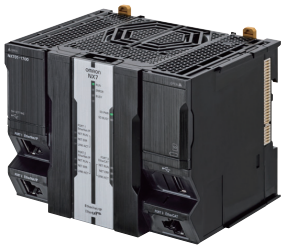
Machine Automation Controller

NJ/NX-Series

CSM_NJ_NX-series_DS_E_4_4

New controller that covers functions and high-speed processing required for machine control and safety, reliability and maintainability



NX701-□□□□

NJ501-□□□□

Features

- Integration of Logic and Motion in one CPU.
- Conforms to IEC 61131-3 (JIS B 3503) standard programming and PLCopen function blocks for Motion Control. Programming with variables allows users to create complex programs efficiently.
- Fast and accurate control by synchronizing all EtherCAT devices, such as vision sensors, servo drives, and field devices, with the PLC and Motion Engines.
- Offers speed without compromising on reliability and robustness expected from PLCs.
- Complete RAS functions: Transmission frame error check, timeout, bus diagnosis, Watchdog (WDT), memory check, and topology check, etc.
- Ideal for large-scale, fast, and highly-accurate control with up to 256 axes. (NX701-□□□□)
- Ideal for large-scale, fast, and high-accurate control with up to 64 axes. (NJ501-□□□□)
- Ideal for small-scale control with up to 8 axes. (NJ301-□□□□)
- Ideal for simple machines. (NJ101-□□□□)
- Linear and circular interpolation.
- Electronic gear and cam synchronization.
- The Controller can be directly connected to a database. No special Unit, software, nor middleware is required. (NX701-1□20/NJ501-□□20/NJ101-□020)
- The NJ501 SECS/GEM CPU Unit has built-in the SECS/GEM communications functions which are the standards in the semiconductor industry. (NJ501-1340)
- Control function of parallel link robots, cartesian robots and serial link robots. (NJ501-4□□0)
- Realize high-accuracy synchronization motion control (MC) and numerical control (NC) functions by ONE controller. G-Code available. (NJ501-5300)

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This product includes software developed by the OpenSSL Project for use in the OpenSSL Toolkit. (http://www.openssl.org/)
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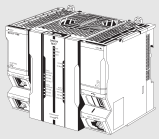
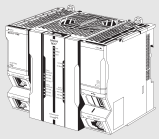
Ordering Information

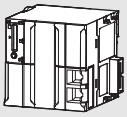
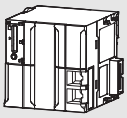
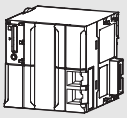
International Standards

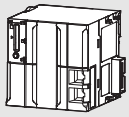
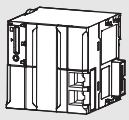
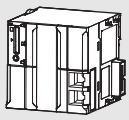
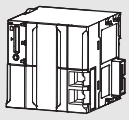
- The standards are abbreviated as follows: U: UL, U1: UL(Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus(Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, CE: EU Directives, RCM: Regulatory Compliance Mark and KC: KC Registration.
- Contact your OMRON representative for further details and applicable conditions for these standards.

NX701 CPU Units

Product Name	Specifications			Current (Power) consumption	Model	Standards
	Program capacity	Memory capacity for variables	Number of motion axes			
NX701 CPU Units 	80 MB	4 MB: Retained during power interruption 256 MB: Not retained during power interruption	256	40 W (including SD Memory Card and End Cover)	**NX701-1700**	UC1, N, L, CE, RCM, KC
			128		**NX701-1600**	
NX701 Database Connection CPU Units 		4 MB: Retained during power interruption 256 MB: Not retained during power interruption (including Memory for CJ-series Units)	256		**NX701-1720**	UC1, CE, RCM, KC
			128		**NX701-1620**	

NJ-series CPU Units

Product name	Specifications				Current consumption (A)		Model	Standards
	I/O capacity / maximum number of configuration Units (Expansion Racks)	Program capacity	Memory capacity for variables	Number of motion axes	5 VDC	24 VDC		
NJ501 CPU Units OPC UA Support 	2,560 points / 40 Units (3 Expansion Racks)	20 MB	2 MB: Retained during power interruption 4 MB: Not retained during power interruption	64	1.90	---	**NJ501-1500**	UC1, N, L, CE, RCM, KC
				32			**NJ501-1400**	
				16			**NJ501-1300**	
NJ301 CPU Units 		5 MB	0.5 MB: Retained during power interruption 2 MB: Not retained during power interruption	8			**NJ301-1200**	
				4			**NJ301-1100**	
NJ101 CPU Units 		3 MB		2			**NJ101-1000**	
				0			**NJ101-9000**	

Product name	Specifications								Current consumption (A)		Model	Standards
	I/O capacity / maximum number of configuration Units (Expansion Racks)	Program capacity	Memory capacity for variables	Number of motion axes	Database Connection function	SECS/GEM Communication function	Number of controlled robots	Numerical Control Functions	5 VDC	24 VDC		
NJ-series Database Connection CPU Units 	2,560 points / 40 Units (3 Expansion Racks)	20 MB	2 MB: Retained during power interruption 4 MB: Not retained during power interruption	64	Yes	No	---	No	1.90	---	**NJ501-1520**	UC1, N, L, CE, RCM, KC
				32							**NJ501-1420**	
				16							**NJ501-1320**	
		3 MB	0.5 MB: Retained during power interruption 2 MB: Not retained during power interruption	2							**NJ101-1020**	
				0							**NJ101-9020**	
NJ-series SECS/GEM CPU Unit 	2,560 points / 40 Units (3 Expansion Racks)	20 MB	2 MB: Retained during power interruption 4 MB: Not retained during power interruption	16	No	Yes	---	No	1.90	---	**NJ501-1340**	UC1, N, L, CE, RCM, KC
NJ-series NJ Robotics CPU Units 				64		No	8 max. *1				**NJ501-4500**	
				32							**NJ501-4400**	
				16	No		1				**NJ501-4300**	
											NJ501-4310	
					Yes		8 max. *1				**NJ501-4320**	
NJ-series NC Integrated Controller 				16 *2	No	No	---	Yes *3			**NJ501-5300**	UC1, CE, RCM, KC

*1. The number of controlled robots varies according to the number of axes used for the system.
*2. The number of controlled axes of the MC Control Function Module is included.
*3. One CNC Operator License (SYSMAC-RTNC0001L) is attached with the CPU Unit.

NX1P2 CPU Units

The compact entry model NX1P2 CPU Unit is also available.
Refer to NX1P Catalog (Cat. No.P115).

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model	Standards
Sysmac Studio Standard Edition Ver.1.□□	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI. Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/ Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version) The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer). For details, refer to your OMRON website.	– (Media only)	DVD	**SYSMAC-SE200D**	–
		1 license *1	–	**SYSMAC-SE201L**	–
Sysmac Studio Team Development Option *2	Sysmac Studio Team Development Option is a licence to enable the project version control function.	1 license *1	–	**SYSMAC-TA401L**	–

*1. Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).
*2. This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it.
This option can be used by applying the Team Development Option to Sysmac Studio version 1.20 or higher.
Project version control function is supported by CPU Unit version 1.16 or later.

Collection of software functional components Sysmac Library

Please download it from following URL and install to Sysmac Studio.
http://www.ia.omron.com/sysmac_library/

Typical Models

Product	Features	Model
Vibration Suppression Library	The Vibration Suppression Library is used to suppress residual vibration caused by the operation of machines.	**SYSMAC-XR006**
Device Operation Monitor Library	The Device Operation Monitor Library is used to monitor the operation of devices such as air cylinders, sensors, motors, and other devices.	**SYSMAC-XR008**
Dimension Measurement Library	The Dimension Measurement Library is used to dimension measurement with ZW-7000/5000 Confocal Fiber Displacement Sensor, or E9NC-TA0 Contact-Type Smart Sensor.	**SYSMAC-XR014**

SECS/GEM Configurator (For NJ-series SECS/GEM CPU Unit NJ501-1340)

Please purchase the required number of SECS/GEM Configurator licenses and a Sysmac Studio Standard Edition DVD the first time you purchase the SECS/GEM Configurator.
The Sysmac Studio Standard Edition DVD includes the SECS/GEM Configurator. The license does not include the DVD.

Product Name	Specifications			Model	Standards
		Number of licenses	Media		
SECS/GEM Configurator Ver.1.□□	The SECS/GEM Configurator is the software to make HSMS, SECSII and GEM settings for NJ501 SECS/GEM CPU Units. The SECS/GEM Configurator runs on the following OS. Windows XP (Service Pack3 or higher, 32-bit edition), Windows Vista (32-bit edition), or Windows 7 (32-bit or 64-bit edition) The software is included in the Sysmac Studio Standard Edition DVD.	1 license	---	**WS02-GCTL1**	---

Operation Software CNC Operator (For NJ-series NC Integrated Controller NJ501-5300)

Please purchase a DVD or download it from following URL.
http://www.ia.omron.com/cnc-operator/
One CNC Operator License (SYSMAC-RTNC0001L) is attached with the CPU Unit.

Product Name	Specifications			Model	Standards
		Number of licenses	Media		
CNC Operator	The CNC Operator is the software that provides a operation interface for NC programming, debugging and maintenance of CNC machine. CNC Operator runs on the following OS. Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version)	--- (Installer only)	--- (Download)	**SYSMAC-RTNC0000**	---
		--- (Media only)	DVD	**SYSMAC-RTNC0000D**	---
CNC Operator License	The one license key (hardware key, USB dongle). The CNC Operator needs license key.	1 license	---	**SYSMAC-RTNC0001L**	---
CNC Operator Software Development Kit	The CNC Operator Software Development Kit provides a environment for customization of CNC Operator. Supported execution environment: NET Framework (4.6.1) Development environment: Visual Studio 2013/2015 Development languages: C#	---	DVD	**SYSMAC-RTNC0101D**	---

Recommended EtherCAT and EtherNet/IP Communications Cables

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (aluminum tape and braiding) for EtherCAT.
For EtherNet/IP, required specification for the communications cables varies depending on the baud rate.
For 100BASE-TX/10BASE-T, use a straight or cross STP (shielded twisted-pair) cable of category 5 or higher.
For 1000BASE-T, use a straight or cross STP cable of category 5e or higher with double shielding (aluminum tape and braiding).

