

**FACTORY AUTOMATION** 

# NUMERICAL CONTROL (CNC) C80 Series



Global Player Contents

# GLOBAL IMPACT OF MITSUBISHI ELECTRIC







Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

### Changes for the Better

"Changes for the Better" represents the Mitsubishi Electric Group's attitude to "always strive to achieve something better", as we continue to change and grow. Each one of us shares a strong will and passion to continuously aim for change, reinforcing our commitment to creating "an even better tomorrow".

Mitsubishi Electric is involved in many areas including the following:

#### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

#### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

#### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

#### Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

#### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.

#41 TOP NO SOUTH COMPANS

Our advances in Al and IoT are adding new value to society in diverse areas from automation to information systems. The creation of game-changing solutions is helping to transform the world, which is why we are honored to be recognized in the 2019 "Forbes Digital 100" as one of world's most influential digital corporations.

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Revolutionary, next-generation CNC opens a new era of production lines through compatibility with MELSEC iQ-R Series

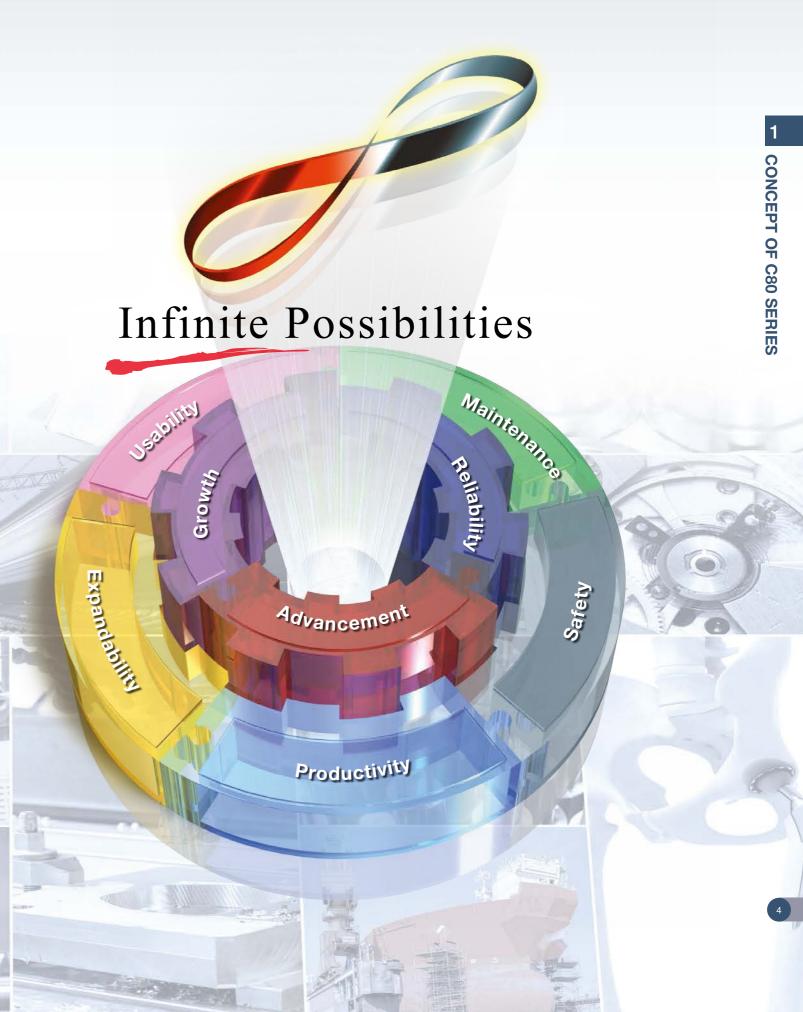
# **C80 Series**

Advanced technologies delivered by the breakthrough performance of our CNC-dedicated CPU. Reliable MELSEC quality accumulated in various industrial scenes.

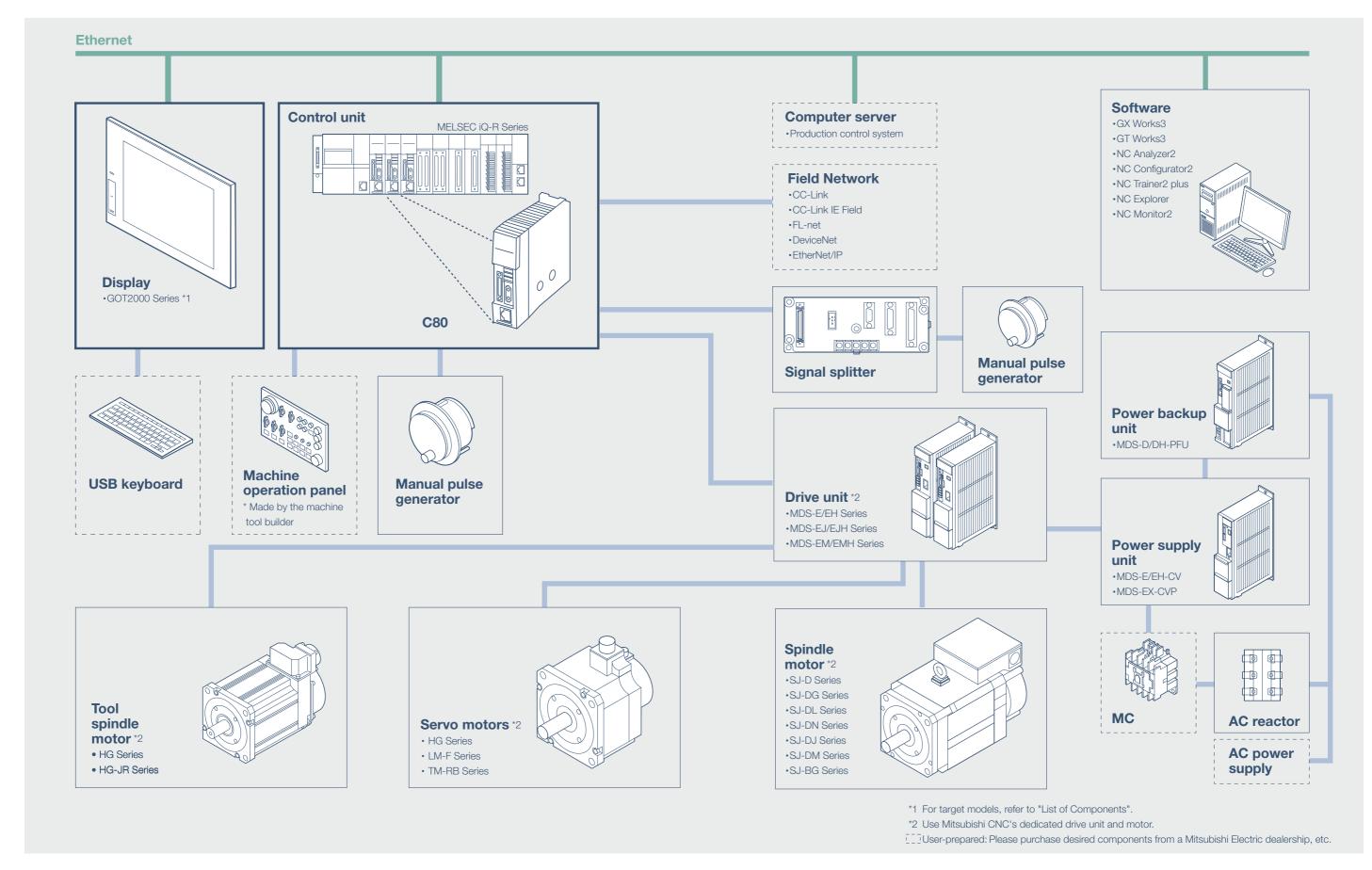
In addition, the CNC C80 Series can be expanded and updated over time.

Five features (productivity, expandability, usability, maintenance and safety) empower manufacturing lines with infinite possibilities and innovative values in terms of advancement, reliability and growth.



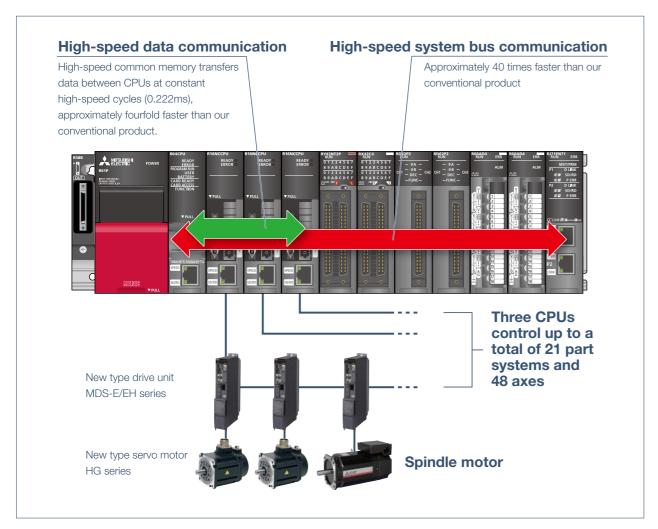


# **CNC SYSTEM CONFIGURATIONS**



### **PRODUCTIVITY**

Mitsubishi Electric's original CNC-dedicated CPU provides a major leap in basic performance. A newly developed high-speed system bus approximately 40 times faster than our conventional product provides high-speed, large-capacity data communication. CNC control functions and drive units have been improved, enabling high-speed, highly accurate machining. The C80 Series contributes to reducing cycle time and increasing productivity.



#### PLC processing capability (PCMIX value)



High processing capability of the PLC enables large-scale ladder logic to be processed at high speed in response to the demands in the era of IoT.

#### **CNC-to-drive** communication capability



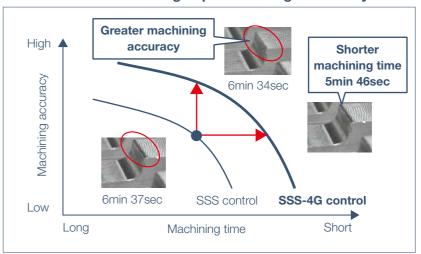
Optical communication speed between CNC and drive has been increased. This improves system responsiveness, leading to more accurate machining.

### processing capability



Miscellaneous command processing between CNC and PLC became 1.5 times faster than our conventional product. Shorter processing time leads to reduction in cycle time.

#### CNC functions ensure high speed and high accuracy



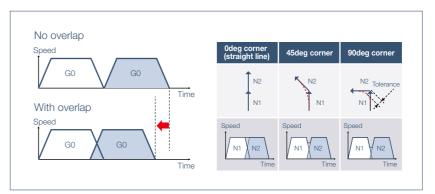
#### **SSS-4G Control**

The M80 Series is equipped with Super Smooth Surface 4th-Generation (SSS-4G) control. This feature effectively reduces tact time, including acceleration and deceleration appropriate for the characteristics of each axis. SSS-4G control simultaneously enhances cutting accuracy, reducing cutting time while maintaining the same degree of accuracy compared to our previous models.



