhances user convenience with user-defined shortcut key
- Remote connection with RS-485 communication & Ethernet
- Remote connection with Max. 32 main units using built-in RS485 Communication



Remote connection using RS-485 Communication



Remote connection using Ethernet

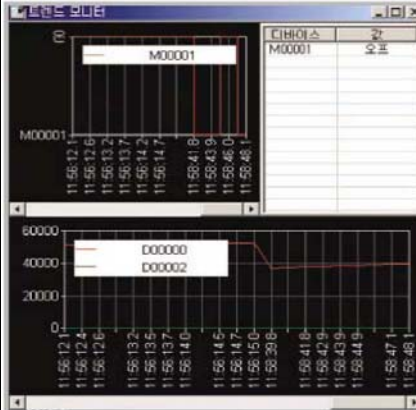
## Monitoring

### User Defined Events



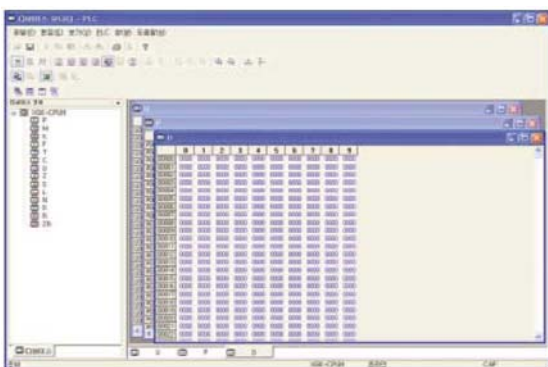
By registering user-defined events, users can read the record of specified event and user it for PLC operation and debugging.

### Trend Monitoring

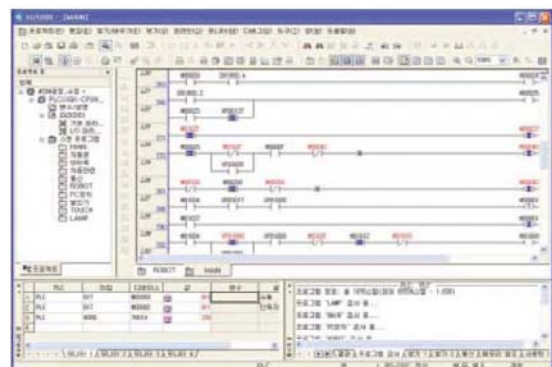


The progressive / changing value can be monitored and saved as a file.

### Device Monitoring



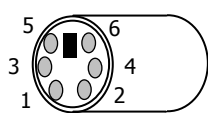
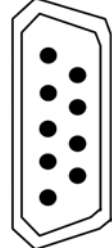
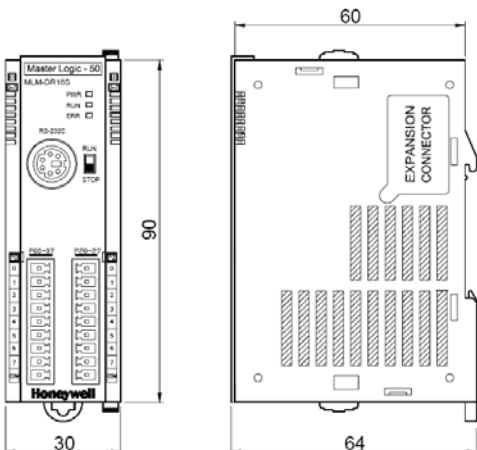
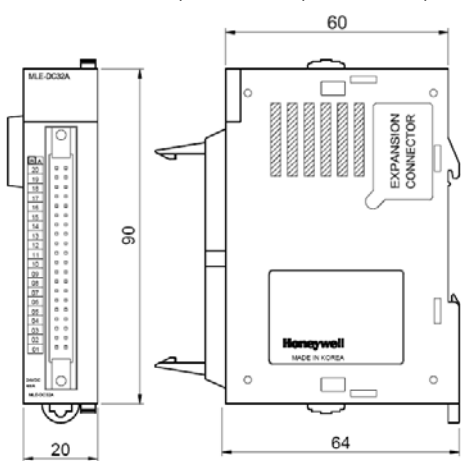
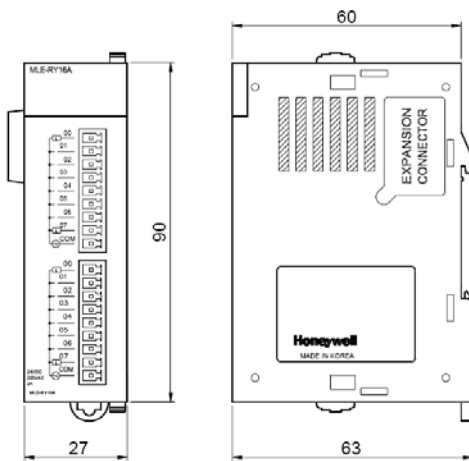
### Variable Monitoring



System Requirement	
O/S	Windows 2000, XP (Limited use in Windows 98, ME)
CPU	IBM Compatible PC with Min. 200 MHz Pentium Processor
Memory	Min. 128 Mbytes RAM
HDD	100 MB(Free Memory space)
Serial Port	Communication port for program transmission (RS-232C)
Printer	Compatible with Windows 98 or later
Mouse	Compatible with Windows 98 or later