Cable with Connectors

Item		Recommended manufacturer	Cable length (m)	Model
Wire Gauge and Number of Pairs: AWG26, 4-pair Cable Cable Sheath material: LSZH *2	Cable with Connectors on Both Ends (RJ45/RJ45) Standard RJ45 plug type *1 Cable color: Yellow *3 	OMRON	0.3	XS6W-6LSZH8SS30CM-Y
			0.5	XS6W-6LSZH8SS50CM-Y
			1	XS6W-6LSZH8SS100CM-Y
			2	XS6W-6LSZH8SS200CM-Y
			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	Cable with Connectors on Both Ends (RJ45/RJ45) Rugged RJ45 plug type *1 Cable color: Light blue 	OMRON	0.3	XS5W-T421-AMD-K
			0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
	Cable with Connectors on Both Ends (M12 Straight/M12 Straight) Shield Strengthening Connector cable *4 M12/Smartclick Connectors Cable color: Black 	OMRON	0.5	XS5W-T421-BM2-SS
			1	XS5W-T421-CM2-SS
			2	XS5W-T421-DM2-SS
			3	XS5W-T421-EM2-SS
			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
	Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *4 M12/Smartclick Connectors Rugged RJ45 plug type Cable color: Black 	OMRON	0.5	XS5W-T421-BMC-SS
			1	XS5W-T421-CMC-SS
			2	XS5W-T421-DMC-SS
			3	XS5W-T421-EMC-SS
			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

*1. Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the *Industrial Ethernet Connectors Catalog* (Cat. No. G019).
*2. The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.
*3. Cable colors are available in yellow, green, and blue.
*4. For details, contact your OMRON representative.

Cables / Connectors

Item			Recommended manufacturer	Model
Products for EtherCAT or EtherNet/IP (1000BASE-T*2/100BASE-TX)	Wire Gauge and Number of Pairs: AWG24, 4-pair Cable	Cables	Hitachi Cable, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *1
			Kuramo Electric Co.	KETH-SB *1
			SWCC Showa Cable Systems Co.	FAE-5004 *1
		RJ45 Connectors	Panduit Corporation	MPS588-C *1
Products for EtherCAT or EtherNet/IP (100BASE-TX/10BASE-T)	Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	Cables	Kuramo Electric Co.	KETH-PSB-OMR *3
			JMACS Japan Co., Ltd.	PNET/B *3
		RJ45 Assembly Connector 	OMRON	XS6G-T421-1 *3

*1. We recommend you to use the above Cable and RJ45 Connector together.
*2. The products can be used only with the NX701.
*3. We recommend you to use the above Cable and RJ45 Assembly Connector together.

Memory Card

Item	Specification	Model
Memory Card	SD Memory Card, 2 GB	HMC-SD291*
	SDHC Memory Card, 4 GB	HMC-SD491

* HMC-SD291 cannot be used for the NJ501-□□□□ hardware revision A/unit version 1.15 or later.

Accessories

The following accessories come with the CPU Unit.

Item	CPU Unit		
	NX701-1□00	NX701-1□20	NJ-series
Battery	CJ1W-BAT01		
End Cover	NX-END01 (must be attached to the right end of the CPU Rack)		CJ1W-TER01 (must be attached to the right end of the CPU Rack)
End Plate	---		PFP-M (2 required)
Fan Unit	NX-FAN01		---
SD Memory Card (Flash Memory)	---	HMC-SD491	HMC-SD291*

* NJ501-□□20 or NJ101-□□20 or NJ501-1340 only.
HMC-SD491 is provided with NJ501-□□20 and NJ501-1340 hardware revision A/unit version 1.15 or later.

General Specifications

Item		NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Enclosure		Mounted in a panel			
Grounding Method		Ground to less than 100 Ω			
Dimensions (height×depth×width)		100 mm × 100 mm × 132 mm	90 mm × 90 mm × 90 mm		
Weight		880 g (including the End Cover)	550 g (including the End Cover)		
Current Consumption		---	5 VDC, 1.90 A (including SD Memory Card and End Cover)		
Power consumption		40 W (including SD Memory Card and End Cover)	---		
Operation Environment	Ambient Operating Temperature	0 to 55°C			
	Ambient Operating Humidity	10% to 95% (with no condensation)	10% to 90% (with no condensation)		
	Atmosphere	Must be free from corrosive gases.			
	Ambient Storage Temperature	-25 to 70°C (excluding battery and fan unit)	-20 to 75°C (excluding battery)		
	Altitude	2,000 m or less			
	Pollution Degree	2 or less: Conforms to JIS B3502 and IEC 61131-2.			
	Noise Immunity	2 kV on power supply line (Conforms to IEC 61000-4-4.)			
	Overvoltage Category	Category II: Conforms to JIS B3502 and IEC 61131-2.			
	EMC Immunity Level	Zone B			
	Vibration Resistance	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz Acceleration of 9.8 m/s^2 for 100 min in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)			
	Shock Resistance	Conforms to IEC 60068-2-27. 147 m/s^2, 3 times in X, Y, and Z directions (100 m/s^2 for Relay Output Units)			
Battery	Life	2.5 years (at 25°C, Power ON time rate 0% (power OFF))	5 years at 25°C		
	Model	CJ1W-BAT01			
Applicable Standards		Conforms to cULus, NK *1, LR *1, EU Directives, RCM and KC Registration.	Conforms to cULus, NK *2, LR *2, EU Directives, RCM and KC Registration *3.		

*1. Supported only by the CPU Units manufactured in December 2016 or later. Not supported by the NX701-1□20.
*2. Not supported by the NJ501-5300.
*3. Supported only by the CPU Units with unit version 1.01 or later.

Performance Specifications

Item				NX701-		NJ501-			NJ301-		NJ101	
				17□0	16□0	□5□0	□4□0	□3□0	1200	1100	1□□0	9□□0
Processing Time	Instruction Execution Times	LD instruction		0.37ns or more		1.1ns (1.7ns or less)			2.0ns (3.0ns or less)		3.3ns (5.0ns or less)	
		Math Instructions (for Long Real Data)		3.2ns ns or more		24ns or more *1			42 ns or more		70 ns or more	
Programming	Program capacity *2	Size		80 MB (1600 KS)		20 MB (400 KS)			5 MB (100 KS)		3 MB (60 KS)	
		Number	POU definition	6,000		3,000			750		450	
			POU instance	48,000		Using Sysmac Studio Ver. 1.05 or lower : 6,000 Using Sysmac Studio Ver. 1.06 or higher : 9,000			Using Sysmac Studio Ver. 1.04 or lower : 1,500 Using Sysmac Studio Ver. 1.05 or higher : 3,000		1,800	
	Variables capacity	No Retain Attribute *3	Size	256 MB		4 MB			2 MB			
			Number	360,000		90,000			22,500			
		Retain Attribute *4	Size	4 MB		2 MB			0.5 MB			
			Number	40,000		10,000			Using Sysmac Studio Ver. 1.04 or lower : 2,500 Using Sysmac Studio Ver. 1.05 or higher : 5,000		5,000	
	Data type	Number		8,000		2,000			1,000			
	Memory for CJ-Series Units (Can be Specified with AT Specifications for Variables.)	CIO Area		NX701-1□00: --- NX701-1□20: 6144 words (CIO 0 to CIO 6143) *5		6,144 words (CIO 0 to CIO 6143)						
		Work Area		NX701-1□00: --- NX701-1□20: 512 words (W0 to W511) *5		512 words (W0 to W511)						
		Holding Area		NX701-1□00: --- NX701-1□20: 1536 words (H0 to H1535) *6		1,536 words (H0 to H1535)						
		DM Area		NX701-1□00: --- NX701-1□20: 32768 words (D0 to D32767) *6		32,768 words (D0 to D32767)						
		EM Area		NX701-1□00: --- NX701-1□20: 32768 words × 25 banks (E0_00000 to E18_32767) *7		32,768 words × 25 banks (E0_00000 to E18_32767) *7			32,768 words × 4 banks (E0_00000 to E3_32767) *7			
Unit Configuration	Maximum Number of Connectable Units	Maximum number of CJ/NX unit per CPU Rack or Expansion Rack		---		10 Units						
		Maximum number of CJ unit on the system		---		40 Units						
		Maximum number of NX unit on the system		4,096 (on NX series EtherCAT slave terminal)							400 (on NX series EtherCAT slave terminal)	
	Maximum number of Expansion Racks			0		3 max.						
	I/O Capacity	Maximum number of I/O Points on CJ-series Units		---		2,560 points max.						
	Power Supply Unit for CPU Rack and Expansion Racks	Model		NX-PA9001 NX-PD7001		NJ-P□3001						
		Power OFF Detection Time	AC Power Supply	30 to 45 ms		30 to 45 ms						
			DC Power Supply	5 to 20ms		22 to 25 ms						

*1. When the hardware revision for the Unit is A.
*2. This is the capacity for the execution objects and variable tables (including variable names).
*3. Words for CJ-series Units in the Holding, DM, and EM Areas are not included. For NX701-1□20, Words for CJ-series Units are included.
*4. Words for CJ-series Units in the CIO and Work Areas are not included. For NX701-1□20, Words for CJ-series Units are included.
*5. You can set the size in 1ch unit. Use Non-Retain attribute memory.
*6. You can set the size in 1ch unit. Use Retain attribute memory.
*7. When the Spool function of the NJ501-1□20 is enabled, the DB Connection Service uses E9_0 to E18_32767 (NJ501-1□20).
When the Spool function of the NJ101-□□20 is enabled, the DB Connection Service uses E1_0 to E3_32767 (NJ101-□□20).
NX701-1□20 use the dedicated area for the spool function. Even if the spool function is valid, Retain attribute memory is not used.

Item				NX701-		NJ501-			NJ301-		NJ101	
				17□0	16□0	□5□0	□4□0	□3□0	1200	1100	1□□0	9□□0
Motion Control	Number of Controlled Axes	Maximum Number of Controlled Axes		Maximum number of axes which can be defined. The number of controlled axes = The number of motion control axes + The number of single-axis position control axes								
				256 axes	128 axes	64 axes	32 axes	16 axes	15 axes *8	15 axes *8	6 axes	
			Motion control axes	Maximum number of motion control axes which can be defined. All motion control function is available.								
				256 axes	128 axes	64 axes	32 axes	16 axes	15 axes	15 axes	6 axes	
		Maximum number of used real axes		Maximum number of used real axes. The Number of used real axes includes following servo axes and encoder axes.								
				256 axes	128 axes	64 axes	32 axes	16 axes	8 axes	4 axes	2 axes	
			Used motion control servo axes	Maximum number of servo axes which all motion control function is available. The number of used motion control servo axes = The number of motion control axes whose axis type is set to servo axis and axis use is set to used axis.								
				256 axes	128 axes	64 axes	32 axes	16 axes	8 axes	4 axes	2 axes	
		Maximum number of axes for linear interpolation axis control		4 axes per axes group								
		Number of axes for circular interpolation axis control		2 axes per axes group								
	Maximum Number of Axes Groups			64 groups		32 groups						
	Motion Control Period			The same control period as that is used for the process data communications cycle for EtherCAT.								
	Cams	Number of Cam Data Points	Maximum Points per Cam Table	65,535 points								
			Maximum Points for All Cam Tables	1,048,560 points		1,048,560 points			262,140 points			
		Maximum Number of Cam Tables		640 tables		640 tables			160 tables			
	Position Units			Pulses, millimeters, micrometers, nanometers, degrees or inches								
	Override Factors			0.00% or 0.01% to 500.00%								
Peripheral USB Port	Supported Services			Sysmac Studio connection								
	Physical Layer			USB 2.0-compliant B-type connector								
	Transmission Distance between Hub and Node			5 m max.								
Built-in EtherNet/IP Port	Number of port			2		1						
	Physical Layer			10BASE-T/ 100BASE-TX / 1000BASE-T		10Base-T or 100Base-TX						
	Frame length			1514 max.								
	Media Access Method			CSMA/CD								
	Modulation			Baseband								
	Topology			Star								
	Baud Rate			1Gbps (1000BASE-T)		100 Mbps (100Base-TX)						
	Transmission Media			STP (shielded, twisted-pair) cable of Ethernet category 5, 5e or higher								
	Maximum Transmission Distance between Ethernet Switch and Node			100m								
	Maximum Number of Cascade Connections			There are no restrictions if Ethernet switch is used.								