#### **Tolerance Control**

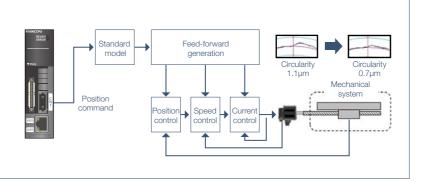
This function enables operators to make high-quality surfaces simply by specifying the desired surface dimensional accuracy and providing a smooth cutting motion within specified error tolerances.



#### **Rapid Traverse Block** Overlap

This function enables cutting of the next block to start before positioning deceleration (G00) or reference position return (G28/G30) has been completed, resulting in shorter intervals between cutting processes.

#### **Drive function increases speed**



#### **OMR-FF Control**

This function optimizes the position loop gain for each axis, leading to smoother and more accurate cutting, and drawing out the full potential of the machine tools.

## EXPANDABILITY e-F@ctory

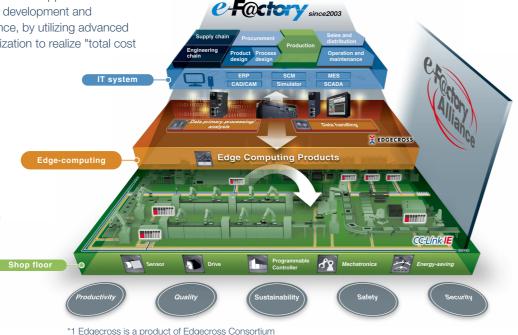
The e-F@ctory integrated solution supports the future of machining in all areas, from development and manufacturing to maintenance, by utilizing advanced expertise and factory optimization to realize "total cost reduction."



The CNC C80 Series supports the iQ Platform, the integrated FA platform that forms the core of e-F@ctory.



Utilization of open software platform "Edgecross" which realizes FA-IT coordination in the edge computing level enhances Edge computing and e-F@ctory.



#### This solution enables visualization and analysis that lead to improvements and increase availability at production sites.

The Manufacturing Execution System (MES) Interface is the link for data passing from production equipment to controlling devices. The High-speed Data Logger collects data from each measuring device directly without requiring dedicated logging equipment.

The Box Data Logger can be connected to a network while existing equipment is running, and collect data thereafter.

The C Language Controller provides control, information processing and higher-level communication using C/C++ programming.

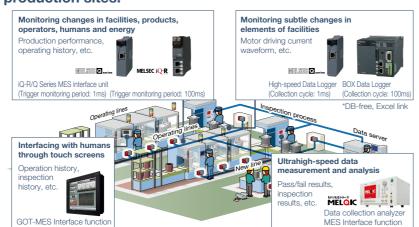
These products, which enable information sharing between FA and IT, implement factory-wide optimization, from higher-level information systems to facility management systems.

#### e-F@ctory Alliance

e-Factory Alliance offers our customers the optimal solution across entire supply and engineering chains through strong alliances with partners who provide software and devices highly compatible formation with Mitsubishi FA products, and system and operation of the integration partners who build systems production floor using those products.

#### **Participating companies:** 900 or more

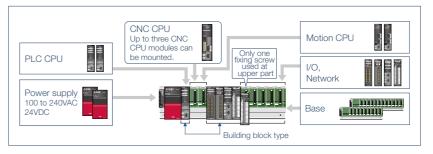
(In total domestic and overseas, as of Sep. 2020)



Data on shop floor have different characteristics according to their purposes



#### Flexible system configurations



The PLC CPU is independent in the C80 Series, enabling selection according to production scale and application, and best-fit configuration of hardware.

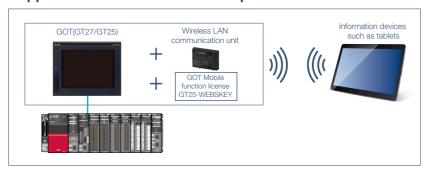
#### Edge computing, the latest technology



#### **MELIPC MI5000**

One module realizes device control and information processing which were previously managed with a combination of computer and dedicated device for example. Equipped with real-time OS VxWorks®, the MELIPC realizes real-time control which cannot be achieved with general industrial computers, contributing to high-accuracy device control and information processing at high-speed.

#### Support for "visualization" of shop floor

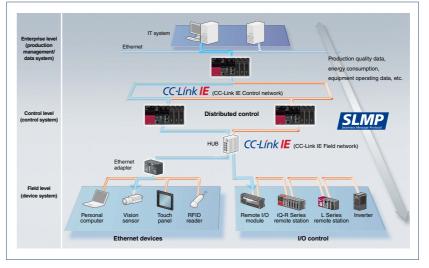


#### **GOT Mobile**

Via GOT at the worksite, connected devices can be monitored from computers and tablets in a remote location.

\*A separate license (GT25-WEBSKEY) is

#### Seamless connectivity between shop floor and host information system



#### Field network **CC-Link IE Field**

Single network covers high-speed controller distributed control, I/O control and safety control. The network allows a high degree of freedom in wiring for flexible equipment layouts.

#### **Controller network CC-Link IE Control**

The controller network builds a highly reliable high-speed, large-capacity system and dual optical loop.

CNC monitor2 newly developed to simplify use through the introduction of touch-screen operation displays the equivalent screen to the M800/M80 Series standard screens available in 8.4, 10.4 and 12.1-type models.



#### CNC monitor2 screen designed with pursuit of ease-of-use



Program edit screen enables direct-touch data entry, eliminating the use of cursor keys and realizing more intuitive operation.

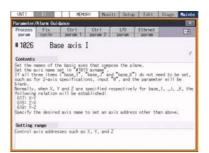
#### Direct transition to CNC monitor2 screen

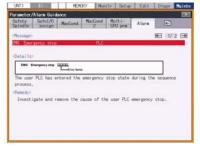


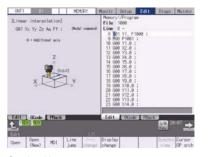
NC monitor2 allows a short-cut key to be designated for taking the operator directly to a specific CNC monitor2 screen from a machine builder-prepared screen. The key enables the operator to, for example, call up a parameter screen with a single touch instead of the conventional three-step operation. Additionally, machine builders can use CNC monitor2 screens as is, reducing the workload related to designing screens.

#### More convenient guidance function

Pressing Help opens a guidance of the currently displayed screen (parameter, alarm or G-code format). This frees the operator from looking information up in a printed manual.







Parameter guidance

Alarm guidance

G code guidance

#### Simple screen with enhanced visibility from a long distance



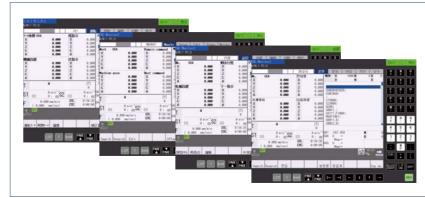
The simple monitor screen has been designed to make it easy to see and read only data required from a distance.

Switching between Normal screen and Simple screen is done from the screen menu.

\*The simple display can be used only when the parameter #11019 (2-system display) is invalid.

Simple monitor screen

#### CNC monitor2 supports 17 languages



Display languages can be switched with a single parameter operation.

This provides great ease of use for users worldwide.

#### Languages supported

oupunooc	011111000 (110
English	Chinese (sir
German	Korean
Italian	Portuguese
French	Hungarian
Spanish	Dutch

Chinese (traditional)
Chinese (simplified)
Korean
Portuguese
Hungarian
Czech
Chinese (traditional)
Curkish
Turkish
Polish
Russian
Czech

#### VGA added to product line



CNC monitor2 supports VGA in addition to the conventional SVGA resolution, which expands the availability of GOT2000 Series.

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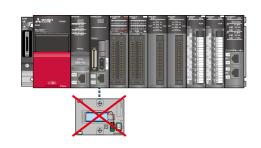
Press the [Setup] key.

### **MAINTENANCE**

The C80 Series has greatly improved maintenance features compared to our conventional product, including the ability to acquire three times the alarm and warning history data. The program number and PLC number of the machining program executed can also be acquired, leading to early problem solving and less downtime.

#### **CNC CPU** requires no batteries

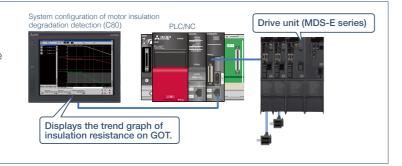
The CNC CPU backs up NC data (e.g., parameters, machining programs and alarm history) without the use of batteries. Troublesome battery management and battery exchange are no longer required, leading to a reduction in maintenance costs.



#### Motor insulation degradation detection function

Insulation resistance value measured by a drive unit can be displayed. The trend graph displayed on GOT can be

used for preventive maintenance.



### **Operation history**

This function traces various histories and NC operating information to analyze and solve

This information is recorded in the history data file, it can be displayed on the screen and can also be output to a file.



### Log viewer function

GOT log viewer function displays the NC sampling data. This enables waveforms to be diagnosed on the spot for early troubleshooting.

In addition, the trends of insulation resistance value can be checked on the viewer. (Displays last 13 months data on a monthly basis)



#### **GOT** backup/restoration

The C80 Series supports data storage (backup) and writing (restore) of not only C80 parameters and programs, but also PLC CPU data into SD memory card or the USB memory of the GOT. The system can be restored using GOT only, enabling parts to be exchanged for quick system restoration.



#### On-board ladder edit of GOT

Use the GOT "Sequence program monitor (R Ladder) function" to edit sequence ladder programs without requiring GX Works on a computer. Ladder program operation status can be confirmed as well.





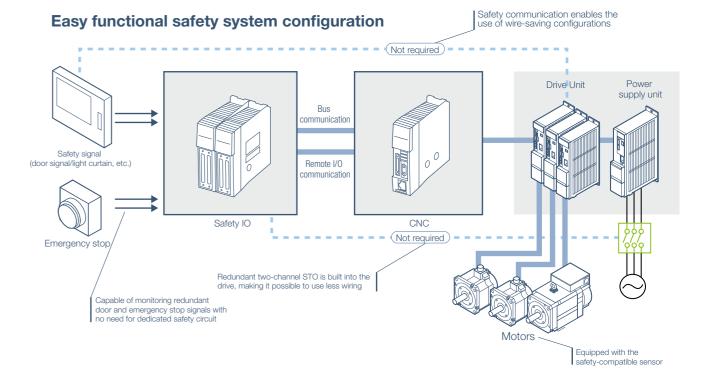
The C80 Series provides a range of safety features collectively called the "Smart Safety Observation Function". This function has achieved full conformity with the safety standards that cover the entire system including CNC, drive, I/O, sensors and communication.