Product List / Dimension			
Product List			
Item	Model	Specification	Remark
Base Module	MLM-DR16S	DC24V power supply, DC24V input 8 points, Relay output 8 points	
	MLM-DN16S	DC24V power supply, DC24V input 8 points, open collector output 8 points, built-in positioning function	
	MLM-DN32S	DC24V power supply, DC24V input 16 points, open collector output 16 points, built-in positioning function	
Expansion I/O Module	MLE-DC08A	DC24V input 8 points	
	MLE-DC16A	DC24V input 16 points	
	MLE-DC32A	DC24V input 32 points	
	MLE-RY08A	Relay output 8 points	
	MLE-RY16A	Relay output 16 points	
	MLE-TN08A	Open collector output 8 points(NPN output)	
	MLE-TN16A	Open collector output 16 points(NPN output)	
	MLE-TN32A	Open collector output 32 points(NPN output)	
	MLE-DR16A	DC24V input 8 points, Relay output 8 points	
Expansion Special Module	MLF-AD04A	Current / Voltage input 4 channel	
	MLF-DC04A	Current output 4 channel	
	MLF-DV04A	Voltage output 4 channel	
	MLF-RD04A	RTD input 4 channel	
	MLF-TC04A	Thermocouple input 4 channel	Jan '08
Expansion Comm. Module	MLL-CU21A	Snet (RS-232C, Modem)	Dec '07
	MLL-CU41A	Snet (RS422/485)	
	MLL-EMTA	Ethernet interface	Oct '07
Software	SoftMaster	Engineering software	
Loader Cable	PMC-310S	Connection Cable (PC to PLC), 9 pin (PC) – 6 pin (PLC), soft tube type cable.	Soft tube type

\* 64-point I/O and Open Collector (PNP) output modules are under development.(MLE-DC64A, TN64A, TP8A, TP16A, TP32A, TP64A)

<p><b>Loader Cable Connection</b></p>	<div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>ML50(6Pin, Male)</p>  </div> <div style="text-align: center;"> <p>PC(9Pin, Female)</p>  </div> </div>
<p><b>Dimension</b></p>	<p>Model : MLM-DN16/32S, MLM-DR16S</p> 
	<p>Model : MLE-DCXXA, MLE-TNXXA, MLF-AD04A, MLF-DX04A</p> 
	<p>Model : MLE-RY16A</p> 

## Model Interpretation

### MasterLogic 50 Logic Controller Assemblies

SPECIFICATIONS	MODEL NUMBER	AVAILABILITY
<b>BASE MODULE (CPU + PWR SUPPLY + BASE I/O)</b>		
DC24V PWR Supply, DC24V Input (8 ch) & Relay Output (8 ch) (Note 1)	MLM-DR16S	•
DC24V PWR Supply, DC24V Input (8 ch) & Open Collector Output (8 ch) (Note 1)	MLM-DN16S	•
DC24V PWR Supply, DC24V Input (16 ch) & Open Collector Output (16 ch) (Note 1)	MLM-DN32S	•
<b>DIGITAL INPUT EXPANSION</b>		
DC24V Input (8 ch)	MLE-DC08A	•
DC24V Input (16 ch)	MLE-DC16A	•
DC24V Input (32 ch)	MLE-DC32A	•
<b>DIGITAL OUTPUT EXPANSION</b>		
Relay Output (8 ch)	MLE-RY08A	•
Relay Output (16 ch)	MLE-RY16A	•
Open Collector Output (8 ch)	MLE-TN08A	•
Open Collector Output (16 ch)	MLE-TN16A	•
Open Collector Output (32 ch)	MLE-TN32A	•
<b>DIGITAL INPUT / OUTPUT EXPANSION</b>		
DC24V Input (8 ch) & Relay Output (8 ch)	MLE-DR16A	•
<b>ANALOG INPUT EXPANSION</b>		
Current/Voltage Input (4 ch)	MLF-AD04A	•
RTD Input (4 ch)	MLF-RD04A	•
TC Input (4 ch)	MLF-TC04A	
<b>ANALOG OUTPUT EXPANSION</b>		
Current Output (4 ch)	MLF-DC04A	•
Voltage Output (4 ch)	MLF-DV04A	•
<b>COMMUNICATION EXPANSION</b>		
RS-232C/Modem (MLDP)	MLL-CU21A	
RS-422/485 (MODBUS RTU/ASC II, MLDP)	MLL-CU41A	•
Ethernet (TCP/IP, UDP/IP)	MLL-EMTA	•
<b>MANUAL &amp; ACCESSORY</b>		
ML50 Product Manuals (Full Document Set - Hard Copy, English) (Note 2)	MLM-00422	•
Loader Cable	PMC-310S	•
Smart Link Terminal Board 40 pins	SLP-T40P	•
Smart Link Cable Ass'y 20x2-40P, 0.5 Meter (Note 3)	SLT-CT051-XBM	•
Smart Link Cable Ass'y 20x2-40P, 1.0 Meter (Note 3)	SLT-CT101-XBM	
Smart Link Cable Ass'y 40-40P, 1.5 Meter (Note 4)	SLT-CT151-XBE	•
Smart Link Cable Ass'y 40-40P, 3.0 Meter (Note 4)	SLT-CT301-XBE	•

**Note 1:** Documentation is not provided with this model. If required, order the item separately.

**Note 2:** The manual set contains all ML50 product manuals. Documentation is available only in English language.

**Note 3:** The cable is used for the remote wiring of the Base Module MLM-DN32S only.

**Note 4:** The cable is used for the remote wiring of the DI/O Expansion Module MLE-TN32A / MLE-DC32A only.

## Warranty / Remedy

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Contact your local sales office for warranty information. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace without charge those items it finds defective. The foregoing is Buyer's sole remedy and is **in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose**. Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use. While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.

*Specifications are subject to change without notice.*

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