*8 This number of axes is achieved in a combination of a CPU Unit with unit version 1.06 or later and Sysmac Studio version 1.07 or higher. In other combinations, the maximum number of controlled axes is 8 axes (NJ301-1200) or 4 axes (NJ301-1100).

Item				NX701-		NJ501-			NJ301-		NJ101	
				17□0	16□0	□5□0	□4□0	□3□0	1200	1100	1□□0	9□□0
Built-in EtherNet/IP Port	CIP service: Tag Data Links (Cyclic Communications)	Maximum Number of Connections		256 / port total 512		32						
		Packet interval *9		0.5 to 10,000 ms in 0.5-ms increments Can be set for each connection.		1 to 10,000 ms in 1.0-ms increments *10 Can be set for each connection. (Data will be refreshed at the set interval, regardless of the number of nodes.)						
		Permissible Communications Band		40,000 pps *11 including heartbeat		3,000 pps *11 *12 (including heartbeat)						
		Maximum Number of Tag Sets		256 / port total 512		32						
		Tag types		Network variables		Network variables, CIO, Work, Holding, DM, and EM Areas						
		Number of tags per connection (i.e., per tag set)		8 (7 tags if Controller status is included in the tag set.)								
		Maximum Link Data Size per Node (total size for all tags)		256 / port total 512		256						
		Maximum number of tag		369,664 byte (Total in 2 ports 739,328 byte)		19,200 bytes						
		Maximum Data Size per Connection		1,444 byte		600 bytes						
		Maximum Number of Registrable Tag Sets		256 / port total 512 (1 connection = 1 tag set)		32 (1 connection = 1 tag set)						
		Maximum Tag Set Size		1,444 bytes (Two bytes are used if Controller status is included in the tag set.)		600 bytes (Two bytes are used if Controller status is included in the tag set.)						
		Multi-cast Packet Filter *13		Supported.								
	Cip Message Service: Explicit Messages	Class 3 (number of connections)		128 / port total 256 (clients plus server)		32 (clients plus server)						
		UCMM (non-connection type)	Maximum Number of Clients that Can Communicate at One Time	32 / port total 64		32						
			Maximum Number of Servers that Can Communicate at One Time	32 / port total 64		32						
	Maximum number of TCP socket service			30		30 *14					30	
	OPC UA Server (Only NJ501-1□00)	Support Profile/Model		---		UA 1.02 Micro Embedded UA Server Profile PLCopen Information Model			---		---	
		Default Endpoint/Port		---		opc.tcp://192.168.250.1:4840/			---		---	
		Maximum number of sessions (Client)		---		5			---		---	
		Maximum number of Monitored Items per server		---		2,000			---		---	
		Sampling rate of the Monitored Items (ms)		---		0, 50, 100, 250, 500, 1000,2000, 5000, 10000 if set to 0 (zero), it is assumed that is set to 50.			---		---	
		Maximum number of Subscriptions per server		---		100			---		---	
		Maximum number of variables to open as OPC UA objects		---		10,000			---		---	
		Maximum number of Value attribute of variables to open as OPC UA objects		---		10,000			---		---	

*9. Data is updated on the line in the specified interval regardless of the number of nodes.
*10. The Packet interval of the CPU Unit version 1.02 or earlier is 10 to 10,000 ms in 1.0-ms increments.
*11. Means packets per second, i.e., the number of communications packets that can be sent or received in one second.
*12. The Permissible Communications Band of the CPU Unit version 1.02 or earlier is 1,000 pps.
*13. An IGMP client is mounted for the EtherNet/IP port. If an ethernet switch that supports IGMP snooping is used, filtering of unnecessary multicast packets is performed.
*14. The Maximum number of TCP socket service of the CPU Unit version 1.02 or earlier is 16.

Item				NX701-		NJ501-			NJ301-		NJ101	
				17□0	16□0	□5□0	□4□0	□3□0	1200	1100	1□□0	9□□0
Built-in EtherNet/IP Port	OPC UA Server (Only NJ501-1□00)	Structure's definitions able to open		---		100			---		---	
		Variables unable to open		---		• Variable which size are over 1024Bytes • Double and over dimensional array of structures • Structures includes double and over dimensional array • Structures nested 4 and over Unions • Array which's index number don't start from 0 • Array which's element is over 1024 • Structures which's members are over 100.			---		---	
		SecurityPolicy/Mode		---		None • Sign - Basic128Rsa15 • Sign - Basic256 • Sign - Basic256Sha256 • SignAndEncrypt - Basic128Rsa15 • SignAndEncrypt - Basic256 • SignAndEncrypt - Basic256Sha256			---		---	
		Application Authentication	Authentication	---		X.509			---		---	
			Maximum number of certification	---		Trusted certification: 32 Issuer certification: 32 Rejected certification: 32			---		---	
		User Authentication	Authentication	---		User name / Password Anonymous			---		---	
Built-in EtherCAT Port	Communications Standard			IEC 61158 Type12								
	EtherCAT Master Specifications			Class B (Feature Pack Motion Control compliant)								
	Physical Layer			100BASE-TX								
	Modulation			Baseband								
	Baud Rate			100 Mbps (100Base-TX)								
	Duplex mode			Auto								
	Topology			Line, daisy chain, and branching								
	Transmission Media			Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)								
	Maximum Transmission Distance between Nodes			100m								
	Maximum Number of Slaves			512		192					64	
	Range of node address			1-512		1-192						
	Maximum Process Data Size			Inputs: 11,472 bytes Outputs: 11,472 bytes (However, the maximum number of process data frames is 8.)		Inputs: 5,736 bytes Outputs: 5,736 bytes (However, the maximum number of process data frames is 4.)						
	Maximum Process Data Size per Slave			Inputs: 1,434 bytes Outputs: 1,434 bytes								
	Communications Cycle			• Primary periodic task: 125 μs, 250 μs to 8 ms (in 250-μs increments) • Priority-5 periodic task: 125 μs, 250 μs to 100 ms (in 250-μs increments)		500/1,000/2,000/4,000 μs *15					1,000/2,000/4,000 μs	
	Sync Jitter			1 μs max.								
Internal Clock				At ambient temperature of 55°C: -3.5 to +0.5 min error per month At ambient temperature of 25°C: -1.5 to +1.5 min error per month At ambient temperature of 0°C: -3 to +1 min error per month								

*15. The Maximum Communications Cycle of the NJ301 CPU Unit version 1.02 or earlier is 1,000/2,000/4,000 μs.
The EtherCAT communications cycle of NJ501-4□□0 for robot control is 1 ms or more.

Note: For robot control by NJ501-4□□0, use the G5 series/1S series AC Servo Drive with built-in EtherCAT communications, absolute encoder, and brake.

Performance Specifications Supported by the NJ-series NC Integrated Controller

Item				NJ501-
				5300
Numerical Control	Task Period	Primary periodic cycle		500/1,000/2,000/4,000 μs
		CNC Planner Service period		500 μs to 16 ms
	Number of CNC motors	Maximum number of CNC motors *1		16
	CNC Coordinate system	Maximum number of CNC coordinate systems		4
		Maximum number of CNC motor configurations that are included in a CNC coordinate system (excluding spindle axes)		8
		Number of spindle axes that are included in a CNC coordinate system		1
	Number of simultaneous interpolation axes			4
	NC Program	Program buffer size *2		16 MB
		Maximum number of programs	Upper limit of main registrations	512
			Upper limit of sub registratioins	512
	NC program variables	P variable		Double-precision floating point 65536 *3
		Q variable		Double-precision floating point 8192 *3
		L variable		Double-precision floating point 256
	CNC motor compensation table	Maximum number of CNC motor compensation tables		32
		Maximum size of all compensation tables		1 MB

*1. The number of controlled axes of the MC Control Function Module is included.
*2. The number of programs and their capacities that can be loaded into the CPU Unit at the same time.
The program capacity is the maximum size available. As fragmentation will occur, the size that is actually available will be smaller than the maximum size.
*3. Some parts of the area are reserved by the system.

Function Specifications

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Tasks	Function			I/O refreshing and the user program are executed in units that are called tasks. Tasks are used to specify execution conditions and execution priority.			
		Periodically Executed Tasks	Maximum Number of Primary Periodic Tasks	1			
			Maximum Number of Periodic Tasks	4	3		
		Conditionally executed tasks *1	Maximum number of event tasks	32			
			Execution conditions	When Activate Event Task instruction is executed or when condition expression for variable is met.			
	Setup	System Service Monitoring Settings		---	The execution interval and the percentage of the total user program execution time are monitored for the system services (processes that are executed by the CPU Unit separate from task execution).		
Programming	POU (program organization units)	Programs		POUs that are assigned to tasks.			
		Function Blocks		POUs that are used to create objects with specific conditions.			
		Functions		POUs that are used to create an object that determine unique outputs for the inputs, such as for data processing.			
	Programming Languages	Types		Ladder diagrams *2 and structured text (ST)			
	Namespaces *3			A concept that is used to group identifiers for POU definitions.			
	Variables	External Access of Variables	Network Variables	The function which allows access from the HMI, host computers, or other Controllers			
	Data Types	Data Types	Boolean	BOOL			
			Bit Strings	BYTE, WORD, DWORD, LWORD			
			Integers	INT, SINT, DINT,LINT, UINT, USINT, UDINT, ULINT			
			Real Numbers	REAL, LREAL			
			Durations	TIME			
			Dates	DATE			
			Times of Day	TIME_OF_DAY			
			Date and Time	DATE_AND_TIME			
			Text Strings	STRING			
		Derivative Data Types		Structures, unions, enumerations			
		Structures	Function	A derivative data type that groups together data with different variable types.			
			Maximum Number of Members	2048			
			Nesting Maximum Levels	8			
			Member Data Types	Basic data types, structures, unions, enumerations, array variables			
			Specifying Member Offsets	You can use member offsets to place structure members at any memory locations.*3			
		Unions	Function	A derivative data type that groups together data with different variable types.			
			Maximum Number of Members	4			
			Member Data Types	BOOL, BYTE, WORD, DWORD, LWORD			
		Enumerations	Function	A derivative data type that uses text strings called enumerators to express variable values.			
	Data Type Attributes	Array Specifications	Function	An array is a group of elements with the same data type. You specify the number (subscript) of the element from the first element to specify the element.			
			Maximum Number of Dimensions	3			
			Maximum Number of Elements	65535			
			Array Specifications for FB Instances	Supported.			
		Range Specifications		You can specify a range for a data type in advance. The data type can take only values that are in the specified range.			
		Libraries		User libraries			

*1. Supported only by the CPU Units with unit version 1.03 or later.
*2. Inline ST is supported. (Inline ST is ST that is written as an element in a ladder diagram.)
*3. Supported only by the CPU Units with unit version 1.01 or later.