#### **Smart Safety Observation Function**

Safety-related I/O observation Safely-Limited Speed (SLS) Safe Operating Stop (SOS) Safe Brake Control/Safe Brake Test (SBC/SBT) Safe Stop (SS1/SS2)

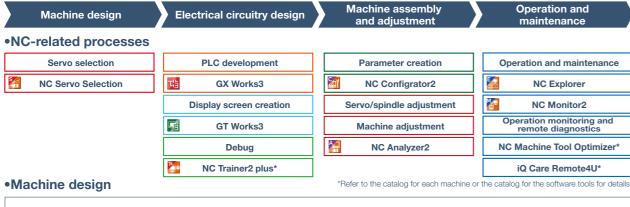
Emergency stop observation Safely-Limited Position (SLP) Safe Speed Monitor (SSM) Safe Cam (SCA) Safe Torque Off (STO)

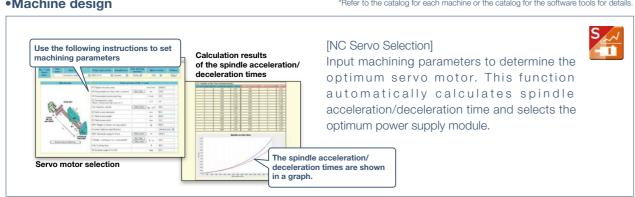
Safety Communication Network (SCN)



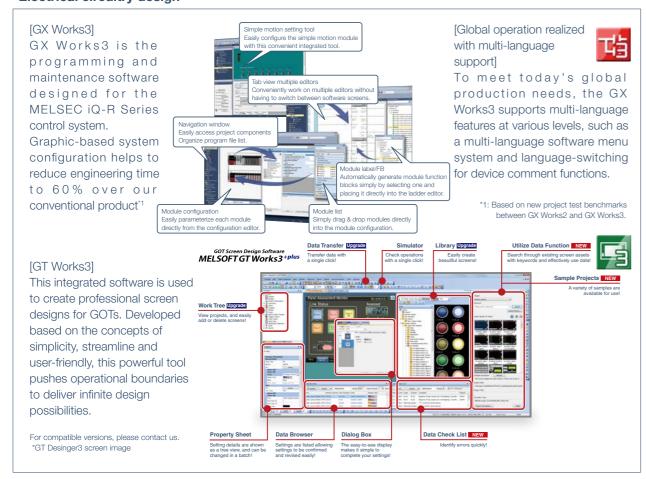
### **SOFTWARE TOOLS**

#### Flow from machine design and development to operation and maintenance



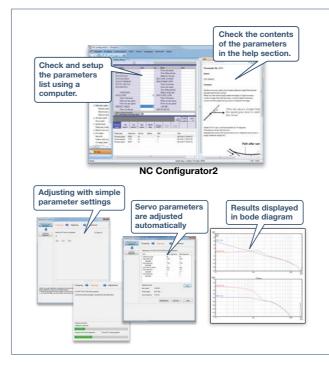


#### •Electrical circuitry design



For details on GX Works3, please refer to the GX Works3 catalog (L(NA)08334). For details on GT Works3, please refer to the GT Works3 catalog (L(NA)08170). For details on each software tool, refer to the software tools catalog (BNP-A1246).

#### Machine assembly and adjustment



#### [NC Configurator2]

NC parameters required for NC control or machine operation can be edited on a computer. It is also possible to create initial parameters simply by inputting the machine configuration.

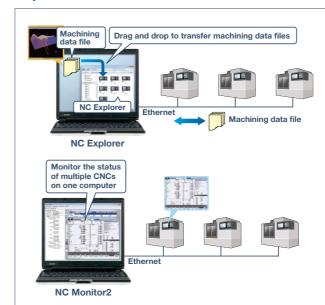


#### [NC Analyzer2]

Servo parameters can be adjusted automatically by measuring and analyzing machine characteristics. Measurement and analysis can be done by running a servo motor using the machining program for adjustment, or using the vibration signal. This function can sample various types of data.



#### Operation and maintenance



#### [NC Explorer]

CNC machining data can be managed using Windows® Explorer on a computer when the computer is connected to multiple CNCs via Ethernet.



#### [NC Monitor2]

Taking advantage of connection with a factory network, CNC operation status can be monitored from remote locations. Several CNCs can be connected and monitored simultaneously.



### **DRIVE SYSTEM**

#### Drive units



#### High-performance Servo/ Spindle Drive Units MDS-E/EH Series

- •The servo control-dedicated core processor realizes improved control speed, leading to enhanced basic performance. When combined with a higher resolution motor sensor and enhanced high-speed optical communication, this drive contributes to high-speed, high-accuracy control.
- •The motor power connector is equipped with an anti-misinsertion mechanism. This helps to eliminate connection errors.
- •Improved diagnostic and preventive maintenance features
- •Safe Torque Off (STO) and Safe Brake Control (SBC) are also incorporated as additional safety



#### Multi-hybrid Drive Units MDS-EM/EMH Series

- •Multi-hybrid drive units are capable of driving a maximum of three servo axes and one spindle. This contributes to downsizing machines and offers technical advantages.
- •The motor power connector is equipped with an anti-misinsertion mechanism. This helps to eliminate connection errors.
  •Safe Torque Off (STO) and Safe
- Brake Control (SBC) are also incorporated as additional safety features.
- •The fan unit facilitates fan exchange. •An MDS-EMH drive unit is available for 400V systems.



#### All-in-one Compact Drive Units MDS-EJ/EJH Series

- •Ultra-compact drive units with built-in power supply contribute to smaller control panel size.
- A 2-axis type has been added for further downsizing.
- •The servo control-dedicated core processor realizes improved control speed, leading to improved basic performance. When combined with a higher resolution motor sensor and enhanced high-speed optical communication, this drive contributes to high-speed, high-accuracy control.
- Safe Torque Off (STO) and Safe Brake Control (SBC) are also incorporated as additional safety features.
- •An MDS-EJH drive unit is available for 400V systems. (Note 1)



#### PWM Converter MDS-EX-CVP Series

- Products of the PWM converter series which provides a stabilizing DC voltage function and boost function. The MDS-EX-CVP Series reduces the output deceleration of the spindle motor and improves output in the high-speed range.
- Available for 400V system power supply units only.

### •Spindle motors



#### High-performance Spindle Motors SJ-D Series

- •Motor energy loss has been significantly reduced by optimizing the magnetic circuit.
- High-speed bearings are incorporated as a standard feature, helping to achieve higher speed, lower vibration and improved durability.
   Range: 3.7 to 26 [kW]
- •Maximum speed: 8,000 to 12,000 [r/min]

#### High-output, High-speed Spindle Motors SJ-DG Series

- •The addition of S3 rating (%ED rating) has improved output and torque acceleration/deceleration characteristics
- •A balance adjustment ring added to the counter-load side allows for fine tuning.
- •Range: S3 rating: 5.5 to 15 [kW]
- •Maximum speed: 10,000 to 12,000 [r/min]

#### High-torque Spindle Motors SJ-DN Series

- Higher torque characteristics than those of the SJ-D Series with the same output. This series can be driven with a small-capacity multi-hybrid drive unit.
- Suitable for heavy cutting. Helps to improve productivity.
- •Range: 7.5 to 18.5 [kW]
  •Maximum speed: 8,000 [r/min]

#### Low-inertia, High-speed Spindle Motors SJ-DL Series

- •This series of spindle motors is dedicated for use in tapping machines that require faster drilling and tapping.
- •The latest design technologies make it possible to attain lower vibration and greater rigidity even with lighter weight.
- •Range: 0.75 to 7.5 [kW]
- •Maximum speed: 10,000 to 24,000 [r/min]

#### Compact, Lightweight Spindle Motors SJ-DJ Series

- •Spindle motors that are smaller and lighter than the SJ-D Series with the same output. This helps to further downsize machines.
- •Range: 5.5 to 15 [kW]
- •Maximum speed: 8,000 to 12,000 [r/min]

# High-output High-torque IPM Spindle Motors SJ-DM Series

- •The use of magnets allows for higher output and torque, leading to reduced cycle time.
- •The SJ-DM Series can provide torque characteristics comparable to the former SJ-D Series of the next frame number.
- •Maximum rotation speed: 12,000 [r/min]

#### Servo motors



#### Medium-inertia, High-accuracy, High-speed Motors HG Series

- Sensor resolution has been significantly improved.
   These servo motors, which boast smooth rotation and outstanding acceleration capabilities, are well-suited as feed axes of machine tools.
- •Range: 0.2 to 11 [kW]
- •Maximum rotation speed:
- Safety support sensors are included as standard specification. Sensor connectors are screw-locked and provide enhanced vibration resistance. Three sensor resolutions (i.e., 1, 4 or 67 million pulses/rev) are available.
- These motors can also be used as a tool spindle motor.
- •The small-sized connector allows horizontal cable connection to save space in machines. (Note 2)



#### Linear Servo Motors LM-F Series

- •These motors can be used in clean environments, since no ball screws are used, eliminating possible grease contamination.
- •Elimination of transmission mechanisms, including backlash, enables smooth, quiet operation even at high speeds.
- •Range:
- Maximum thrust: 900 to 18,000 [N·m]



#### Direct-drive Servo Motors TM-RB Series

- High-torque, direct-drive motors combined with high-gain control provide quick acceleration and positioning, making rotation smoother.
- •Suitable for rotary axes that drive tables or spindle heads
- •Range:
- Maximum torque: 36 to 1,280 [N⋅m]



#### Built-in Spindle Motors SJ-BG Series

- •The electrical design has been optimized to increase the continuous rated torque per unit volume, contributing to downsizing spindle units.
- •Options for mold and cooling jacket specifications are available.



### **Tool Spindle Motors HG-JR Series**

- Compact tool spindle motors are designed to have the small, high-output characteristics of servo motors yet offer high-speed rotation (8,000r/min).
   These motors contribute to downsizing spindle size, like rotary tool spindles.
- •Range: 0.75 to 1.5 [kW] •Maximum rotation speed: 8,000 [r/min]
- •Small-sized connector allows horizontal cable connection to save space in machines. (Note 2)

(Note 1) For servo motors only (Note 2) Options supported (Flange size 90SQ only) \* Use Mitsubishi Electric CNC's dedicated drive unit and motor.