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Motion Control	Control Modes			position control, velocity control, torque control			
	Axis Types			Servo axes, virtual servo axes, encoder axes, and virtual encoder axes			
	Positions that can be managed			Command positions and actual positions			
	Single-axis	Single-axis Position Control	Absolute Positioning	Positioning is performed for a target position that is specified with an absolute value.			
			Relative Positioning	Positioning is performed for a specified travel distance from the command current position.			
			Interrupt Feeding	Positioning is performed for a specified travel distance from the position where an interrupt input was received from an external input.			
			Cyclic synchronous absolute positioning *1	The function which outputs command positions in every control period in the position control mode.			
		Single-axis Velocity Control	Velocity Control	Velocity control is performed in Position Control Mode.			
			Cyclic Synchronous Velocity Control	A velocity command is output each control period in Velocity Control Mode.			
		Single-axis Torque Control	Torque Control	The torque of the motor is controlled.			
		Single-axis Synchro-nized Con-trol	Starting Cam Operation	A cam motion is performed using the specified cam table.			
			Ending Cam Operation	The cam motion for the axis that is specified with the input parameter is ended.			
			Starting Gear Operation	A gear motion with the specified gear ratio is performed between a master axis and slave axis.			
			Positioning Gear Operation	A gear motion with the specified gear ratio and sync position is performed between a master axis and slave axis.			
			Ending Gear Operation	The specified gear motion or positioning gear motion is ended.			
			Synchronous Positioning	Positioning is performed in sync with a specified master axis.			
			Master Axis Phase Shift	The phase of a master axis in synchronized control is shifted.			
			Combining Axes	The command positions of two axes are added or subtracted and the result is output as the command position.			
		Single-axis Manual Operation	Powering the Servo	The Servo in the Servo Drive is turned ON to enable axis motion.			
			Jogging	An axis is jogged at a specified target velocity.			
		Auxiliary Functions for Single-axis Control	Resetting Axis Errors	Axes errors are cleared.			
			Homing	A motor is operated and the limit signals, home proximity signal, and home signal are used to define home.			
			Homing with parame-ter *1	Specifying the parameter, a motor is operated and the limit signals, home proximity signal, and home signal are used to define home.			
			High-speed Homing	Positioning is performed for an absolute target position of 0 to return to home.			
			Stopping	An axis is decelerated to a stop at the specified rate.			
			Immediately Stopping	An axis is stopped immediately.			
			Setting Override Fac-tors	The target velocity of an axis can be changed.			
			Changing the Current Position	The command current position or actual current position of an axis can be changed to any position.			
			Enabling External Latches	The position of an axis is recorded when a trigger occurs.			
			Disabling External Latches	The current latch is disabled.			
			Zone Monitoring	You can monitor the command position or actual position of an axis to see when it is within a specified range (zone).			
			Enabling digital cam switches *4	You can turn a digital output ON and OFF according to the position of an axis.			
			Monitoring Axis Following Error	You can monitor whether the difference between the command positions or actual positions of two specified axes exceeds a threshold value.			
			Resetting the Following Error	The error between the command current position and actual current position is set to 0.			
			Torque Limit	The torque control function of the Servo Drive can be enabled or disabled and the torque limits can be set to control the output torque.			
			Command position compensation *5	The function which compensate the position for the axis in operation.			
			Start velocity *6	You can set the initial velocity when axis motion starts.			

*1. Supported only by the CPU Units with unit version 1.03 or later.
*4. Supported only by the CPU Units with unit version 1.06 or later.
*5. Supported only by the CPU Units with unit version 1.10 or later.
*6. Supported only by the CPU Units with unit version 1.05 or later.

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Motion Control	Axes Groups	Multi-axes Coordinated Control	Absolute Linear Interpolation	Linear interpolation is performed to a specified absolute position.			
			Relative Linear Interpolation	Linear interpolation is performed to a specified relative position.			
			Circular 2D Interpolation	Circular interpolation is performed for two axes.			
			Axes Group Cyclic Synchronous Absolute Positioning	A positioning command is output each control period in Position Control Mode.*3			
		Auxiliary Functions for Multi-axes Coordinated Control	Resetting Axes Group Errors	Axes group errors and axis errors are cleared.			
			Enabling Axes Groups	Motion of an axes group is enabled.			
			Disabling Axes Groups	Motion of an axes group is disabled.			
			Stopping Axes Groups	All axes in interpolated motion are decelerated to a stop.			
			Immediately Stopping Axes Groups	All axes in interpolated motion are stopped immediately.			
			Setting Axes Group Override Factors	The blended target velocity is changed during interpolated motion.			
			Reading Axes Group Positions	The command current positions and actual current positions of an axes group can be read.*3			
			Changing the Axes in an Axes Group	The Composition Axes parameter in the axes group parameters can be overwritten temporarily.*3			
	Common Items	Cams	Setting Cam Table Properties	The end point index of the cam table that is specified in the input parameter is changed.			
			Saving Cam Tables	The cam table that is specified with the input parameter is saved in non-volatile memory in the CPU Unit.			
			Generating cam tables *7	The cam table that is specified with the input parameter is generated from the cam property and cam node.			
		Parameters	Writing MC Settings	Some of the axis parameters or axes group parameters are overwritten temporarily.			
			Changing axis parameters *7	You can access and change the axis parameters from the user program.			
	Auxiliary Functions	Count Modes		You can select either Linear Mode (finite length) or Rotary Mode (infinite length).			
		Unit Conversions		You can set the display unit for each axis according to the machine.			
		Acceleration/ Deceleration Control	Automatic Acceleration/ Deceleration Control	Jerk is set for the acceleration/deceleration curve for an axis motion or axes group motion.			
			Changing the Acceleration and Deceleration Rates	You can change the acceleration or deceleration rate even during acceleration or deceleration.			
		In-position Check		You can set an in-position range and in-position check time to confirm when positioning is completed.			
		Stop Method		You can set the stop method to the immediate stop input signal or limit input signal.			
		Re-execution of Motion Control Instructions		You can change the input variables for a motion control instruction during execution and execute the instruction again to change the target values during operation.			
		Multi-execution of Motion Control Instructions (Buffer Mode)		You can specify when to start execution and how to connect the velocities between operations when another motion control instruction is executed during operation.			
		Continuous Axes Group Motions (Transition Mode)		You can specify the Transition Mode for multi-execution of instructions for axes group operation.			
		Monitoring Functions	Software Limits	Software limits are set for each axis.			
			Following Error	The error between the command current value and the actual current value is monitored for an axis.			
			Velocity, Acceleration Rate, Deceleration Rate, Torque, Interpolation Velocity, Interpolation Acceleration Rate, And Interpolation Deceleration Rate	You can set and monitor warning values for each axis and each axes group.			
		Absolute Encoder Support		You can use an OMRON G5-Series or 1S-Series Servomotor with an Absolute Encoder to eliminate the need to perform homing at startup.			
		Input signal logic inversion *6		You can inverse the logic of immediate stop input signal, positive limit input signal, negative limit input signal, or home proximity input signal.			
	External Interface Signals			The Servo Drive input signals listed on the right are used. Home signal, home proximity signal, positive limit signal, negative limit signal, immediate stop signal, and interrupt input signal			

*3. Supported only by the CPU Units with unit version 1.01 or later.
*6. Supported only by the CPU Units with unit version 1.05 or later.
*7. Supported only by the CPU Units with unit version 1.08 or later.

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Unit (I/O) Management	EtherCAT Slaves	Maximum Number of Slaves		512	192		64
	CJ-Series Units	Maximum number of Units		---	40		
		Basic I/O Units	Load Short-circuit Protection and I/O Disconnection Detection	Alarm information for Basic I/O Units is read.			
Communications	Peripheral USB Port			A port for communications with various kinds of Support Software running on a personal computer.			
	Built-in EtherNet/IP port Internal Port	Communications protocol		TCP/IP, UDP/IP			
		CIP Communications Service	Tag Data Links	Programless cyclic data exchange is performed with the devices on the EtherNet/IP network.			
			Message Communications	CIP commands are sent to or received from the devices on the EtherNet/IP network.			
		TCP/IP functions	CIDR	The function which performs IP address allocations without using a class (class A to C) of IP address.			
			IP Forwarding *5	The function which forward IP packets between interfaces.	---		
		TCP/IP Applications	Socket Services	Data is sent to and received from any node on Ethernet using the UDP or TCP protocol. Socket communications instructions are used.			
			FTP client *7	File can be read from or written to computers at other Ethernet nodes from the CPU Unit. FTP client communications instructions are used.			
			FTP Server	Files can be read from or written to the SD Memory Card in the CPU Unit from computers at other Ethernet nodes.			
			Automatic Clock Adjustment	Clock information is read from the NTP server at the specified time or at a specified interval after the power supply to the CPU Unit is turned ON. The internal clock time in the CPU Unit is updated with the read time.			
			SNMP Agent	Built-in EtherNet/IP port internal status information is provided to network management software that uses an SNMP manager.			
		OPC UA (Only NJ501-1□00)	Server Function	---	Functions to respond to requests from clients on the OPC UA network	---	---
	EtherCAT Port	Supported Services	Process Data Communications	Control information is exchanged in cyclic communications between the EtherCAT master and slaves.			
			SDO Communications	A communications method to exchange control information in noncyclic event communications between EtherCAT master and slaves. This communications method is defined by CoE.			
		Network Scanning		Information is read from connected slave devices and the slave configuration is automatically generated.			
		DC (Distributed Clock)		Time is synchronized by sharing the EtherCAT system time among all EtherCAT devices (including the master).			
		Packet Monitoring *8		The frames that are sent by the master and the frames that are received by the master can be saved.The data that is saved can be viewed with WireShark or other applications.			
		Enable/disable Settings for Slaves		The slaves can be enabled or disabled as communications targets.			
		Disconnecting/Connecting Slaves		Temporarily disconnects a slave from the EtherCAT network for maintenance, such as for replacement of the slave, and then connects the slave again.			
		Supported Application Protocol	CoE	SDO messages of the CAN application can be sent to slaves via EtherCAT.			
	Communications Instructions			The following instructions are supported. CIP communications instructions, socket communications instructions, SDO message instructions, no-protocol communications instructions *9, FTP client instructions, and Modbus RTU protcol instructions *9	The following instructions are supported. CIP communications instructions, socket communications instructions, SDO message instructions, no-protocol communications instructions, protocol macro instructions, and FTP client instructions *7, and Modbus RTU protcol instructions *9		
Operation Management	RUN Output Contacts			The output on the Power Supply Unit turns ON in RUN mode.			
System Management	Event Logs	Function		Events are recorded in the logs.			
		Maximum number of events	System event log	2,048	1,024	512	
			Access event log	1,024		512	
			User-defined event log	1,024		512	

*5. Supported only by the CPU Units with unit version 1.10 or later.
*6. Supported only by the CPU Units with unit version 1.05 or later.
*7. Supported only by the CPU Units with unit version 1.08 or later.
*8. For NJ301, Supported only by the CPU Units with unit version 1.10 or later.
*9. Supported only by the CPU Units with unit version 1.11 or later.

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Debugging	Online Editing	Single		Programs, function blocks, functions, and global variables can be changed online. Different operators can change different POUs across a network.			
	Forced Refreshing			The user can force specific variables to TRUE or FALSE.			
		Maximum Number of Forced Variables	Device Variables for EtherCAT Slaves	64			
			Device Variables for CJ-series Units and Variables with AT Specifications	---	64		
	MC Test Run *10			Motor operation and wiring can be checked from the Sysmac Studio.			
	Synchronizing			The project file in the Sysmac Studio and the data in the CPU Unit can be made the same when online.			
	Differentiation monitoring *1			Rising/falling edge of contacts can be monitored.			
		Maximum number of contacts *1		8			
	Data Tracing	Types	Single Triggered Trace	When the trigger condition is met, the specified number of samples are taken and then tracing stops automatically.			
			Continuous Trace	Data tracing is executed continuously and the trace data is collected by the Sysmac Studio.			
		Maximum Number of Simultaneous Data Trace		4	4 *11	2	
		Maximum Number of Records		10,000			
		Sampling	Maximum Number of Sampled Variables	192 variables		48 variables	
		Timing of Sampling		Sampling is performed for the specified task period, at the specified time, or when a sampling instruction is executed.			
		Triggered Traces		Trigger conditions are set to record data before and after an event.			
			Trigger Conditions	When BOOL variable changes to TRUE or FALSE Comparison of non-BOOL variable with a constant Comparison Method: Equals (=), Greater than (>), Greater than or equals (≥), Less Than (<), Less than or equals (≤), Not equal (≠)			
			Delay	Trigger position setting: A slider is used to set the percentage of sampling before and after the trigger condition is met.			
	Simulation			The operation of the CPU Unit is emulated in the Sysmac Studio.			
Reliability Functions	Self-diagnosis	Controller Errors	Levels	Major fault, partial fault, minor fault, observation, and information			
		User-defined errors		User-defined errors are registered in advance and then records are created by executing instructions.			
			Levels	8 levels			
Security	Protecting Software Assets and Preventing Operating Mistakes	CPU Unit Names and Serial IDs		When going online to a CPU Unit from the Sysmac Studio, the CPU Unit name in the project is compared to the name of the CPU Unit being connected to.			
		Protection	User Program Transfer with No Restoration Information	You can prevent reading data in the CPU Unit from the Sysmac Studio.			
			CPU Unit Write Protection	You can prevent writing data to the CPU Unit from the Sysmac Studio or SD Memory Card.			
			Overall Project File Protection	You can use passwords to protect .smc files from unauthorized opening on the Sysmac Studio.			
			Data Protection	You can use passwords to protect POUs on the Sysmac Studio.*3			
		Verification of Operation Authority		Online operations can be restricted by operation rights to prevent damage to equipment or injuries that may be caused by operating mistakes.			
			Number of Groups	5	5 *12		5
		Verification of User Program Execution ID		The user program cannot be executed without entering a user program execution ID from the Sysmac Studio for the specific hardware (CPU Unit).			
SD Memory Card Functions	Storage Type			SD Memory Card, SDHC Memory Card			
	Application	Automatic transfer from SD Memory Card *1		The data in the autoload folder on an SD Memory Card is automatically loaded when the power supply to the Controller is turned ON.			
		Transfer program from SD Memory Card *9		The user program on an SD Memory Card is loaded when the user changes system-defined variable to TRUE.			
		SD Memory Card Operation Instructions		You can access SD Memory Cards from instructions in the user program.			
		File Operations from the Sysmac Studio		You can perform file operations for Controller files in the SD Memory Card and read/write standard document files on the computer.			
		SD Memory Card Life Expiration Detection		Notification of the expiration of the life of the SD Memory Card is provided in a systemdefined variable and event log.			

*1. Supported only by the CPU Units with unit version 1.03 or later.
*3. Supported only by the CPU Units with unit version 1.01 or later.
*9. Supported only by the CPU Units with unit version 1.11 or later.
*10.Cannot be used with the NJ101-9000.
*11.Maximum Number of Simultaneous Data Trace of the NJ501-1□20 CPU Unit with unit version 1.08 or later is 2.
*12.When the NJ501 CPU Units with unit version 1.00 is used, this value becomes two.

Item				NX701-□□□□	NJ501-□□□□	NJ301-□□□□	NJ101-□□□□
Backup functions *1	SD Memory Card backup functions	Operation	Using front switch	You can use front switch to backup, compare, or restore data.			
			Using system-defined variables	You can use system-defined variables to backup, compare, or restore data. *13			
			Memory Card Operations Dialog Box on Sysmac Studio	Backup and verification operations can be performed from the SD Memory Card Operations Dialog Box on the Sysmac Studio.			
			Using instruction *7	Backup operation can be performed by using instruction.			
		Protection	Prohibiting backing up data to the SD Memory Card	Prohibit SD Memory Card backup functions.			
	Sysmac Studio Controller backup functions			Backup, restore, and verification operations for Units can be performed from the Sysmac Studio.			

*1. Supported only by the CPU Units with unit version 1.03 or later.
*7. Supported only by the CPU Units with unit version 1.08 or later.
*13. Restore is supported with unit version 1.14 or later.

Function Specifications of the NJ/NX-series Database Connection CPU Units

Besides functions of the NX701-□□□□/NJ501-□□□□/NJ101-□□□□, functions supported by the NX701-1□20/NJ501-□□20/NJ101-□020 are as follows.

Item		Description		
		NX701-1□20	NJ501-1□20	NJ101-□020
Supported port		Built-in EtherNet/IP port		
Supported DB *1*2		Microsoft Corporation: SQL Server 2008/2008 R2/2012/2014/2016 Oracle Corporation: Oracle Database 10g /11g /12c MySQL Community Edition 5.1/5.5/5.6/5.7 *3 International Business Machines Corporation (IBM): DB2 for Linux, UNIX and Windows 9.5/9.7/10.1/10.5/11.1 Firebird Foundation Incorporated: Firebird 2.1/2.5 The PostgreSQL Global Development Group: PostgreSQL 9.2/9.3/9.4/9.5/9.6		
Number of DB Connections (Number of databases that can be connected at the same time)		3 connections max. *4		1
Instruction	Supported operations	The following operations can be performed by executing DB Connection Instructions in the NJ-series CPU Units. Inserting records (INSERT), Updating records (UPDATE), Retrieving records (SELECT), and Deleting records (DELETE)		
	Number of columns in an INSERT operation	SQL Server: 1,024 columns max. Oracle: 1,000 columns max.		
	Number of columns in an UPDATE operation	SQL Server: 1,024 columns max. Oracle: 1,000 columns max.		
	Number of columns in a SELECT operation	SQL Server: 1,024 columns max. Oracle: 1,000 columns max.		
	Number of records in the output of a SELECT operation	65,535 elements max., 4 MB max.		
Run mode of the DB Connection Service		Operation Mode or Test Mode • Operation Mode: When each instruction is executed, the service actually accesses the DB. • Test Mode: When each instruction is executed, the service ends the instruction normally without accessing the DB actually.		
Spool function		Used to store SQL statements when an error occurred and resend the statements when the communications are recovered from the error.		
	Spool capacity	2 MB *5	1 MB *5	192 KB *5
Operation Log function		The following three types of logs can be recorded. • Execution Log: Log for tracing the executions of the DB Connection Service. • Debug Log: Detailed log for SQL statement executions of the DB Connection Service. • SQL Execution Failure Log: Log for execution failures of SQL statements in the DB.		
DB Connection Service shutdown function		Used to shut down the DB Connection Service after automatically saving the Operation Log files into the SD Memory Card.		

*1. SQL Server 2014, Oracle Database 12c and PostgreSQL 9.2/9.3/9.4 are supported by DBCon version 1.02 or higher.
SQL Server 2016, My SQL 5.7, DB2 11.1 and Postgre SQL 9.5/9.6 are supported by DBCon version 1.03 or higher.
*2. Connection to the DB on the cloud is not supported.
*3. The supported storage engines of the DB are InnoDB and MyISAM.
*4. When two or more DB Connections are established, the operation cannot be guaranteed if you set different database types for the connections.
*5. Refer to "NJ/NX-series Database Connection CPU Units User's Manual(W527)" for the information.

Function Specifications of the NJ-series SECS/GEM CPU Units

Besides functions of the NJ501-1300, functions supported by the NJ501-1340 are as follows.

Item	Description
Supported port	Built-in EtherNet/IP port
Supported standard *1	The Unit conforms to the following SEMI standards: E37-0303, E37.1-0702, E5-0707, and E30-0307
Fundamental GEM requirement	State Model, Equipment Processing State, Host-initiated S1, F13/F14 Scenario, Event Notification, On-Line Identification, Error Message, Control (Operator Initiated), Documentation
Additional GEM capability	Establish Communications, Dynamic Event Report Configuration, Variable Data Collection, Trace Data Collection, Status Data Collection, Alarm Management, Remote Control, Equipment Constant, Process Recipe Management *1, Material Movement, Equipment Terminal Service, Clock, Limit Monitoring, Spooling *2, Control (Host Initiated)
User-defined message	You can create non-GEM compliant communications messages and have host communications.
GEM specific instruction	The Unit supports 29 instructions to perform the following: • Changing the GEM Service status. • Setting HSMS communications. • Reporting events and reporting alarms. • Acknowledging host commands and enhanced remote commands. • Changing equipment constants. • Uploading and downloading process programs. • Sending and acknowledging equipment terminal messages. • Requesting to change time. • Sending user-defined messages. • Getting SECS communications log.
GEM Service log *2	Can record the following information. • HSMS communications log: Keeps log of HSMS communications operations. • SECS message log: Keeps log of SECS-II communications messages. • Execution log: Keeps log of executions of GEM instructions.
Shutting down the GEM Service	Saves the spool data and GEM Service log records into an SD Memory Card and ends the GEM Service.

*1. E42 recipes, large process programs, and E139 recipes are not supported.
*2. The capability is not available when no SD Memory Card is mounted.