# **LIST OF COMPONENTS**

### **CNC-CPU** unit

Product	Model	Remarks
CNC control module	R16NCCPU-S1	

### GOT2000 related unit SD card

Product	Model	Model code	Remarks
SD card	NZ1MEM-2GBSD	1WC535	2GB SD memory card for GOT

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Pro	oduct	Model	Model code	Remarks
	GT2715	GT2715-XTBA	1EA790	15" XGA[1024×768 dots]TFT color LCD 65536 colors (Multimedia & Video/RGB compliant Multi-touch compliant) 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version (GOT2000) 1.117X or later is required.
	GT2712	GT2712-STBA	1EA780	12.1** SVGA [800×600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
	G12/12	GT2712-STBD	1EA781	12.1** SVGA [800×600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 24VDC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
	GT2710	GT2710-STBA	1EA770	10.4** SVGA [800×600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant) 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
	G12710	GT2710-STBD	1EA771	10.4** SVGA [800×600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 24VDC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
GT27	GT2708	GT2708-STBA	1EA740	8.4** SVGA [800x600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128ME GT Designer3 Version1 (GOT2000) 1.155M or later is required.
Model		GT2708-STBD	1EA741	8.4** SVGA [800×600 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 24VDC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
	GT2710	GT2710-VTBA	1EA760	10.4** VGA [640×480 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128ME GT Designer3 Version1 (GOT2000) 1.165X or later is required.
		GT2710-VTBD	1EA761	10.4** VGA [640×480 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 24VDC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
		GT2708-VTBA	1EA730	8.4" VGA [640×480 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 100 to 240VAC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128ME GT Designer3 Version1 (GOT2000) 1.165X or later is required.
		GT2708-VTBD	1EA731	8.4** VGA [640×480 dots] TFT color LCD 65536 colors (Multimedia & Video / RGB compliant Multi-touch compliant 24VDC, User memory Memory for storage (ROM): 57MB, Memory for operation (RAM): 128MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
	GT2705	GT2705-VTBD	1EA721	5.7"" VGA [640×480 dots] TFT color LCD 65536 colors (Multi-touch compliant) 24VDC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
'		GT27-15PSCC	1EK313	Surface treatment: anti-glare, Sheet color: transparent, USB environmental protection cover area: open, Number of sheets included in a set: 5
		GT25-12PSCC	1EK307	For 12.1" Clear type, Transparent, With a hole for the USB environmental protection cover, A set of 5 sheets
Protective	sheet	GT25-10PSCC	1EK304	For 10.4"" Clear type, Transparent, With a hole for the USB environmental protection cover, A set of 5 sheets
		GT25-08PSCC	1EK301	For 8.4** Clear type, Transparent, With a hole for the USB environmental protection cover, A set of 5 sheets
		GT25-05PSCC	1EK316	For 5.7"" Clear type, Transparent, With a hole for the USB environmental protection cover, A set of 5 sheets

### GT25 Model

	Pro	duct	Model	Model code	Hemarks
		GT2512	GT2512-STBA	1EA580	12.1" SVGA [800×600 dots] TFT color LCD 65536 colors 100 to 240VAC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
			GT2512-STBD	1EA581	12.1" SVGA [800×600 dots] TFT color LCD 65536 colors 24VDC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.155M or later is required.
		0.70510	GT2510-VTBA	1EA560	10.4" VGA [640×480 dots] TFT color LCD 65536 colors 100 to 240VAC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
		GT2510	GT2510-VTBD	1EA561	10.4*" VGA [640×480 dots] TFT color LCD 65536 colors 24VDC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
	GT25 Model	GT2508	GT2508-VTBA	1EA530	8.4"" VGA [640×480 dots] TFT color LCD 65536 colors 100 to 240VAC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
			GT2508-VTBD	1EA531	8.4"" VGA [640×480 dots] TFT color LCD 65536 colors 24VDC, User memory Memory for storage (ROM): 32MB, Memory for operation (RAM): 80MB GT Designer3 Version1 (GOT2000) 1.165X or later is required.
		GT25 Handy GOT	GT2506HS-VTBD	09J922	Display section: 6.5" VGA, TFT color LCD, 65536 colors, panel color: black, power supply: 24VDC GT Works3 Version1.195D or later.
		GT25 Handy Connector conversion box	GT16H-CNB-42S	09V701	For converting the Handy GOT signals into individual signals for the terminal block, D-sub connector, and Ethernet RJ-45.
		GT25 Handy	GT16H-C30-42P	09V702	For connection between the Handy GOT and the connector conversion box (GT16H-CNB-42S) 3m
		External connection cable to connect the connector	GT16H-C60-42P	09V703	For connection between the Handy GOT and the connector conversion box (GT16H-CNB-42S) 6m
		conversion box	GT16H-C100-42P	09V704	For connection between the Handy GOT and the connector conversion box (GT16H-CNB-42S) 10m

#### MELSEC iQ-R Series modules

	duct	Model R04CPU	Model code	Remarks Program capacity, 40K steps; basic operation processing speed (LD instruction), 0.98ns
			1FMA00	
DI 0 05::		R08CPU	1FMA01	Program capacity, 80K steps; basic operation processing speed (LD instruction), 0.98ns
PLC CPU		R16CPU	1FMA02	Program capacity, 160K steps; basic operation processing speed (LD instruction), 0.98ns
		R32CPU	1FMA03	Program capacity, 320K steps; basic operation processing speed (LD instruction), 0.98ns
		R120CPU	1FMA04	Program capacity, 1200K steps; basic operation processing speed (LD instruction), 0.98ns
SD memory ca	ard	NZ1MEM-2GBSD	1WC535	SD memory card, 2Gbytes
Extended SRA		NZ2MC-1MBS	1FMB00	1Mbytes
EXICITACA OF F	IIVI GAGGGETE	R35B	1FME00	5 slots, for MELSEC iQ-R Series modules
Main base	-	R38B		8 slots, for MELSEC iQ-R Series modules
IVIAIIT Dase	-		1FME01	· ·
		R312B	1FME02	12 slots, for MELSEC iQ-R Series modules
		R65B	1FME07	5 slots, for MELSEC iQ-R Series modules
Extension bas	e	R68B	1FME06	8 slots, for MELSEC iQ-R Series modules
		R612B	1FME05	12 slots, for MELSEC iQ-R Series modules
		RQ65B	1FME08	5 slots, for MELSEC-Q Series modules
RQ extension	base	RQ68B	1FME03	8 slots, for MELSEC-Q Series modules
	1	RQ612B	1FME04	12 slots, for MELSEC-Q Series modules
		RC06B	1FM001	0.6m cable for extension and RQ extension base units
Extension cab	le -	RC12B	1FM002	1.2m cable for extension and RQ extension base units
	-	RC30B	1FM003	3m cable for extension and RQ extension base units
		RC50B	1FM004	5m cable for extension and RQ extension base units
		R61P	1FMC00	AC power supply; input, 100 to 240VAC; output, 5VDC/6.5A
Davis !		R62P	1FMC02	AC power supply; input, 100 to 240VAC; output, 5VDC/3.5A, 24VDC/0.6A
Power supply		R63P	1FMC01	DC power supply; input, 24VDC; output, 5VDC/6.5A
		R64P	1FMC03	AC power supply; input, 100 to 240VAC; output, 5VDC/9A
	AC	RX10		AC input, 16 points; 100 to 240VAC, output, 3VDC/9A
			1FM103	
lanut	DC	RX40C7	1FM100	DC input, 16 points; 24VDC, 7.0mA
Input	(PositiveCommon/	RX41C4	1FM101	DC input, 32 points; 24VDC, 4.0mA
	Negative Common	RX42C4	1FM102	DC input, 64 points; 24VDC, 4.0mA
	Shared Type)	RX41C4-TS	1FM113	DC input, 32 points; 24VDC, 4.0mA, Spring clamp terminal block
	Relay	RY10R2	1FM153	Relay output, 16 points; 24VDC/2A, 240VAC/2A
		RY18R2A	1FM15A	Relay output, 8 points; 24VDC/2A, 240VAC/2A
	Triac	RY20S6	1FM157	Triac output, 16 points; 100 to 240VAC/0.6A
	.1100		1FM150	Transistor (sink) output, 16 points; 12 to 24VDC, 0.5A
	Transistor (Sink)	RY40NT5P		
Output		RY41NT2P	1FM151	Transistor (sink) output, 32 points; 12 to 24VDC, 0.2A
	· '	RY42NT2P	1FM152	Transistor (sink) output, 64 points; 12 to 24VDC, 0.2A
	Transistor (Source)	RY40PT5P	1FM154	Transistor (source) output, 16 points; 12 to 24VDC, 0.5A
		RY41PT1P	1FM155	Transistor (source) output, 32 points; 12 to 24VDC, 0.1A
		RY42PT1P	1FM156	Transistor (source) output, 64 points; 12 to 24VDC, 0.1A
		RY41PT1P-TS	1FM15E	Transistor (source) output, 32 points; 12 to 24VDC, 0.1A, Spring clamp terminal block
I/O	DC input/			DC input, 32 points; 24VDC, 4.0mA
combined	transistor output	RH42C4NT2P	1FM200	Transistor (sink) output, 32 points; 12 to 24VDC, 0.2A
SST INTIOU	a ar ioioitor outipul	A6CON1	13L101	Soldering 32 point-connector (40-pin connector)
		A6CON2	13L101	Solderling 32 point-connection (40-pin connector)  Solderless terminal connection 32 point-connector (40-pin connector)
Connector	-			
		A6CON3	13L103	Flat-cable pressure displacement 32 point-connector (40-pin connector)
		A6CON4	13L124	Soldering 32 point-connector (40-pin connector, bidirectional cable mountable)
Spring clamp	terminal block	Q6TE-18SN	1W4299	For 16-point I/O modules, 0.3 to 1.5mm² (2216AWG)
Connector/ten	minal block	A6TBX70	13L112	For positive common input modules (3-wire type)
		A6TBXY36	13L106	For positive common input modules and sink output modules (standard type)
conversion mo	odule	A6TBXY54	13L109	For positive common input modules and sink output modules (2-wire type)
		AC05TB	13L006	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 0.5m
Connector/		AC10TB	13L007	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 1m
				For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 1111
terminal		AC20TB	13L008	
block .	cable	AC30TB	13L009	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 3m
conversion		AC50TB	13L010	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 5m
module		AC80TB	13L026	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 8m* *Common current 0.5A or lo
		AC100TB	13L027	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 10m* *Common current 0.5A or lo
Relay terminal	module	A6TE2-16SRN	13L131	For 40-pin connector 24VDC transistor output modules (sink type)
. ,		AC06TE	13L021	For A6TE2-16SRN, 0.6m
Rolay			13L022	For A6TE2-16SRN, 1m
Relay	aabla	AC10TE		
terminal	cable	AC30TE	13L023	For AGTE2-16SRN, 3m
module		AC50TE	13L024	For A6TE2-16SRN, 5m
		AC100TE	13L025	For A6TE2-16SRN, 10m
	Voltage input	R60ADV8	1FM503	8 channels for voltage inputs -10 to 10VDC, -32000 to 32000; 80µs/CH
Analog input	Current input	R60ADI8	1FM504	8 channels for current inputs 0 to 20mADC/0 to 32000; 80us/CH
- Indiag in pac	Voltage/			
	Voltage/	R60AD4	1FM501	4 channels for voltage/current inputs
	current input			-10 to 10VDC, -32000 to 32000; 0 to 20mADC, 0 to 32000; 80µs/CH
Analog output	Voltage output	R60DAV8	1FM505	8 channels for voltage outputs
	Current output	R60DAI8	1FM506	-32000 to 32000, -10 to 10VDC; 80μs/CH 8 channels for current outputs
	Voltage/			0 to 32000, 0 to 20mADC; 80µs/CH 4 channels for voltage/current outputs
	current output	R60DA4	1FM502	-32000 to 32000, -10 to 10VDC; 0 to 32000, 0 to 20mADC; 80µs/CH
		D60TCDT4	1FY40E	RTD (Pt100, JPt100), 4 channels for input
	Platinum temperature-	R60TCRT4		
	measuring resistor	R60TCRT4BW	1FY40F	RTD (Pt100, JPt100), 4 channels for input, heater disconnection detection
_				Thermocouple (B, R, S, K, E, J, T, N, U, L, PL@, W5Re/W26Re), 4 channels for input
		B60TCTBT2TT2	1EV400	
	Thermocouple	R60TCTRT2TT2	1FY40C	(2 channels can also be used for RTD input)
Temperature control	Thermocouple -	R60TCTRT2TT2 R60TCTRT2TT2BW	1FY40C 1FY40D	

Pro	duct	Model	Model code	Remarks
		RD62P2	1FM50B	5/12/24VDC input, 2 channels; counting speed, max. 200k pulse/s; external output, transistor (sink type)
High-speed o	ounter	RD62D2	1FM50C	Differential input, 2 channels; max. counting speed, 8M pulse/s; external output, transistor (sink type)
		RD62P2E	1FM50D	5/12/24VDC input, 2 channels; counting speed, max. 200k pulse/s; external output, transistor (source type)
Ethernet		BJ71FN71	1FM601	1 Gbps/100Mbps/10Mbps,
Ethernet		DJ/ IEIV/ I	I FIVIOU I	2 ports Multi-network connectivity (Ethernet/CC-Link IE)
		RJ71C24	1FM604	Max. 230.4kbps; RS-232, 1 channel; RS-422/485, 1 channel
Serial commu	nication	RJ71C24-R2	1FM605	Max. 230.4kbps; RS-232, 2 channels
		RJ71C24-R4	1FM606	Max. 230.4kbps; RS-422/485, 2 channels
MFS Interface		RD81MES96N 1FTD00	4ETD00	1000BASE-T/100BASE-TX/10BASE-T Database connection
IVIES ITTETIACE	,		(MX MESInterface-R is required)	
CC-Link IE Co	ontrol	RJ71GP21-SX	1FM602	1 Gbps, fiber-optic cable, control/normal station
CC-Link IE Fie	eld	RJ71GF11-T2	1FM600	1 Gbps, master/local station
CC-Link		RJ61BT11	1FM603	Max. 10Mbps, master/local station, CC-Link Ver.2 supported
	Screw	AJ65SBTB1-16D	1W5131	Input 16 points: 24VDC (positive/negative common shared) 1-wire type Terminal block type Response time 1.5ms
CC-Link	terminal block	AJ65SBTB1-32D	1W5141	Input 32 points: 24VDC (positive/negative common shared) 1-wire type Terminal block type Response time 1.5ms
Remote I/O	type	AJ65SBTB1-16TE	1W5128	Output 16 points: 12/24VDC (0.1A) Transistor output (source type) 1-wire type Terminal block type
module	typo	AJ65SBTB1-32TE1	1W5452	Output 32 points: 12/24VDC (0.5A) Transistor output (source type) 1-wire type Terminal block type
module	Waterproof	AJ65FBTA4-16DE	1W5108	Input 24VDC (negative common) 4-wire type Thin, waterproof type Response time 1.5ms
	connector type	AJ65FBTA2-16TE	1W5103	Output 16 points: 12/24VDC (1.0A) Transistor output (source type) 2-wire type Thin, waterproof type
DeviceNet		RJ71DN91	1FM613	Max. 500kbaud, master/local station
PROFIBUS-D	IP	RJ71PB91V	1FM615	Max. 12Mbps, master/local station
EtherNetI/P		RJ71EIP91	1FM616	EtherNet/IP™ Scanner Module

(Note) For other related units, please contact us.

#### MELSEC Q Series modules

Proc	luct	Model	Model code	Remarks
		Q63B	1W4E07	3 slots, 1 power supply module required, for Q Series modules
		Q65B	1W4E03	5 slots, 1 power supply module required, for Q Series modules
Extension base		Q68B	1W4E04	8 slots, 1 power supply module required, for Q Series modules
Extension base		Q612B	1W4E05	12 slots, 1 power supply module required, for Q Series modules
		Q52B	1W4E14	2 slots, power supply module not required, for Q Series modules
		Q55B	1W4E15	5 slots, power supply module not required, for Q Series modules
		QC05B	1W4006	0.45m cable for connecting extension base unit
		QC06B	1W4000	0.6m cable for connecting extension base unit
Extension cable		QC12B	1W4001	1.2m cable for connecting extension base unit
LATERISION CADIC	7	QC30B	1W4002	3m cable for connecting extension base unit
		QC50B	1W4003	5m cable for connecting extension base unit
		QC100B	1W4004	10m cable for connecting extension base unit
		Q61P	1W4C11	Input voltage: 100 to 240VAC, output voltage: 5VDC, output current: 6A
Power supply		Q63P	1W4C02	Input voltage: 24VDC, output voltage: 5VDC, output current: 6A
		Q64PN	1W4C12	Input voltage: 100 to 240VAC, output voltage: 5VDC, output current: 8.5A
Output	Transistor (Independent)	QY68A	1W4310	8 points, 5 to 24VDC, 2A/point, 8A/module, response time: 10ms, sink/source type, 18-point terminal block, with surge suppression, all points independent
Analog output	Voltage/ current output	Q62DA-FG	1W4571	2 channels, input (resolution): 0 to 12000, -12000 to 12000, -16000 to 16000, output: -12 to 12VDC, 0 to 22mADC, conversion speed: 10ms/2 channels, 18-point terminal block, channel isolated
MELSECNET/	Optical loop (SI)	QJ71LP21-25	1W4516	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote mater station)
Н	Coaxial bus	QJ71BR11	1W4511	3C-2V/5C-2V coaxial cable, single bus, control network (control/normal station) or remote I/O network (remote master station)
FL-net(OPCN-2)	Ver.2.00	QJ71FL71-T-F01	1W4593	10BASE-T, 100BASE-TX
AS-I		QJ71AS92	1W4524	Master station, AS-Interface Specification Version 2.11 compatible
DeviceNet		QJ71DN91	1W4518	Master station/local station combined use, for QCPU, DeviceNet(Release2.0) compatible.

#### Peripheral unit

Product		Model	Remarks			
	Dual-signal modules	R173SXY	IO redundant monitoring module (Up to three modules)			
Division al	Terminal block	FA-TBS40P	Terminal block conversion (separately prepared: Mitsubishi Electric Engineering) UL supported			
Dual signal	Terminal block	FA-LTB40P	Terminal block conversion (separately prepared: Mitsubishi Electric Engineering)			
module	Cable	FA-CBL□□FMV-M	Terminal block conversion connection cable (length □□= 05: 0.5m, 10: 1m, 20: 2m, 30: 3m, 50: 5m) (separately prepared: Mitsubishi Electric Engineering)			
Signal splitter FL-net (OPCN-2) Interface		FCU7-HN387	Option (Necessary when manual pulse generator is used for two or three axes)			
		ER-1FL2-T	10BASE-T, 100BASE-TX			

#### Parts

T dito						
Product	Model	Remarks				
Manual pulse generator	UFO-01-2Z9	5V specification				
Ivial luai puise generator	HD60C	12V specification, for the operation board signal splitter connection, 12V power supply separately necessary				
	OSE 1024-3-15-68	6000r/min, no straight type connector enclosed, new JIS key, 68 square flange				
Encoder	OSE 1024-3-15-68-8	8000r/min, no straight type connector enclosed, 68 square flange				
	OSE 1024-3-15-160	6000r/min, no straight type connector enclosed, new JIS key, 160 square flange				
Grounding plata	Grounding plate D	With cable clamp A(2)				
Grounding plate	Grounding plate F	With cable clamp B(1)				

### **INSTALLATION ENVIRONMENT CONDITIONS**

#### **CNC CPU module**

Item	Specification							
Ambient operating temperature	0 to 55°C							
Ambient storage temperature	−25 to 75°C							
Ambient operating humidity	5 to 95%RH, non-condensing							
Ambient storage humidity	5 to 95%RH, non-condensing							
		Frequency	Constant acceleration	Half amplitude	Sweep count			
	Under intermittent	5 to 8.4Hz	-	3.5mm	10 times each in X, Y			
Vibration resistance	vibration	8.4 to 150Hz	9.8m/s²	-	and Z directions (80 min.)			
	Under continuous	5 to 8.4Hz	-	1.75mm				
	vibration	8.4 to 150Hz	4.9m/s <sup>2</sup>	-	-			
Shock resistance	147m/s², 3 times in each of 3 directions X, Y and Z							
Operating ambience	No corrosive gases or inflammable gases							
Operating altitude	2000m (6561.68ft.) or lower (Note 3)							
Installation location	Inside control panel							
Overvoltage category (Note 1)	II or less							
Pollution level (Note 2)	2 or less							

C80, which is open equipment, must be installed within a sealed metal control panel (IP54 or higher). C80 must also be used and stored under the conditions listed in the specifications table above. The following environmental conditions are also required for the layout design.

• No large amount of accumulated dust, iron filings, oil mist, salt, or organic solvents • No direct sunlight • No strong electrical or magnetic fields • No direct vibrations or shocks

(Note 1) Assumes that module is connected between a public power distribution network and local machinery.

Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for the rated voltage of up to 300V is 2,500V. (Note 2) Indicates the degree to which material accumulates in terms of the environment where the equipment is used.

Pollution level 2 means that only non-conductive pollution can occur. However, temporary conductivity may be caused by accidental condensation.

(Note 3) Do not use or store C80 Series modules under pressure higher than the atmospheric pressure of altitude 0m. Doing so may cause operation failure.

### **LIST OF MANUALS**

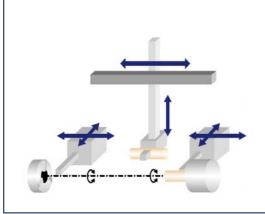
Manuals relating to the C80 are listed below. For the latest versions, please contact us.