Conformance to Fundamental GEM Requirements and Additional Capabilities

Fundamental GEM requirements	GEM-compliant
State Model	Yes
Equipment Processing State	
Host-initiated S1, F13/F14 Scenario	
Event Notification	
On-Line Identification	
Error Message	
Control (Operator Initiated)	
Documentation	

Additional capabilities	GEM-compliant
Establish Communications	Yes
Dynamic Event Report Configuration	
Variable Data Collection	
Trace Data Collection	
Status Data Collection	
Alarm Management	
Remote Control	
Equipment Constant	
Process Recipe Management	Process program: Yes E42 recipes: No E139 recipes: No
Material Movement	Yes
Equipment Terminal Service	
Clock	
Limit Monitoring	
Spooling	
Control (Host Initiated)	

Function Specifications of the NJ-series NJ Robotics CPU Units

Besides functions of the NJ501-1□00, functions supported by the NJ501-4□□□ are as follows.

Item				NJ501-				
				4500	4400	4300	4310	4320
Robot control functions	Axes groups	Multi-axes coordinated control	Conveyer tracking	The robot is moved in synchronization with the conveyor during the conveyor tracking operation.				
		Auxiliary functions for multi-axes coordinated control	Kinematics Setting	Set parameters for robot operation, such as arm length of Delta3 robot.				
	Auxiliary functions	Monitoring functions	Work space function	Set the coordinate values for workspace check and check the workspace during operation.				

Function Specifications of the NJ-series NC Integrated Controller

Besides functions of the NJ501-1□00, functions supported by the NJ501-5300 are as follows.

Item					NJ501-5300
Numerical Control	CNC coordinate system	Axes types			Positioning axis, Spindle axis
		Control modes	Positioning axis		Position control
			Spindle axis		Velocity control
		Positions that can be managed			Absolute position (command), absolute position (actual), program position, remaining travel distance
		NC program execution	Execute		Executes the NC program.
			Reset		Interrupt NC program
			Single step execution		Executes the NC program by block.
			Back trace		Executes back trace of interpolation pass.
			Feed hold / Feed hold reset		Temporarily stops the NC program, and restarts it.
			Optional stop		Stops the NC program with optional signal.
			Optional block stop		Skips one block of the NC program with optional signal.
			Dry run		Runs operation from the NC program.
			Machine lock		Locks each axis operation during execution of the NC program.
			Auxiliary lock		Locks M code output.
			Override		Overrides the feed rate and spindle velocity.
		G Code	Position control	Rapid Positioning	Rapid feed of each CNC motor according to the motor setting.
				Linear interpolation	Interpolates linearly.
				Circular interpolation	Interpolates circularly, helically, spirally, or conically.
				Skip function	Rapid feed until an external signal is input.
			Return to reference point		Returns to a specified position on the machine.
			Canned cycle	Rigid tap	Performs tapping machining.
			Feed function	Exact stop	Temporarily prevents blending of positioning operations before and after an exact stop direction.
				Exact stop mode	Mode in which anteroposterior positioning operations are not blended.
				Continuous-path mode	Mode in which anteroposterior positioning operations are blended.
				Dwell	Waits for the specified period of time.
			Coordinate system selection	Machine Coordinate System	The coordinate system uses the machine home position as the home of the system.
				Work Coordinate System	The coordinate system has work offset for the Machine Coordinate System.
				Local Coordinate System	The coordinate system has additional offset for the Work Coordinate System.
			Auxiliary for coordinate system	Absolute/relative selection	Specifies manipulated variable absolutely, or switches to the relative setting.
				Metric/inch selection	Selects metric or inch as the orthogonal axes unit system.
				Scaling	Scales the current coordinates of the orthogonal axes.
				Mirroring	Mirrors the current coordinates for the specified orthogonal axes.
				Rotation	Rotate the current coordinates around the coordinates of the specified axis.
			Tool functions	Cutter compensation	Compensation of the tool edge path according to the tool radius.
				Tool length compensation	Compensation of tool center point path according to the tool length.
		M code	M code/M code reset		Outputs M codes, and interlocks with sequence control program using reset.
			Spindle axis	CW/CCW/Stop	Outputs/stops velocity commands in velocity loop control mode.
				Orientation	Stops spindle axis to the specified phase by setting up feed back loop.
			Subroutine call		Calls a subroutine of the NC program.
		NC programming	Arithmetic operation		Performs a calculation in the NC program.
			Branch control		Branches on condition in the NC program.
			User variables		Memory area in the NC program used for processing such as data calculation.
				P variable	System global memory area common to CNC coordinate systems
				Q variable	Global system area unique to each CNC coordinate system
				L variable	Memory area that can be used as the primary area during execution of the NC program
		Auxiliary control functions	Error reset		Function that resets errors or CNC coordinate system and CNC motor.
			Immediate stop		Function that stops all the CNC motors of the CNC coordinate system.

Item					NJ501- 5300
Numerical Control	CNC motor	Positions that can be managed			Commanded positions and actual positions.
		Position control	Absolute positioning		Positioning is performed for a target position that is specified using an absolute value.
			Relative positioning		Positioning is performed for a specified travel distance from the command current position.
			Cyclic positioning		A commanded position is output at each control period in Position Control Mode.
		Spindle control	CW/CCW/Stop		Outputs/stops velocity commands in velocity loop control mode.
		Manual operation	Powering the Servo		The Servo in the servo driver is turned ON to enable CNC motor operation.
			Jogging		A CNC motor is jogged at a specified target velocity.
		Auxiliary control functions	Homing		A CNC motor is operated, and the limit signals, home proximity signal, and home signal are used to define home.
			Immediate stop		A CNC motor is stopped immediately.
		CNC motor compensation table	Ball screw compensation		Pitch error compensation for one-dimensional ball screw.
			Cross-axis compensation		Compensation of one-dimensional cross-axis.
			Editing the CNC motor compensation table		Edit using sequence control program. (Read/write)
		Auxiliary functions	In-position check		You can set an in-position range and in-position check time to confirm when positioning is completed.
			Stop method		You can set the stop method to the immediate stop input signal or limit input signal.
			Monitoring functions	Software limits	Monitors the movement range of a CNC motor.
				Following error	Monitors the error between the command current value and the actual current value for a CNC motor.
			Absolute encoder support		You can use an OMRON 1S-series Servomotor or G5-series Servomotor with an Absolute Encoder to eliminate the need to perform homing at startup.
			Input signal logic inversion		You can inverse the logic of immediate stop input signal, positive limit input signal, negative limit input signal, or home proximity input signal.
		External interface signals			The Servo Drive input signals listed on the right are used. Home signal, home proximity signal, positive limit signal, negative limit signal, immediate stop signal, and interrupt input signal.
	Common items	Parameters	Changing CNC coordinate system and CNC motor parameters		You can access and change the CNC coordinate system and CNC motor parameters from the user program.

Version Information

Unit Versions

Units	Models	Unit Version
NX701 CPU Units	NX701-1□00	From unit version 1.10 to 1.16
NX701 Database Connection CPU Units	NX701-1□20	Unit version 1.16
NJ501 CPU Units	NJ501-□□□□	From unit version 1.00 to 1.17
NJ301 CPU Units	NJ301-□□□□	From unit version 1.01 to 1.16
NJ101 CPU Units	NJ101-□□□□	From unit version 1.11 to 1.16
NJ-series Database Connection CPU Units	NJ501-□□20	Unit version 1.05 From unit version 1.07 to 1.16
	NJ101-□020	From unit version 1.11 to 1.16
NJ-series SECS/GEM CPU Unit	NJ501-1340	From unit version 1.09 to 1.16
NJ-series NJ Robotics CPU Units	NJ501-4□□0	From unit version 1.02 to 1.16
NJ-series NC Integrated Controller	NJ501-5300	Unit version 1.16

Unit Versions and Programming Devices (NX701 CPU Units / NJ-series CPU Units)

The following tables show the relationship between unit versions and Sysmac Studio versions.

Unit Versions and Programming Devices

Unit Version of CPU Unit	Corresponding version of Sysmac Studio
1.17	1.21
1.16 *1 *2	1.20
1.15	1.19
1.14	1.18
1.13	1.17
1.12	1.16
1.11	1.15
1.10 *3 *4	1.14
	1.13
	1.12
1.09 *5	1.11
	1.10
1.08	1.09
1.07	1.08
1.06	1.07
1.05 *6	1.06
1.04	1.05
1.03	1.04
1.02	1.03
1.01	1.02
1.00 *7	1.01
	1.00

*1. The NX701-1□20 can be used with Sysmac Studio version 1.21 or higher.
*2. The NJ501-5300 can be used with Sysmac Studio version 1.20 or higher.
*3. The NJ101-1020 or NJ101-9020 can be used with Sysmac Studio version 1.14 or higher.
*4. The NX701-□□□□/NJ101-□□□□ CPU Unit can be used with Sysmac Studio version 1.13 or higher.
*5. The NJ501-1340 CPU Unit can be used with Sysmac Studio version 1.11 or higher.
*6. The NJ501-1□20 CPU Unit can be used with Sysmac Studio version 1.07 or higher.
*7. There is no NJ301-□□□□ CPU Unit with unit version 1.00. Therefore, you cannot use an NJ301-□□□□ CPU Unit with Sysmac Studio version 1.01 or lower.

Note: 1. If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the CPU Unit that corresponds to the Sysmac Studio version.
If you use a CPU Unit with an earlier version, select the unit version of the connected CPU Unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected CPU Unit.
2. The license number for a robot is required to use this CPU Unit. Contact your OMRON representative for details.

Unit Versions, DBCon Versions and Programming Devices (NJ/NX-series Database Connection CPU Units)

The following table gives the relationship between unit versions of CPU Units and the corresponding Sysmac Studio versions.

Unit version of CPU Unit	DBCon Version	Corresponding version of Sysmac Studio
1.16 *1	1.03	1.21
	1.02	1.20
1.15		1.19
1.14		1.18
1.13		1.17
1.12		1.16
1.11		1.15
1.10 *2		1.14
	1.01	1.13 1.12
1.09		1.11 1.10
1.08		1.09
1.07	1.00	1.08
1.05		1.07 1.06

Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the CPU Unit that corresponds to the Sysmac Studio version.
If you use a CPU Unit with an earlier version, select the unit version of the connected CPU Unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected CPU Unit.

*1. The NX701-1□20 can be used with Sysmac Studio version 1.21 or higher.
*2. For NJ101-□020, Supported only by the Sysmac Studio version 1.14 or higher.

Unit Versions, Robot Versions and Programming Devices (NJ-series NJ Robotics CPU Units)

The following table gives the relationship between unit versions of CPU Units and the corresponding Sysmac Studio versions.

Unit version of CPU Unit	Robot version of CPU Unit	Corresponding version of Sysmac Studio
1.16	1.04	1.20
1.15		1.19
1.14		1.18
1.13	1.03	1.17
1.12		1.16
1.11		1.15
1.10	1.02	1.14
1.09	1.02	1.13
1.08	1.02	1.12
	1.01	1.11 1.10
1.07	1.00	1.08
1.06		1.07
1.05		1.06
1.04		1.05
1.03		1.04
1.02		

Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the CPU Unit that corresponds to the Sysmac Studio version.
If you use a CPU Unit with an earlier version, select the unit version of the connected CPU Unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected CPU Unit.