Classification	Manual title	Manual No.	Intended purpose/contents
	M800/M80/E80/C80 Series Specifications Manual (Function)	IB-1501505	·Model selection ·Outline of various functions
C80	M800/M80/E80/C80 Series Specifications Manual (Hardware)	IB-1501506	·Model selection ·Specifications of hardware
	M800/M80/E80/C80 Series PLC Interface Manual	IB-1501272	·Electrical circuitry design ·Interface signals between NC and PLC
	M800/M80/E80/C80 Series Programming Manual (Lathe System) (1/2)	IB-1501275	·G code programming for lathe system ·Basic functions, etc.
	M800/M80/E80/C80 Series Programming Manual (Lathe System) (2/2)	IB-1501276	·G code programming for lathe system ·Functions for multi-part system, high-accuracy function, etc.
	M800/M80/E80/C80 Series Programming Manual (Machining Center System) (1/2)	IB-1501277	·G code programming for machining center system ·Basic functions, etc.
	M800/M80/E80/C80 Series Programming Manual (Machining Center System) (2/2)	IB-1501278	·G code programming for machining center system ·Functions for multi-part system, high-accuracy function, etc.
	C80 Series Connection and Setup Manual	IB-1501452	- Detailed specifications of hardware -Installation, connection, wiring, setup (startup/adjustment)
	C80 Series Instruction Manual	IB-1501453	·Operation guide for NC ·Explanation for screen operation, etc.
	C80 Series Maintenance Manual	IB-1501454	·Cleaning and replacement for each unit ·Other items related to maintenance
	C80 Series Alarm/Parameter Manual	IB-1501560	·Alarms ·Parameters
	MDS-E/EH Series Specifications Manual	IB-1501226	·Specifications of regenerative power modules
	MDS-E/EH Series Instruction Manual	IB-1501229	·Handling of regenerative power modules
Drive	MDS-EJ/EJH Series Specifications Manual	IB-1501232	·Specifications of resistor regeneration type units
system (servo/	MDS-EJ/EJH Series Instruction Manual	IB-1501235	·Handling of resistor regeneration type units
spindle)	MDS-EM/EMH Series Specifications Manual	IB-1501238	·Specifications of multi-axis integrated, regenerative power modules
-, -,	MDS-EM/EMH Series Instruction Manual	IB-1501241	·Handling of multi-axis integrated, regenerative power modules
	DATA BOOK	IB-1501252	·Specifications of servo drive unit, spindle drive unit, motor, etc.
	MELSEC iQ-R Module Configuration Manual	SH-081262	Outline of system configuration, specifications, installation, wiring, maintenance, etc.
	MELSEC iQ-R CPU Module User's Manual (Startup)	SH-081263	Outline of specifications, procedures before operation, troubleshooting, etc. for CPU modul
iQ-R	MELSEC iQ-R CPU Module User's Manual (Application)	SH-081264	Outline of memory, functions, devices, parameters, etc. for CPU module
IQ-11	QCPU User's Manual (Hardware Design, Maintenance and Inspection)	SH-080483	Outline of specifications, necessary knowledge to configure the system and maintenance-related descriptions for Q series CPU module, etc.
	GX Works3 Operating Manual	SH-081215	Outline of functions, programming, etc.
	GOT2000 Series User's Manual (Hardware)	SH-081194	Outline of hardware such as part names, external dimensions, installation, wiring, maintenance, etc. of GOTs
	GOT2000 Series User's Manual (Utility)	SH-081195	Outline of utilities such as screen display setting, operation method, etc. of GOTs
GOT	GOT2000 Series User's Manual (Monitor)	SH-081196	Outline of each monitor function of GOTs
	GOT2000 Series Connection Manual (Mitsubishi Electric Products)	SH-081197	Outline of connection types and connection method between GOT and Mitsubishi Electric connection devices
	GT Designer3 (GOT2000) Screen Design Manual	SH-081220	Outline of screen design method using screen creation software GT Designer3

### **CASE STUDY**

One CNC CPU controls up to seven part systems and 16 axes. Up to three CNC CPUs can be mounted on a single base. The C80 Series modules can control not only the machines in automobile parts production lines, but also various other machines.

#### Lathe system (two spindles and two turrets, equipped with workpiece loading robot)



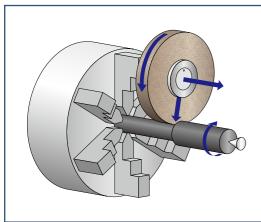
#### [Point to adopt C80 Series]

- Multi-part system control (up to 7 systems) enables independent control of lathe machining and work loading.
- iQ Platform-based robot control is supported.
- The system enables concurrent use of networks (field network, between controllers) are required in manufacturing lines.

#### [Main functions]

- Multi-part system control (start point designation timing synchronization, etc.)
- Machine group-based alarm stop
- Rapid traverse block overlap
- · Connection to various networks

#### Grinder



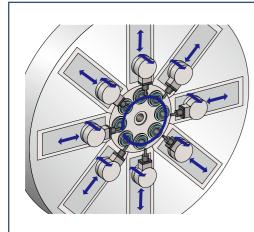
#### [Point to adopt C80 Series]

- GT Works3 helps design a variety of customized screens.
- Tool offset and tool life management functions support automation.
- $\bullet \mbox{Subprogram control allows modular part programming.} \\$

#### [Main functions]

- Tool offset and tool radius compensation
- Tool life management
- Subprogram control (up to eight nesting levels)

#### **Multi-station machine**



#### [Point to adopt C80 Series]

- $\bullet$  C80 modules support up to three CPUs mounted, which enables multi-axis multi-part system control (up to 21 part-systems and 48 axes).
- A great number of tools can be managed through tool offset and tool life management functions.

#### [Main functions]

- Timing synchronization between part systems(\*)
- Start point designation timing synchronization(\*)
- Multi-part system program management(1)
- Multi-part system simultaneous high-accuracy control<sup>(1)</sup>
- Number of tool offset sets [machining center system: up to 400 sets, lathe system: up to 256 sets]
- Number of tool life management sets [machining center system: up to 400 sets, lathe system: up to 256 sets]

### **FUNCTIONAL SPECIFICATIONS**

OStandard △Optional □Selection

		80	
class	Lathe system	Machining center system	General explanation
Control axes			
1 Control axes			
Number of basic control axes (NC axes)	02	03	The NC axis, spindle, and PLC axis are generically called the control axis.
2 Max. number of axes (NC axes + Spindles + PLC axes)	16	16	The NC axis can be manually or automatically operated using a machining program.
1 Max. number of NC axes (in total for all the part systems)	16	16	The PLC axis can be controlled using a sequence program.  The number of axes that is within the max. number of control axes, and that does not exceed the max.
2 Max. number of spindles	7	7	number given for the NC axis, spindle and PLC axis, can be used.
3 Max. number of PLC axes	8	8	
4 Max. number of PLC indexing axes	8	8	The number of PLC axes available to be used as indexing axis.
5 Number of simultaneous contouring control axes	4	4	Number of axes with which simultaneous interpolation control is possible.
6 Max. number of NC axes in a part system	8	8	Max. number of NC axes possible to control in the same part system.
7 Axis name extension	0	0	The axis name (command axis name) to issue the absolute/incremental command to NC control axis be expanded to two letters.
2 Control part system			De expanded to two letters.
Standard number of part systems	1	1	One part system is the standard.
Max. number of part systems (main + sub)	07	07	one part of our no trie durinduct.
1 Max. number of main part systems	07	07	Up to seven part systems.
2 Max. number of sub part systems	02	-	op to sever pair systems.
1 1 1	02		
3 Control axes and operation modes	+		
2 Memory mode	0	0	Machining programs stored in the memory of the CNC module are run.
3 MDI mode	0	0	MDI data stored in the memory of the CNC unit are executed.
4 High-speed program server mode			
3 FTP high-speed program server mode	Δ	Δ	This function allows high-speed transfer of machining programs from the FTP server to the large-cap buffer memory in CNC CPU via Ethernet to execute the program.
nput command			position manney in one or to the Embrior to oxocolte the program.
1 Data increment			
			The data increment handled in the controller includes the input setting increment and command incre
1 Least command increment			Each type is set with parameters.
Least command increment 1µm	0	0	Possible to command in increments of 0.001mm (linear axis) and 0.001° (rotary axis).
Least command increment 0.1µm	0	0	Possible to command in increments of 0.0001mm (linear axis) and 0.0001° (rotary axis).
2 Least control increment			The least control increment determines the CNC's internal operation accuracy.
Least control increment 0.01µm (10nm)	0	0	Possible to control in increments of 0.00001mm (linear axis) and 0.00001° (rotary axis).
Least control increment 0.001µm (1nm)	0	0	Possible to control in increments of 0.000001mm (linear axis) and 0.000001° (rotary axis).
3 Indexing increment	0	0	This function limits the command value for the rotary axis.
ositioning / Interpolation			
Positioning			
			This function cames out positioning at high speed using a rapid traverse rate with the travel comman
1 Positioning	0	0	given in the program.
2 Unidirectional positioning	_	Δ	The G code command always moves the tool to the final position in the direction determined by parar
2 Linear / Circular interpolation			
1 Linear interpolation	0	0	Linear interpolation is a function that moves a tool linearly by the travel command value supplied in th
- Elioa intorpolation	<del></del>		program at the cutting feedrate designated by the F code.
2 Circular interpolation (Center / Radius designation)	0	0	This function moves a tool along a circular arc on the plane selected by the travel command value su in the program.
3 Helical interpolation	0	0	With this function, any two of three axes intersecting orthogonally are made to perform circular interp while the third axis performs linear interpolation in synchronization with the arc rotation. This control c
	+		exercised to machine large-diameter screws or 3-dimensional cams.  This function interpolates arcs where the start point and end point are not on the circumference of the
4 Spiral / Conical interpolation	_	Δ	circle into spiral shapes.
			This function transfers the shape that is on the cylinder's side surface (shape yielded by the cylindrical
5 Cylindrical interpolation	Δ	Δ	coordinate system) onto a plane, and when the transferred shape is designated in the program in the of plane coordinates, the shape is converted into a movement along the linear and rotary axes of the cylinder coordinates, and the contours are controlled by means of the CNC unit during machining.
6 Polar coordinate interpolation	Δ	Δ	This function converts the commands programmed by the orthogonal coordinate axes into linear axis movements (tool movements) and rotary axis movements (workpiace rotation) to control the contour useful for cutting linear cutouts on the outside diameter of the workpiace, grinding cam shafts, etc.
7 Milling interpolation	Δ	_	When a latthe with linear axes (K, Z axes) and rotary axis (C axis) serving as the control axes is to perfimiling at a workpiece end face or in the longitudinal direction of the workpiece, this function uses the hypothetical axis Y, which is at right angles to both the X and Z axes, to enable the milling shape to b
C us a intermelation			programmed as the X, Y and Z orthogonal coordinate system commands.
3 Curve interpolation			This function automatically appropriate colling automatically
3 Spline interpolation (G05.1Q2 / G61.2)	_	Δ	This function automatically generates spline curves that smoothly pass through rows of dots designa a fine-segment machining program, and performs interpolation for the paths along the curves. This e
			high-speed and high-accuracy machining.
<del>ee</del> d			
5 Thread cutting			
1 Thread cutting (Lead / Thread number designation)	0	Δ	Thread cutting with a designated lead can be performed. Inch threads are cut by designating the nur threads per inch with the E address.
		+	Infreads per inch with the E address.  By commanding the lead increment/decrement amount per thread rotation, variable lead thread cutti
2 Variable lead thread cutting	0		be performed.
3 Synchronous tapping			* With digital I/F spindle
1 Synchronous tapping cycle	0	0	This function performs tapping through synchronized control of the spindle and servo axis. This eliminates and for the spindle and servo axis.
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1			the need for floating taps and enables tapping to be conducted at a highly accurate tapping depth.  The load applied to the tool can be reduced by designating the depth of cut per pass and cutting the
2 Pecking tapping cycle	Δ	Δ	Ine load applied to the tool can be reduced by designating the depth of cut per pass and cutting the workpiece to the hole bottom with a multiple number of passes.
3 Deep-hole tapping cycle	Δ	Δ	In the deep-hole tapping, the load applied to the tool can be reduced by designating the depth of cu
Deep Tole capping Cycle	<u> </u>	Δ	pass and cutting the workpiece to the hole bottom with a multiple number of passes.
4 Multiple spindle synchronous tapping	Δ	Δ	This function enables two or more spindles to perform synchronous tapping at a time, thereby impro the tapping efficiency.
	0		Chamfering can be enabled during the thread cutting cycle by using external signals.
14 I Chamtering		+ -	Circular thread in which the lead is in longitudinal direction can be cut.
4 Chamfering 6 Circular thread cutting	_		The servo axis directly detects and compensates the spindle's delay in tracking by using the commun
4 Chamtening 6 Circular thread cutting			
1 2 2 3	0	0	
6 Circular thread cutting	0	0	between drive units over the high-speed optical servo network. By minimizing the synchronization en accuracy of the synchronous tapping is increased.
6 Circular thread cutting	Ο Δ	0	between drive units over the high-speed optical servo network. By minimizing the synchronization err accuracy of the synchronous tapping is increased.  The thread outling feedrate can be changed by changing the spindle override depending on rough or
6 Circular thread cutting  8 High-speed synchronous tapping (OMR-DD)		0 -	between drive units over the high-speed optical servo network. By minimizing the synchronization em

OStandard △Optional □Selection

		C	:80	OStandard △Optional □Selection	
	class	Lathe system	Machining center system	General explanation	
_	gram memory / editing				
1 1/1	lemory capacity  Memory capacity (number of programs stored)				
	500kB [1280m] (1000 programs)	0	0	Machining programs are stored in the NC memory.	
	1000kB [2560m] (2000 programs)	Δ	Δ	(Note) For a multi-part system, the specifications shown here is the total for all part systems.	
	2000kB [5120m] (2000 programs)	Δ	Δ		
2 E	diting				
2	Program editing  Background editing	0	0	This function enables program editing such as correction, deletion and addition.  This function enables one machining program to be created or edited while another program is running.	
	Buffer correction	0	0	During automatic operation (memory) or MDI operation, this function initiates single block stop and enables the next command to be corrected or changed. When a program error has occurred, the function enables the block in which the error occurred to be corrected and operation to be resumed without having to perform NC resetting.	
5	Multi-part system simultaneous program editing	0	_	When an operation to open a machining program in the NC memory is performed on the edit screen, machining programs are opened in the right and left areas at the same time; the specified machining program of the displayed part system in the edit area being selected and the machining program of another part system with the same name in the unselected edit area.	
6	Special program editing display for synchronization between part systems	Δ	_	When the left and right edit areas are displaying the same named programs of different part systems stored on the NC memory, the display is switched to the synchronized display of the left- and right- side programs aligned using the timing synchronization symbols.	
	ration and display				
11	tructure of operation / display panel  GOT (GOT2000 Series GT27 / GT25 12.1 / 10.4 / 8.4 / 5.7)  peration methods and functions	0	0	Select a GOT in its lineup. For details, refer to catalogs: "GOT2000 series".	
1	Operation input	0	0	In addition to the method of directly inputting numeric data, a method to input the operation results using four basic arithmetic operators and function symbols can be used for specific data settings.	
2	Absolute value / Incremental value setting	0	0	When setting the data, the absolute/incremental setting can be selected from the menu.	
	Multiple display connection	O(GOT)	O(GOT)	Using an Ethernet hub, one CNC module can be connected to and switched between up to eight displays. (Note that the max, number of connectable displays is limited depending on the machine operation panel specifications.)	
4	Common display to multiple NCs	O(GOT)	O(GOT)	Using an Ethernet hub, one display can be connected to and switched between up to 64 CNC modules. (Note that the max. number of connectable displays is limited depending on the machine operation panel specifications.)	
5	Displayed part system switch	0	0	The part system displayed on the screen can be changed.	
6	Menu list	0	0	The menu list function displays the menu configuration of each screen as a list, making it possible to directly select the menu for other screens.	
7		0	0	The screen display changes when the screen mode selection switch is changed.	
8	8 External signal display switch	0	0	The screen display changes with the signal from PLC.	
9	Screen saver	O(GOT)	O(GOT)	The screen saver function protects the display unit by turning the backlight OFF after the length of time specified in a parameter.	
10	Parameter guidance	0	0	This function displays the details of the parameters or the operation methods according to the state of the screen currently displayed.	
11	1 Alarm guidance	0	0	Guidance is displayed for the alarm currently issued.	
14	4 Screenshot capture	O(GOT)	O(GOT)	This function allows to output a bitmap file of a screen displayed on the setting and display unit to USB memory or SD card.	
15	User selectable menu configuration	0	0	This function allows to change the display order of the main menu in the "Monitor", "Setup" and "Edit" screens, and to change display / non-display selection.  Menu items on the "Monitor", "Setup" and "Edit" screens (of MITSUBISHI standard format) can be moved	
19	9 MTB selectable menu configuration	0	0	within a screen or hidden as desired. The custom screen menu items added by machine tool builders, on the contrary, cannot be moved or hidden.	
8 Spin	dle, Tool and Miscellaneous functions			the defined by more or made in	
1 S	pindle functions (S)				
1	Spindle control functions			The spindle rotation speed is determined in consideration of the override and gear ratio for the S command given in automatic operation or with manual numerical commands, and the spindle is rotated.	
	6 Spindle-mode servo motor control	Δ	Δ	This function controls a spindle using the combination of servo motor and servo drive unit (MDS-E Series) which controls NC axis.	
15	5 Multiple spindle synchronization set control	0	0	What contains No. axis.  By setting the parameter, spindle synchronization I, tool spindle synchronization IA/IB (spindle-spindle, polygon), tool spindle synchronization II (hobbing) and spindle superimposition control can be executed simultaneously for multiple sets of spindles.	
	eration support functions				
	terrupt operation		T	Machining intermention in a function which problem into the section of the sectio	
	6 Machining interruption	Δ	Δ	Machining interruption is a function which enables interrupt operations while a program is normally executed.	
	gram support functions				
	lachining method support functions				
	1   Chopping				
	1 Chopping	Δ	Δ	This function continuously raises and lowers the chopping axis independently of program operation. During	
۵	Multi-part system control		<del>                                     </del>	the grinding operation, chopping can produce a better surface accuracy than using abrasive grain.	
HF	3 Mixed control				
	2 Arbitrary axis exchange control	Δ	Δ	An arbitrary axis can be exchanged freely across part systems in the multiple part systems. The machining can be freer by exchanging an axis which can be commanded for machining programs in each part system	
11	High-speed parts machining			Control by Social igning an axis which can be confindabled for machining programs in each part system.	
	Rapid traverse block overlap	Δ	Δ	This function enables the next block to start (overlap) without waiting for positioning (G00) or reference	
3 Hi	igh-speed and high-accuracy functions [kBPM: k Block per Minute]			position return (G28/G30). Consequently, cycle time of machining can be reduced.	
	3 SSS control	_	Δ	With SSS (Super Smooth Surface) control, the large area path information is used instead of just the angle between the blocks. Thus, optimum speed control that is not adversely affected by minute steps or waviness is possible. This enables machining with a fewer scratches and streaks on the cutting surface compared to the normal high-accuracy control function.  Multiple part systems simultaneous high-accuracy function is required to conduct the SSS control in the second or following part systems.	
	4 Tolerance control	_	Δ	This function enables the smooth operation within the tolerance error range. The desired machining result	
$\Box$	T IOIGIALIOS COLILIOI			can be obtained with simple parameter adjustment.	