Unit Versions and Programming Devices (NJ-series NC Integrated Controller)

Unit Version	CNC Version	Corresponding version of Sysmac Studio
Ver.1.16	Ver.1.00	Ver.1.20

Note: If you use a lower version of the Sysmac Studio, you can use only the functions of the unit version of the CPU Unit that corresponds to the Sysmac Studio version.
If you use a CPU Unit with an earlier version, select the unit version of the connected CPU Unit or an earlier unit version in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio. You can use only the functions that are supported by the unit version of the connected CPU Unit.

Relationship between Hardware Revisions of CPU Units and Sysmac Studio Versions

The following table shows how the hardware revisions of the NJ-series CPU Units correspond to Sysmac Studio versions. Use the corresponding version of Sysmac Studio or higher if you execute the Simulator in Execution Time Estimation Mode. You cannot select the relevant hardware revision if you use a lower version of the Sysmac Studio.

Model number	Hardware revision of CPU Unit	Corresponding version of Sysmac Studio
NJ501-□□□□	A	Ver.1.14 or higher

Functions That Were Added or Changed for Each Unit Version and Sysmac Studio version

Additions and Changes to Functional Specifications

The following table gives the unit version of the CPU Units and the Sysmac Studio version for each addition or change to the functional specifications.

Function				Addition/ change	Unit version	Sysmac Studio version
Tasks	Function	Conditionally executed tasks		Addition	1.03	1.04
Programming	Namespaces			Addition	1.01	1.02
	Data types	Structure data types	Specifying member offsets	Addition	1.01	1.02
				Change		1.03
	Libraries			Addition	1.01	1.02
Motion control	Single axes	Single-axis position control	Cyclic synchronous absolute positioning	Addition	1.03	1.04
		Auxiliary function for single-axis control	Homing with specified parameters	Addition	1.03	1.04
			Enabling digital cam switches	Addition	1.06	1.07
			Command position compensation	Addition	1.10	1.12
			Start velocity	Addition	1.05	1.06
	Axes groups	Multi-axes coordinated control	Axes group cyclic synchronous absolute positioning	Addition	1.01	1.02
		Auxiliary functions for multi-axes coordinated control	Reading axes group positions	Addition	1.01	1.02
			Changing the axes in a group	Addition	1.01	1.02
	Common items	Cams	Generating cam tables	Addition	1.08	1.09
		Parameters	Changing axis parameters	Addition	1.08	1.09
	Auxiliary functions	Input signal logic inversion		Addition	1.05	1.06
Unit (I/O) management	NX Units			Addition	1.05	1.06
Communications	EtherNet/ IP port	TCP/IP applications	FTP client	Addition	1.08	1.09
	EtherCAT port	Packet monitoring * (NJ301-□□□□)		Addition	1.10	1.12
	Communications instructions			Change	1.08 1.11	1.09 1.15
Debugging function	Differential monitoring			Addition	1.03	1.04
Reliability functions	Self diagnosis	Controller errors	Changing levels	Addition	1.03	1.04
Security	Asset protection and preventing incorrect operation	Protection	Data protection	Addition	1.01	1.02
		Operation authority verification	Number of groups	Change	1.01	1.02
SD Memory Cards	Application	Automatic transfer from SD Memory Card		Addition	1.03	1.04
		Transfer program from SD Memory Card		Addition	1.11	1.15
Backing up data	SD Memory Card back-ups	Operating methods	CPU Unit front-panel DIP switch	Addition	1.03	1.04
			Specification with system-defined variables	Addition	1.03	1.04
			SD Memory Card Window in Sysmac Studio	Addition	1.03	1.04
			Special instruction	Addition	1.08	1.09
		Protection	Disabling backups to SD Memory Cards	Addition	1.03	1.04
	Sysmac Studio Controller backups			Addition	1.03	1.04

* This addition applies only to an NJ301-□□□□ CPU Unit. The NJ501-□□□□ and NJ101-□□□□ CPU Units support packet monitoring with all versions.

Performance Improvements for Unit Version Upgrades

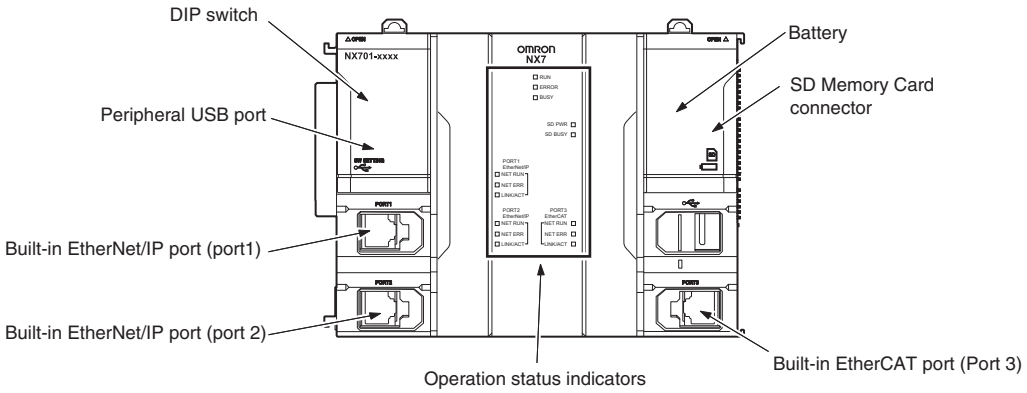
This section introduces the functions for which performance was improved for each unit version of NJ-series CPU Unit and for each Sysmac Studio version.

Function				Performance value	Unit version	Sysmac Studio version
Programming	Program capacity	Quantities	Number of POU instances (NJ501-□□□□)	9,000	---	1.06 or higher
				6,000	---	1.05 or lower
			Number of POU instances (NJ301-□□□□)	3,000	1.04 or later	1.05 or higher
				1,500		1.04 or lower
				2,400	1.03 or earlier	1.05 or higher
				1,500		1.04 or lower
	Memory capacity for variables	Variables with a Retain attribute	Number of variables *1 (NJ301-□□□□)	5,000	1.04 or later	1.05 or higher
				2,500		1.04 or lower
				2,500	1.03 or earlier	---
Motion Control	Number of controlled axes	Maximum number of controlled axes *2*3*4 (NJ301-□□□□)		15 axes	1.06 or later	1.07 or higher
				8 axes (NJ301-1200) 4 axes (NJ301-1100)	Other than the above combination	
		Maximum number of axes for single-axis control *4*5 (NJ301-□□□□)		15 axes	1.06 or later	1.07 or higher
				8 axes (NJ301-1200) 4 axes (NJ301-1100)	Other than the above combination	
Built-in EtherNet/IP port	CIP service: Tag data links (cyclic communications)	Packet interval		Can be set for each connection. 1 to 10,000 ms in 1-ms increments	1.03 or later	---
				Can be set for each connection. 10 to 10,000 ms in 1-ms increments	1.02 or earlier	
		Permissible communications band		3,000 pps*6 (including heartbeat)	1.03 or later	---
				1,000 pps (including heartbeat)	1.02 or earlier	
	Number of TCP sockets			30	1.03 or later	---
				16	1.02 or earlier	
Built-in EtherCAT port	Communications cycle *7 (NJ301-□□□□)			500, 1,000, 2,000, or 4,000 μs	1.03 or later	---
				1,000, 2,000, or 4,000 μs	1.02 or earlier	

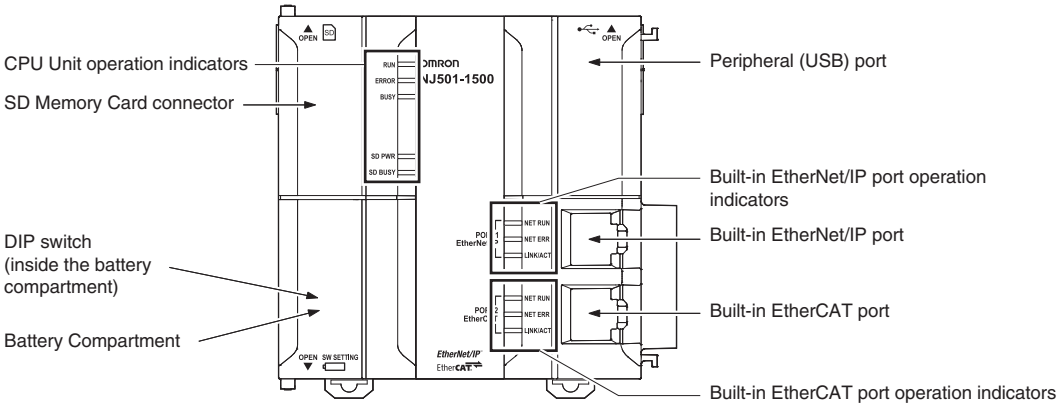
*1. The performance improvement applies only to an NJ301-□□□□ CPU Unit. The maximum number of variables with a Retain attributes for the NJ501-□□□□ is 10,000.
*2. This is the total for all axis types.
*3. The performance improvement applies only to an NJ301-□□□□ CPU Unit. The maximum numbers of controlled axes for the NJ501-□□□□ are as follows:
NJ501-1500: 64 axes, NJ501-1400: 32 axes, and NJ501-1300: 16 axes
*4. There is no change in the maximum number of used real axes.
*5. The performance improvement applies only to an NJ301-□□□□ CPU Unit. The maximum numbers of axes for single-axis control for the NJ501-□□□□ are as follows:
NJ501-1500: 64 axes, NJ501-1400: 32 axes, and NJ501-1300: 16 axes
*6. Here, pps means “packets per second” and indicates the number of packets that can be processed in one second.
*7. The performance improvement applies only to an NJ301-□□□□ CPU Unit. You can use 500, 1,000, 2,000 or 4,000 μs communications cycle with an NJ501-□□□□ CPU Unit, and 1,000, 2,000 or 4,000 μs communications cycle with an NJ101-□□□□ CPU Unit.

Components and Functions

NX-series CPU Unit



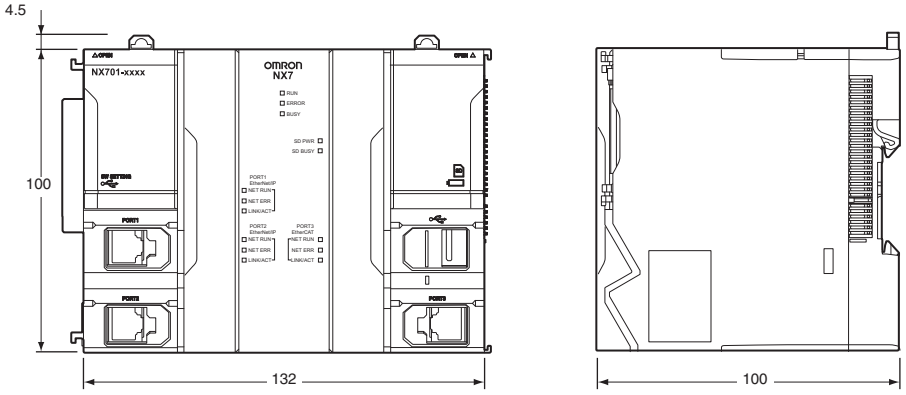
NJ-series CPU Unit



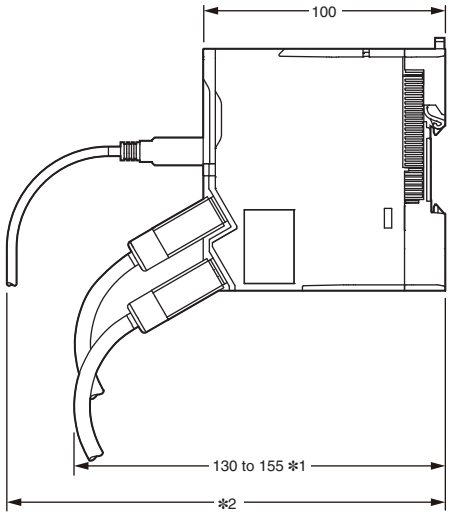
Dimensions

(Unit: mm)

NX701 CPU Units (NX701-□□□□)



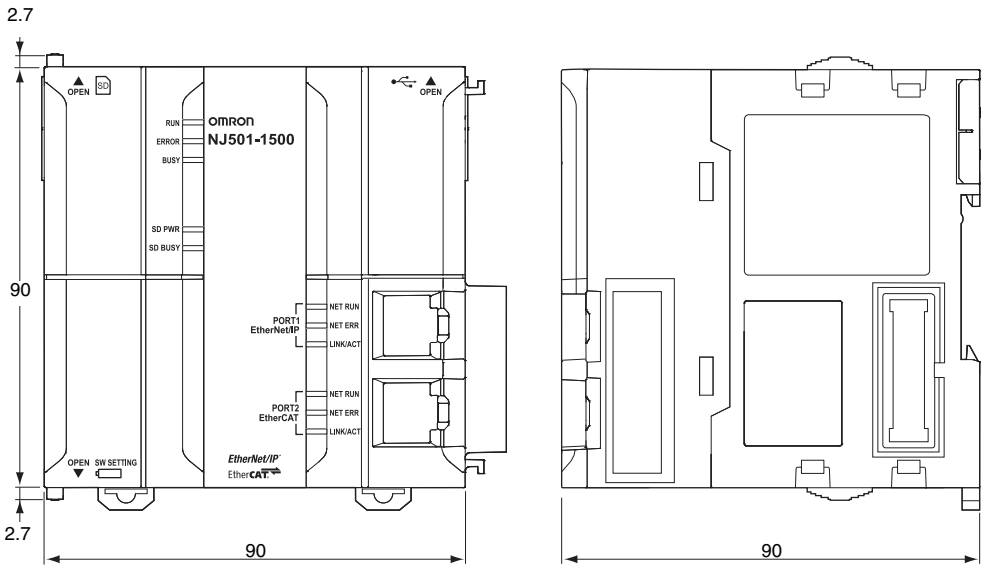
When a cable is connected (such as a communications cable)



✻1. This is the dimension from the back of the Unit to the communications cables.
130 mm: When an MPS588-C Connector is used.
155 mm: When an XS6G-T421-1 Connector is used.

*2. This dimension depends on the specifications of the commercially available USB cable. Check the specifications of the USB cable that is used.

NJ-series CPU Units



Related Manuals

Cat. No.	Model number	Manual	Application	Description
W513	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ Series Startup Guide (CPU Unit)	Using the NJ-series CPU Unit for the first time	The startup procedures for using an NJ-series CPU Unit and the basic operating instructions for the Sysmac Studio are described with a simple sequence control example.
W514	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series Startup Guide (Motion Control)	Using the motion control function module of the NJ/NX-series for the first time	The startup procedures for setting axis parameters and performing simple one-axis positioning and two-axis linear interpolation with an NJ/NX-series CPU Unit and the operating instructions for the Sysmac Studio are described.
W535	NX701-□□□□	NX-series CPU Unit Hardware User's Manual	Learning the basic specifications of the NX701-series CPU Units, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NX701-series system is provided along with the following information on a Controller built with a CPU Unit. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection Use this manual together with the *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W500	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series CPU Unit Hardware User's Manual	Learning the basic specifications of the NJ-series CPU Units, including introductory information, designing, installation, and maintenance Mainly hardware information is provided.	An introduction to the entire NJ-series system is provided along with the following information on a Controller built with a CPU Unit. • Features and system configuration • Introduction • Part names and functions • General specifications • Installation and wiring • Maintenance and inspection Use this manual together with the *NJ-series CPU Unit Software User's Manual* (Cat. No. W501).
W501	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series CPU Unit Software User's Manual	Learning how to program and set up an NJ/NX-series CPU Unit. Mainly software information is provided.	The following information is provided on a Controller built with an NJ/NX-series CPU Unit. • CPU Unit operation • CPU Unit features • Initial settings • Programming language specifications and programming with the IEC 61131-3 standard. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500).
W507	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series CPU Unit Motion Control User's Manual	Learning about motion control settings and programming concepts	The settings and operation of the CPU Unit and programming concepts for motion control are described. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W505	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual	Using the built-in EtherCAT port on an NJ/NX-series CPU Unit	Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W539	NJ501-4□□□	NJ-series Robotics CPU Units User's Manual	Using the robot control with NJ-series Controllers.	Describes the robot control. Use this manual together with the *NJ/NX-series CPU Unit Motion Control User's Manual* (Cat. No. W507) and the *NJ/NX-series Motion Control Instructions Reference Manual* (Cat. No. W508).
W527	NX701-□□20 NJ501-□□20 NJ101-□□20	NJ/NX-series Database Connection CPU Units User's Manual	Learning about the functions and application procedures of the NJ/NX-series DB Connection function.	Describes the functions and application procedures of the NJ/NX-series DB Connection function.
W528	NJ501-1340	NJ-series SECS/GEM CPU Unit User's Manual	Learning about the SECS/GEM CPU Unit and how to use it.	Functional outline, GEM instructions, settings with the GEM Configurator and so on are provided.
O030	NJ501-5300 NY532-5400	NJ/NY-Series NC Integrated Controller User's Manual	For numerical control with NJ/NY-series	Describes the numerical control function. When programming, use this manual together with the G Code Instructions Reference Manual (O0301-E1).
W506	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual	Using the built-in EtherNet/IP port on an NJ/NX-series CPU Unit	Information on the built-in EtherNet/IP port is provided. Information is provided on the basic setup, tag data links, FINS communications (non-disclosure), and other features. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W588	NJ501-1500 NJ501-1400 NJ501-1300	NJ-series CPU Unit OPC UA User's Manual	Learning general information, operating procedures and functions of the NJ-series OPC UA.	This manual describes the setting procedures and functions of NJ-series OPC UA.

Cat. No.	Model number	Manual	Application	Description
W502	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series Instructions Reference Manual	Learning about the specifications of the instruction set that is provided by OMRON	The instructions in the instruction set (IEC 61131-3 specifications) are described. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W508	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series Motion Control Instructions Reference Manual	Learning about the specifications of the motion control instructions that are provided by OMRON	The motion control instructions are described. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500), *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501) and *NJ/NX-series CPU Unit Motion Control User's Manual* (Cat. No. W507).
W503	NX701-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ/NX-series Troubleshooting Manual	Learning about the errors that may be detected in an NJ/NX-series Controller.	Concepts on managing errors that may be detected in an NJ/NX-series Controller and information on individual errors are described. Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
W504	SYSMAC-SE2□□□	Sysmac Studio Version 1 Operation Manual	Learning about the operating procedures and functions of the Sysmac Studio.	Describes the operating procedures of the Sysmac Studio.
O031	NJ501-5300 NY532-5400	NJ/NY-series G code Instruction Reference Manual	Learning about detailed specifications of the G code/M code instructions.	This section describes G code/M code instructions in detail. When programming, use this manual together with the User's Manual (O0301-E1).
W589	SYSMACSE2□□□ SYSMAC-TA4□□□	Sysmac Studio Project Version Control Function Operation Manual	Learning the overview of the Sysmac Studio project version control function and how to use it.	The manual outlines the Sysmac Studio project version control function, and describes how to install, basic operation, and how to operate its major functions.
O032	SYSMAC-RTNC0□□□D	CNC Operator Operation Manual	Learning the overview of CNC Operator and how to use it.	Describes the CNC Operator, installation procedure, basic operation, connection operation, and operating procedures for main functions.
W490 W498 W491 Z317 W492 W494 W497 W495 W493	CJ1W-□□□□*	CJ-series Special Unit Manuals for NJ-series CPU Unit	Leaning how to connect CJ-series Units	The methods and precautions for using CJ-series Units with an NJ-series CPU Unit are described, including access methods and programming interfaces. Manuals are available for the following Units. Analog I/O Units, Insulated-type Analog I/O Units, Temperature Control Units, ID Sensor Units, High-speed Counter Units, and DeviceNet Units, EtherNet/IP Units, CompoNet Master Units Use this manual together with the *NJ-series CPU Unit Hardware User's Manual* (Cat. No. W500) and *NJ/NX-series CPU Unit Software User's Manual* (Cat. No. W501).
Y128	SYSMAC-SE20□□ SYSMAC-RA401L NJ501-4□□□ R88D-KN□-ECT FH-1□□□ FH-3□□□	Vision & Robot Integrated Simulation Startup Guide	Learning about the operating procedures of Vision & Robot integrated simulation.	Describes the operating procedures of Vision & Robot integrated simulation.
Y213		Vision & Robot Integrated Simulation Technology Introduction Guide (Calibration Parameter)	Learning about the calibration parameters created using the 3D Equipment Model Creation Wizard for the Vision & Robot integrated simulation.	Describes calibration parameters created using the 3D Equipment Model Creation Wizard for the Vision & Robot integrated simulation.
Z368		Vision Sensor FH Series Conveyor Tracking Application Programming Guide	Learning about the setup procedure of the wizard style calibration for cameras, robots, or conveyors.	Describes how to configure and operate Conveyor Tracking Calibration Wizard on Sysmac Studio on FH Sensor Controllers.
Z369		Vision Sensor FH Series Operation Manual Sysmac Studio Calibration Plate Print Tool	Learning about the setup procedure for printing the Pattern on a Calibration Plate used for calibration for cameras and robots on Sysmac Studio.	Describes how to configure and operate Calibration Plate Print Tool on Sysmac Studio on FH Sensor Controllers.
Z370		Vision Sensor FH Series Operation Manual Sysmac Studio Conveyor Tracking Calibration Wizard Tool	Learning about the setting procedure of sample macros for conveyor tracking.	Describes the setting procedure of sample macros used for applications of conveyor tracking on FH Sensor Controllers.
Z371		Vision Sensor FH Series Operation Manual Sysmac Studio Conveyor Panorama Display Tool	Learning about the setup procedure of panorama display for image capture of targets on conveyors.	Describes how to configure and operate the Conveyor Panorama Display tool on Sysmac Studio on FH Sensor Controllers.

* You can use only with NJ-series CPU Unit.

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