class		C80		
		Lathe system	Machining center system	General explanation
Machi	ne accuracy compensation			
	tic accuracy compensation		1	
-	Backlash compensation	0	0	This function compensates the error (backlash) produced when the direction of the machine system is revers  Machine accuracy can be improved by compensating the errors in the screw pitch intervals among the
$\perp$	Memory-type pitch error compensation [sets]	010	010	mechanical errors (production errors, wear, etc.) of the feed screws.
3	Memory-type relative position error compensation	0	0	Machine accuracy can be improved by compensating the relative error between machine axes, such as a production error or a
4	External machine coordinate system compensation	Δ	Δ	The coordinate system can be shifted by inputting a compensation amount from the PLC. This compensation amount will not appear on the counters (all counters including machine position).
	Circular error radius compensation	Δ	Δ	With commands designated during arc cutting, this function compensates movement toward the inside of the arcs caused by a factor such as serve of
	Ball screw thermal expansion compensation	Δ	Δ	This compensates the axis feed error caused by a ball screw's thermal expansion, etc. using the values set by the F With this function, the gradually increasing-type lost motion which depends on the distance from the po
8	Position-dependent gradually increasing-type backlash compensation	Δ	Δ	which is function in a gradually floorbasing styge sost motion without respected on the disease is uniformly where the machine movement direction is reversed can be compensated by ordinoling the variation of backlash compensation amount according to the distance from the direction reversal point. Two-way pitch error compensation function is used to compensate the pitch error in each direction by
	Two-way pitch error compensation	Δ	Δ	setting the pitch error compensation amount when moving in the positive and negative direction.
TŤ	amic accuracy compensation		1	This is a high-response and stable position control method using the servo system. SHG control realizes
1	Smooth high-gain (SHG) control	0	0	approximately three-fold position loop gain compared to the conventional control method.
2	Dual feedback	0	0	Use position feedback with a motor-side encorder in ranges with high acceleration to enable stable cont in ranges with low acceleration, use position feedback with the machine-side encorder (scale). This will make it possible to increase the position loop gain. A machine-side encorder (scale) is separately require
3	Lost motion compensation	0	0	This function compensates the error in protrusion shapes caused by lost motion at the arc quadrant changeover section during circular cutting.
4	OMR II (Backlash with filter)	Δ	Δ	The OMR (Optimal Machine Response) control function estimates the machine or motor model (moment or inertia, clone friction, viscosity coefficient, etc.) that can cause a path error (deviation of the actual tool path from the programmed path). High-accuracy machining is achieved by carrying out feed forward control be on that model. This allows error cased by quadrant protrusions during circular interpolation or quadrants of the inner side of the path to be greatly reduced. OMR-II is a function that focuses on the quadrant protrusi and improves the path error with this. Quadrant path compensation is included in OMR-II.
6	OMR-FF	Δ	Δ	OMR-FF control enables fine control by generating feed forward inside the drive unit and can realize the strict feedback control to the program command than the conventional high-speed accuracy control.
Safety	and maintenance			, and the same and
4 Mair	ntenance and troubleshooting			
12	Backup / Restore	0	0	This function stores the setting information (sequence programs, parameters and the setting values, etc a connected device to the installed data storage in GOT, and restores those data to the device as needed.
5 Fun	ctional safety		<u> </u>	
2	Smart Safety observation			
	1 Safety-related I/O observation	Δ	Δ	Using the dual circuits for processing signals input/output to/from the machine (safety signal compare sequence) and dual execution of safety signal process logic made by users (safety PLC), if one circuit has broken down, the other circuit can detect errors, which improves the safety of signal process.
1	2 Emergency stop observation	Δ	Δ	Emergency stop signal is doubled and observed to see whether there is any error. When one emergency stop signal is in open state, the whole system can be set in emergency stop condition.
	3 Drive safety function			
	1 SLS (Safely-Limited Speed)	Δ	Δ	Axis speed (command speed, FB speed) is observed doubly to see whether the speed exceeds the safe spe
	2 SLP (Safely-Limited Position)	Δ	Δ	Axis absolute position (command position, FB position) is observed doubly to see whether the position exceeds the safe position range.
	3 SOS (Safe Operating Stop)	Δ	Δ	Axis stop speed (command speed, FB speed) is observed doubly whether the speed exceeds the safe stop sp Axis stop position (command position, FB position) is observed doubly whether the position exceeds the safe stop position or Observe axis stop position deviation (difference between command position and FB position) doubly to see which
	4 SSM (Safe Speed Monitor)	Δ	Δ	the deviation exceeds the safe stop position deviation.  This function uses the safety signals to inform that the axis speed (command speed, FB speed) is equal to or below the safe sy
	5 SBC / SBT (Safe Brake Control / Safe Brake Test)	Δ	Δ	The brakes connected to motors are activated by this function. Because there are two circuits for activating the bra one circuit can activate the brakes even when the other circuit is broken down. Furthermore, Safe Brake Test (SBT)
	6 SCA (Safe Cam)	Δ	Δ	diagnose the circuits for activating the breaks and the effectiveness of the brakes (deterioration due to abrasion, etc.  This function uses the safety signals to inform that the axis absolute position (command position, FB position) is within the range of safe position.
	7 SS1 / SS2 (Safe Stop)	Δ	Δ	Safe stop 1 (SS1)) STO function is activated after an axis is decelerated and the speed (command spee FB speed) becomes equal to or below the safe stop speed. Safe stop 2 (SS2) SOS function is activated after an axis is decelerated and the speed (command spee
				FB speed) becomes equal to or below the safe stop speed.
	8 STO (Safe Torque Off)	Δ	Δ	This function shuts OFF power supply to axes. Because there are two power shutoff circuits, one circuit shut OFF the power supply even when the other circuit is broken down.
Ш	9 SCN (Safety Communication Network)	Δ	Δ	This function performs safety communication between master station and local station using CC-Link IE field network
	ne support functions			
$\top$	ernal PLC link	Δ	Δ	Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for
1	CC-Link (Master / Local)	(MELSEC)	(MELSEC)	information on the function and the performance.
2	PROFIBUS-DP (Master)	(MELSEC)	(MELSEC)	Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for information on the function and the performance.
3	CC-Link IE Field network (Master / Local)	Δ	Δ	Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for
+		(MELSEC)	(MELSEC)	information on the function and the performance.  Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for
4	PROFINET	(MELSEC)	(MELSEC)	information on the function and the performance.
5	EtherNetI/P	(MELSEC)	(MELSEC)	Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for information on the function and the performance.
8	FL-net	Δ	Δ	Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for
+		(MELSEC)	(MELSEC)	information on the function and the performance.  Refer to manuals of each unit of MITSUBISHI Programmable Controller "MELSEC iQ-R series" for
	DeviceNet (Master)	(MELSEC)	(MELSEC)	information on the function and the performance.
$\overline{}$	alling S/W for machine tools			ADI C // Advanced Decorposed In Logic Controlled velocopy in a function that allows the controlled C
$\perp$	APLC release (Note 1)	Δ	Δ	APLC (Advanced Programmable Logic Controller) release is a function that allows the user-generated C language module trailed from the NC. Control operations that are difficult to express in a sequence program can be created with the C language.
	GOT2000 screen design tool GT Works3	0	0	This integrated software is used to create professional screen designs for GOTs.
3 Othe				
-	CNC remote operation tool	1		NC Monitor2 is a DC pathware tool that manitors information in the NOitt -dith ''
1 1	1 NC Monitor2 (Note 1)	0	0	NC Monitor2 is a PC software tool that monitors information in the NC unit connected with the Ethernet NC Explorer is a software tool to operate the machining data files of each NC unit connected with a hos
$\rightarrow$	2 NC Explorer (Note 3)	0	0	personal computer by Ethernet connection from the Explorer on the host personal computer.
3	Automatic operation lock	0	0	Automatic operation lock function prevents the falsification of APLC (C language module) by a third part
1 1	Power consumption computation	0	0	Present power consumption and accumulated power consumption can be acquired with this function." present power consumption notifies the instantaneous power consumption and the accumulated power consumption notifies the integrated value of the present power consumption.
4				This is the interface to display the variety of NC data on GOT connected to the CNC CPU.

(Note 1) Please contact us to purchase this tool.
(Note 3) This tool is free of charge. Please contact us. Refer to the specifications manuals for details.

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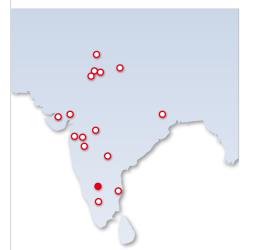
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### WARRANTY

Please confirm the following product warranty details before using MITSUBISHI ELECTRIC CNC.

#### 1. Warranty Period and Coverage

Should any fault or defect (hereafter called "failure") for which we are liable occur in this product during the warranty period, repair services shall be provided at no cost through the distributor from which the product was purchased or through a Mitsubishi Electric service provider. Note, however, that this does not apply if the customer was informed prior to purchasing the product that the product is not covered under warranty. Also note that

we are not responsible for any on-site readiustment and/or trial run that may be required after a defective unit is replaced.

#### [Warranty Term]

The term of warranty for this product shall be twenty-four (24) months from the date of delivery of the product to the end user, provided the product purchased from Mitsubishi Electric or a distributor in Japan is installed in Japan (but in no event longer than thirty (30) months, including distribution time after shipment from Mitsubishi Electric or a distributor).

Note that, in the case where the product purchased from Mitsubishi Electric or a distributor in or outside Japan is exported and installed in any country other than where it was purchased, please refer to "2. Service in Overseas Countries" below.

#### [Limitations]

- (1) The machine tool builder is requested to conduct an initial failure diagnosis, as a general rule. The diagnosis may also be carried out by Mitsubishi Electric or our service provider for a fee at the machine tool builder's request.
- (2)This warranty applies only when the conditions, method, environment, etc., of use are in compliance with the terms, conditions and instructions that are set forth in the instruction manual, user's manual, and the caution label affixed to the product.
- (3)Even during the term of warranty, repair costs will be charged to the customer in the following cases:
- (a) a failure caused by improper storage or handling, carelessness or negligence, etc., or a failure caused by a problem with the customer's hardware or software

- (b) a failure caused by any alteration, etc., to the product made by the customer without Mitsubishi Electric's approval
- (c) a failure which could have been avoided if the customer's equipment in which this product is incorporated had been equipped with a safety device required by applicable laws or has any function or structure considered indispensable in the light of industrial common sense
- (d) a failure which could have been avoided if consumable parts designated in the instruction manual, etc. had been duly maintained and replaced
- (e) any replacement of consumable parts (including the battery, relay and fuse)
- (f) a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquakes, lightning, and natural disasters
- (g) a failure which could not have been foreseen under technologies available at the time of shipment of this product from Mitsubishi Electric
- (h) any other failures which are not attributable to Mitsubishi Electric or which the customer acknowledges are not attributable to Mitsubishi Electric

#### 2. Service in Overseas Countries

If the customer installs a product purchased from Mitsubishi Electric in a machine or equipment and exports it to any country other than where it was purchased, the customer may sign a paid warranty contract with our local FA center

This applies in the case where the product purchased from us in or outside Japan is exported and installed in any country other than where it was purchased.

For details please contact the distributor from which the product was purchased.

#### 3. Exclusion of Responsibility for **Compensation against Loss of** Opportunity, Secondary Loss, etc.

Regardless of the gratis warranty term, Mitsubishi Electric shall not be liable for compensation for:

(1)Damage arising from any cause found not to

be the responsibility of Mitsubishi Electric.

- (2)Lost opportunity or lost profit incurred by the user due to a failure of a Mitsubishi Electric product.
- (3) Special damage or secondary damage, whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi Electric products.
- (4)Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

#### 4. Changes in Product Specifications

Specifications shown in our catalogs, manuals or technical documents are subject to change without notice.

#### **5.Product Application**

- (1) For use of this product, applications should be those that will not result in a serious damage even if a failure or malfunction occurs in the product, and a backup or failsafe function should operate on an external system when any failure or malfunction occurs to the product.
- (2)Mitsubishi Electric CNC is designed and manufactured solely for applications to machine tools for industrial purposes. Do not use this product in applications other than those specified above, especially those which have substantial influence on public interest or which are expected to have significant influence on human lives or properties.

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CNC and EDM machines.

Mitsubishi Electric offers a wide range of automation equipment from PLCs and HMIs to

#### A NAME TO TRUST

Since its beginnings in 1870, some 45 companies use the Mitsubishi name, covering a spectrum of finance, commerce and industry.

The Mitsubishi brand name is recognized around the world as a symbol of premium quality.

Mitsubishi Electric Corporation, established in 1921, is active in space development, transportation, semi-conductors, energy systems, communications and information processing, audio visual equipment and home electronics, building and energy management and automation systems, and has 183 factories, laboratories and offices worldwide in over 140 countries

This is why you can rely on Mitsubishi Electric automation solution - because we know first hand about the need for reliable, efficient, easy-to-use automation and control in our own factories.

As one of the world's leading companies with a global turnover of over 4 trillion Yen (over \$40 billion), employing over 146,000 people, Mitsubishi Electric has the resource and the commitment to deliver the ultimate in service and support as well as the best products.





Fransformers, Med-voltage Distribution Products



Power Monitoring and Energy Saving Products



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<sup>\*</sup> Not all products are available in all countries.

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Official Mitsubishi Electric Mechatronics YouTube account User support videos are available, including how to backup/restore data and replace batteries, and an

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### **A** Safety Warning

To ensure proper use of the products listed in this catalog, please be sure to read the instruction manual prior to use.

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